

Steve's Research

Stephen Freund Williams College

Announcements

- Lab today and tomorrow
- Project meetings Wed Fri
 - Sign up for slots **today** if you have not
 - Meet in library lab

*** STOP: 0x00000019 (0x0000000,0xC00E0FF0,0xFFFFEFD4,0xC0000000) BAD_POOL_HEADER

CPUID: Genuine Intel 5.2.c irgl:1f SYSVER 0xf0000565

| Dll Base | DateStmp - Name | Dll Base DateStmp - | Name |
|----------|----------------------------|---------------------|-----------------|
| 80100000 | 3202c07e – ntoskrnl.exe | 80010000 31ee6c52 - | hal.dll |
| 80001000 | 31ed06b4 - atapi.sys | 80006000 31ec6c74 - | SCS IPORT . SYS |
| 802c6000 | 31ed06bf - aic78xx.sys | 802cd000 31ed237c - | Disk.sys |
| 80241000 | 31ec6c7a - CLASS2.SYS | 8037c000 31eed0a7 - | Ntfs.sys |
| fc698000 | 31ec6c7d - Floppy.SYS | fc6a8000 31ec6ca1 - | Cdrom.SYS |
| fc90a000 | 31ec6df7 - Fs_Rec.SYS | fc9c9000 31ec6c99 - | Null.SYS |
| fc864000 | 31ed868b - KSecDD.SYS | fc9ca000 31ec6c78 - | Beep.SYS |
| fc6d8000 | 31ec6c90 - i8042prt.sys | fc86c000 31ec6c97 - | mouclass.sys |
| fc874000 | 31ec6c94 - kbdclass.sys | fc6f0000 31f50722 - | VIDEOPORT.SYS |
| feffa000 | 31ec6c62 - mga_mil.sys | fc890000 31ec6c6d - | vga.sys |
| fc708000 | 31ec6ccb - Msfs.SYS | fc4b0000 31ec6cc7 - | Npfs.SYS |
| fefbc000 | 31eed262 - NDIS.SYS | a0000000 31f954f7 - | win32k.sys |
| fefa4000 | 31f91a51 - mga.dll | fec31000 31eedd07 - | Fastfat.SYS |
| feb8c000 | 31ec6e6c - TDI.SYS | feaf0000 31ed0754 - | nbf.sys |
| feacf000 | 31f130a7 - tcpip.sys | feab3000 31f50a65 - | netbt.sys |
| fc550000 | 31601a30 - el59x.sys | fc560000 31f8f864 - | afd.sys |
| fc718000 | 31ec6e7a - netbios.sys | fc858000 31ec6c9b - | Parport.sys |
| fc870000 | 31ec6c9b - Parallel.SYS | fc954000 31ec6c9d - | ParVdm.SYS |
| fc5b0000 | 31ec6cb1 - Serial.SYS | fea4c000 31f5003b - | rdr.sys |
| fea3b000 | 31f7a1ba - mup.sys | fe9da000 32031abe - | srv.sys |
| | | | |
| Address | dword dump Build [1381] | | - Name |
| fec32d84 | 80143e00 80143e00 80144000 | ffdff000 00070b02 | – KSecDD.SYS |
| 801471c8 | 80144000 80144000 ffdff000 | C03000b0 00000001 | – ntoskrnl.exe |
| 801471dc | 80122000 f0003fe0 f030eee0 | e133c4b4 e133cd40 | – ntoskrnl.exe |
| 80147304 | 803023f0 0000023c 00000034 | 00000000 00000000 | — ntoskrnl.exe |

Restart and set the recovery options in the system control panel or the /CRASHDEBUG system start option.

The Blue Screen of Death





USS Yorktown

- Smart Ship
 - 27 PCs
 - Windows NT 4.0



[Wired 1997]

- September 21, 1997:
 - data entry error caused a "Divide-By-0" error
 - entire system failed
 - ship dead in the water for over 2 hours

Ariane 5 Rocket June 4, 1996 \$800 million software failure

Mars Climate Orbiter

Purpose: Collect data. Relay signals from Mars Polar Lander (\$165M)

Failure: Smashed into Mars (1999)

Bug: Failed to convert English to metric units



Mars Polar Lander

Purpose: Lander to study the Mars climate (\$120M)

Failure: Smashed into Mars (2000)

Bug: Spurious signals from sensors caused premature engine shutoff



North East Power Failure

Failure: Power grid failed across much of the North East. \$6B losses (2001)

Bug: Timing bug in Ohio power plant



Online Trading Software

Purpose: automatic high-frequency trading

Failure: DOW drops 9.2%, equity markets collapse (2010)

Bug: Bad modeling, and no fail-stops to prevent flooding market with sell orders



Purpose: Computercontrolled radiation therapy machine

Failure: gave fatal radiation doses to 2 cancer patients (1986)

Bug: race condition (timing bug)



Patriot Missile

Purpose: Intercept incoming missiles



Failure: missed SCUD missile that killed 28 US soldiers (1991)

Bug: incorrect calculation of distance to target

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Tesla



Purpose: Self-Driving Cars

Failure: Fatal Crash (2016)

Bug: Failed to distinguish a white tractortrailer crossing the highway against a bright sky. (Other fatal accidents have followed...)

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Tesla



Purpose: Self-Driving Cars

Failure: Fatal Crash (2016)

Bug: Failed to distinguish a white tractortrailer crossing the highway against a bright sky. (Other fatal accidents have followed...) Feb 1, 2022: Tesla recalls 54,000 vehicles due to **software letting them roll through stop signs** without coming to a complete halt.

Feb 3, 2022: Tesla recalls 800,000 vehicles due software bug related to **seat belt reminders**.

April 29, 2022: Tesla recalls 63,000 cars due to a software bug making it **hard to tell how fast the car is going**.

May 11, 2022: Tesla recalls130,000 cars due to software bug leading to **overheating in display system.**

Nov 3, 2022: Tesla recalls 11,000 cars due to bug causing vehicles to **activate forward-collision warnings and activate the emergency brakes for no reason.**

Nov 8, 2022: Tesla recalls 40,000 cars due to software update leading to **power steering failure**.

Purpose: Computercontrolled radiation therapy machine

Failure: gave fatal radiation doses to 2 cancer patients (1986)

Bug: race condition (timing bug)



Patriot Missile

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Heartbleed SSL Attack

Purpose: OpenSSL is widely-used cryptographic library.

Failure: Library could leak secret information, including keys. (2014)

Bug: Buffer overrun



Buffer Overruns [2]: def f(array, index): array[index] = 42[3]: elems = make_array(1,2,3,4,5,6,7,8,9,10) x = 100print(x) f(elems,6) print(x)100 100

Buffer Overruns

- [3]: elems = make_array(1,2,3,4,5,6,7,8,9,10)
 x = 100
- [4]: print(x)
 f(elems,11)
 print(x)

100

IndexError: index 11 is out of bounds for axi
s 0 with size 10

Buffer Overruns



```
void f(int array[], int index) {
  array[index] = 42;
}
int main() {
  int x = 100;
  int elems[10] = { 1,2,3,4,5,6,7,8,9,10 };
  printf("%d\n", x);
  f(elems, 6);
                                    $ gcc array.c
  printf("%d\n", x);
                                    $ ./a.out
  f(elems, 11);
  printf("%d\n", x);
                                    100
}
                                   100
                                    42
```

Buffer Overruns

```
void f(int array[], int index) {
  array[index] = 42;
}
int main() {
  int x = 100;
  int elems[10] = { 1,2,3,4,5,6,7,8,9,10 };
 printf("%d\n", x);
  f(elems, 6);
  printf("%d\n", x);
  f(elems, 11);
 printf("%d\n", x);
}
```



https://www.informationisbeautiful.net/visualizations/million-lines-of-code/

Managing Software Complexity



Research on Program Checkers

Identify Type of Bug

- Bad unit conversion
- Buffer overrun
- Data Race

Design Checking Tool

- static or dynamic?
- precision?
- scalability?
- performance?
- usability?

Validate Technique

- check real software
- find bugs...

Source Code (Static) Checkers



| Good Program | Has No Buffer Overruns |
|--------------|------------------------|
| Bad Program | Has Buffer Overrun |

- No algorithm can precisely compute if a program is "Good" or "Bad"
 - Undecidability of the Halting Problem [Turing 1936]

Source Code (Static) Checkers



| Good Program | Has No Buffer Overruns |
|--------------------|-------------------------------------|
| Bad Program | Has Buffer Overrun |
| Verifiable Program | Can Prove No Buffer Overruns |

- + Catch many errors prior to testing
- Must reject some good programs...

Dynamic Checkers



- + Can discern Good vs. Bad precisely, but...
- only during the tests performed
- Performance



Multithreading and Multicore CPUs



Concurrent Programming With Threads



Concurrent Programming With Threads

y hat = a * table.column('x') + b

Divide array into four pieces and do multiplications and additions for each piece on a different thread

Concurrent Programming With Threads







Thread Interference

Race Conditions

two concurrent unsynchronized accesses, at least one write



Thread Interference

Race Conditions

two concurrent unsynchronized accesses, at least one write



Controlling Thread Interference: Mutual Exclusion Locks

```
Thread A
acq(m);
t1 = bal;
bal = t1 + 10;
rel(m);
```

Thread B

```
acq(m);
t2 = bal;
bal = t2 - 10;
rel(m);
```



Controlling Thread Interference: Mutual Exclusion Locks

| | Thread A | Thread B |
|--------------------------------|---------------|---------------|
| Thread A | acq(m) | |
| acq(m); | t1 = bal | |
| ti = bal; bal = t1 + 10; | bal = t1 + 10 | |
| rel(m); | rel(m) | |
| Thread B | | acq(m) |
| acq(m); | | t2 = bal |
| $t_2 = bal;$ bal = t2 - 10; | | bal = t2 - 10 |
| rel(m); | | rel(m) |
| | \mathbf{X} | |

Controlling Thread Interference: Mutual Exclusion Locks





FastTrack '10, RedCard '13, SlimState '15, BigFoot '17











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Race Freedom is not Enough...



Controlling Thread Interference: Enforce Atomicity

Atomic method must behave as if it executed serially, without interleaved operations of other thread

```
atomic void copy() {
    x = 0;
    thread interference?
    while (x < len) {
        thread interference?
        tmp = a[x];
        thread interference?
        b[x] = tmp;
        thread interference?
        x++;
        thread interference?
    }
}</pre>
```

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}</pre>
```

Theory of Reduction [Lipton 76]



- **R** Right-mover
- L Left-mover
- **B** Both-mover
- N Non-mover

Acquire Release

- Race-Free Access
- **Racy Access**

Serializable blocks have the pattern: R* [N] L*

Examples



(R* [N] L*)



Atomizer '04





Atomizer '04







Traditional Software Process



Program Synthesis



Program Synthesis



- -How to generate candidate versions?
- -How to verify candidates are correct?
- -How to pick most performant?

Programming Languages And Analysis Tools

- language design
- theoretical foundations
- proving theorems
- systems development
- performance modeling
- experimental validation

