

Last Time: Intro to Logic Design and the Y86 Datapath

RISC vs. CISC

- Logic Design and Hardware Control Language
 Combinational circuits
 - Understanding HCL expressions

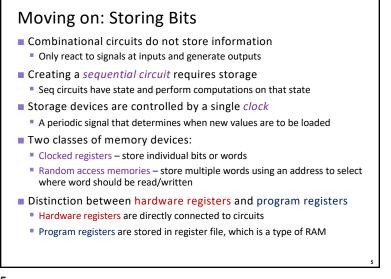
Administrative Details

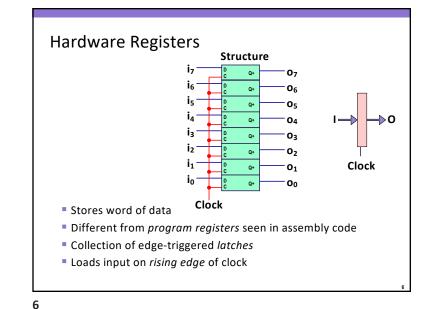
- Quiz due Friday at 2:30pm
- Lab #4 checkpoint due Tuesday at 11pm
- Read CSAPP Ch. 4.2-4.3
- Colloquium on Friday
 - Water robots!

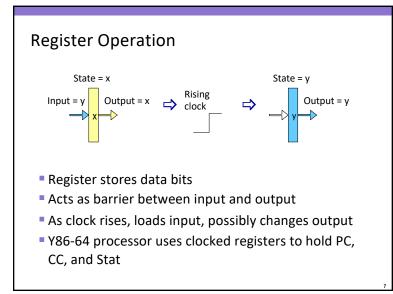
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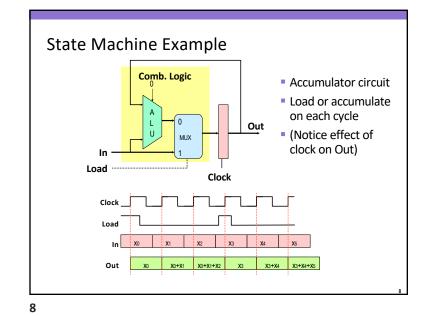
Today: The Y86 Datapath

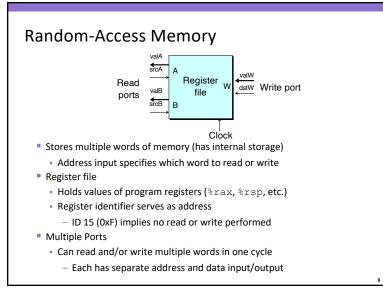
- Memory and clocking
 - How is information stored
- Construction a single-cycle datapath for Y86
- Pipelining Concepts



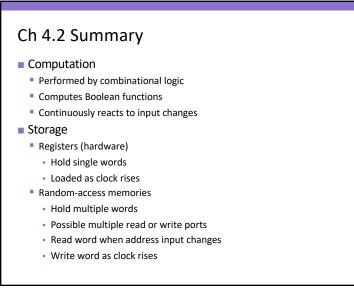


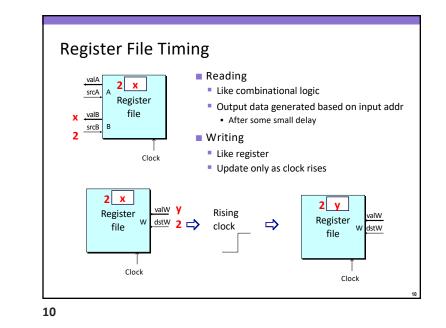












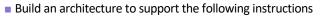
Today: The Y86 Datapath

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What Happens On Instruction Execution?

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Goal



- Arithmetic: addq, subq, andq, xorq
- Data movement: irmovq, rrmovq, cmov*
- Memory references: mrmovq, rmmovq, pushq, popq
- Control: call, ret, jmp, jle, jl,...

Steps For Executing An Instruction

Fetch

Read the next instruction from memory (address in IP/PC)

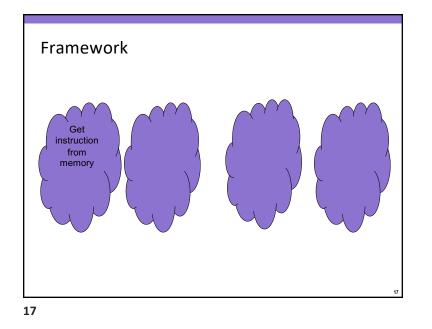
Decode

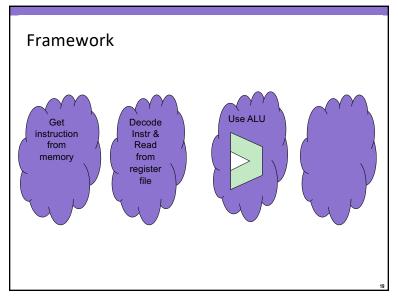
- Figure out which instruction
- Figure out and obtain operands
- Execute
 - Perform calculations
- Memory
 - Read or write data memory
- Write back
- Update registers
- Update program counter

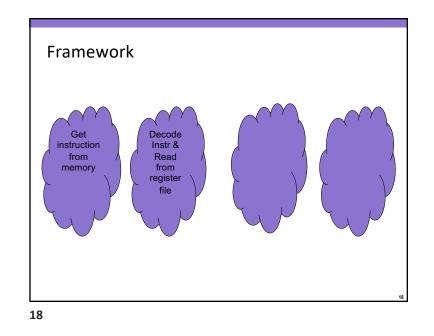
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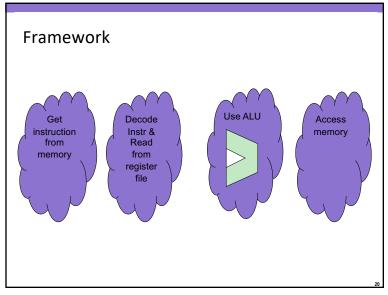
Process

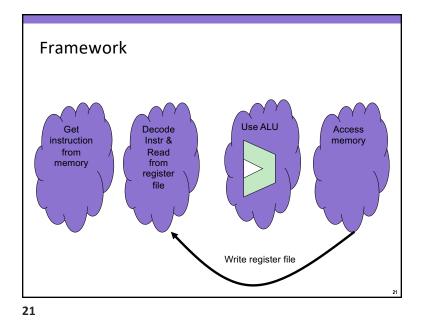
- 1) Design basic framework that is needed by all instructions
- 2) Build a computer for each operation individually
- 3) Add MUXs to choose between different operations
- 4) Add control signals to control the MUXs

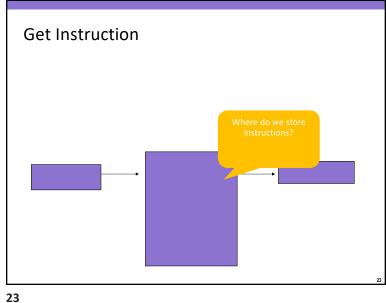


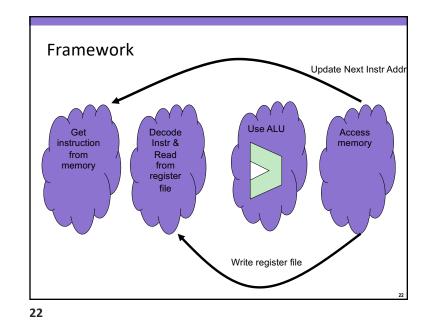


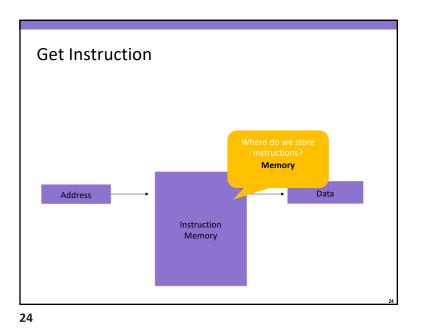


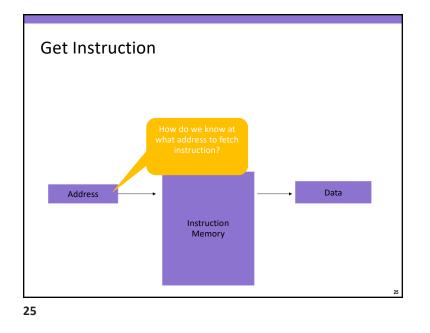


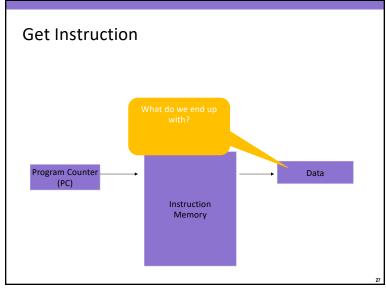


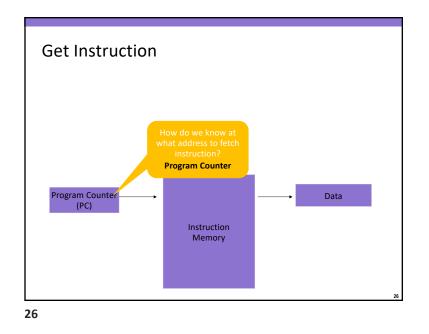


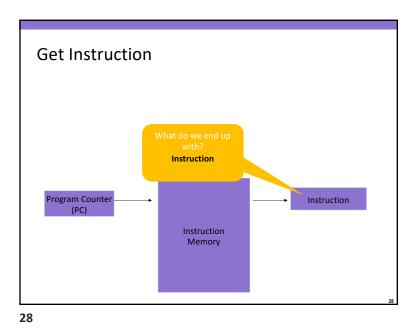


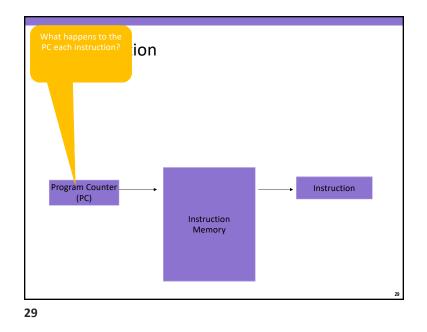


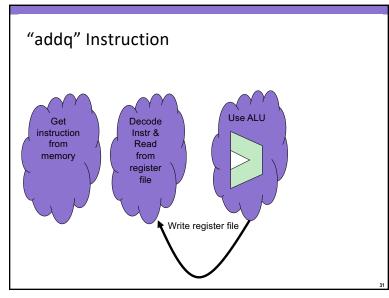


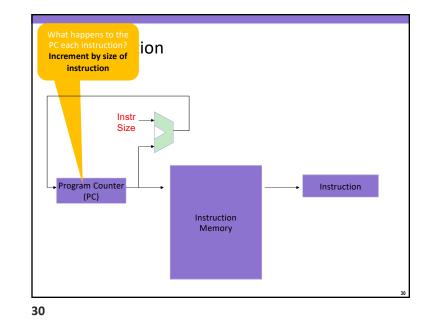


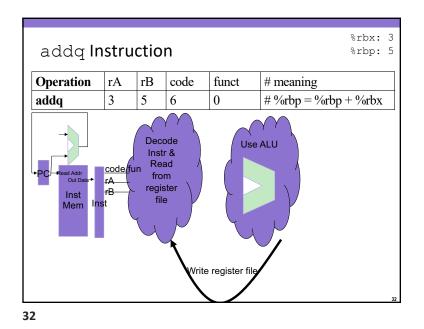


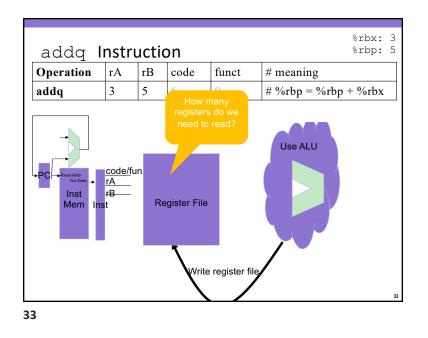


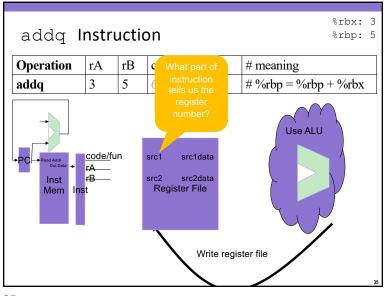


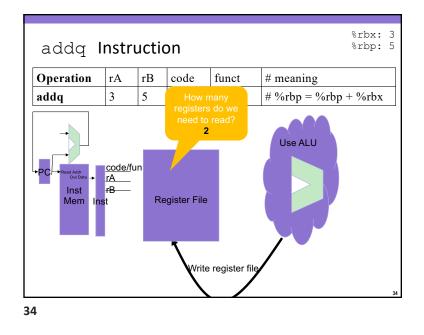


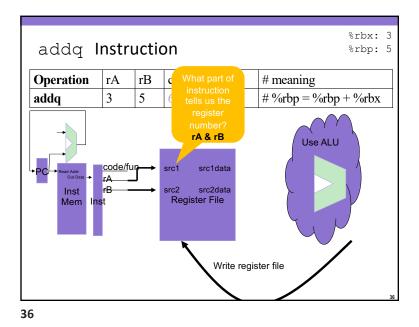


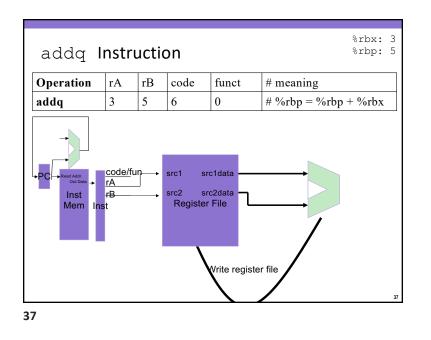


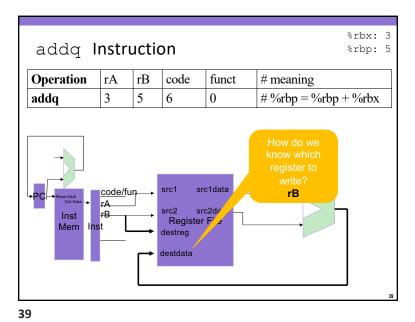


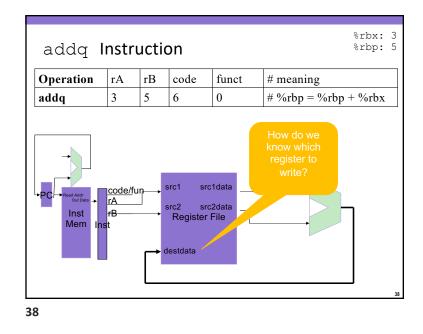


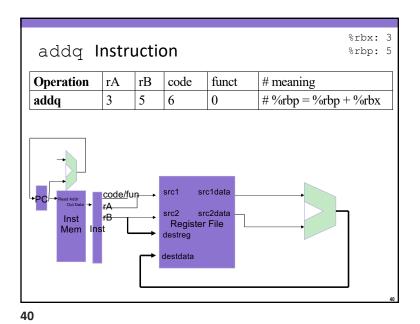


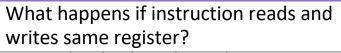












Operation	rA	rB	code	funct	# meaning
addq	3	5	6	0	# %rbp = %rbp + %rbx

