Computer Science 136

Data Structures Lecture #6 (September 22, 2021)

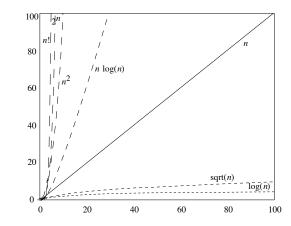
- 1. Vectors.
 - (a) Abstract concept: the extensible array.
 - i. Vectors start "empty," though some array has usually been allocated.
 - ii. Grows (and, possibly, shrinks) as needed.
 - iii. Efficient in time and space.
 - (b) Uses methods get/set/add/remove, not squarebracket indexing.
 - (c) Reshaping occurs through add(position,value) and remove(position).
 - (d) Utility methods: isEmpty and size.
 - (e) Implementing extensibility:
 - i. Keep track of two lengths: the array length and the vector length.
 - ii. Allow some guidance by user.
 - iii. Keys to efficiency:
 - A. double array length when necessary (why is this efficient?)
 - B. details encapsulated in protected ensureCapacity
 - C. shrinking is not automatic (use non-ideal trimToSize explicitly). But: it could be.
- 2. Complexity.
 - (a) Formal definition of what it means for f(x) to be O(g(x)). A definition worth remembering (see p. 98). Write it here:

- iv. Really, we're only concerned about the magnitude of f(x). In practice, $f(x) \ge 0$ since f is often a measure of time or space utilization.
- (b) E.g.: Vectors that extend to size n by 1 takes $O(n^2)$ time.

When you double the Vector's length, the time to expand increases by 4.

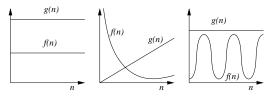
(c) E.g.: Vectors that extend to size n by doubling takes O(n) time.

When you double the Vector's length, the time to expand increases by 2.



- (d) A similar definition of what it means for f(x) to be $\Omega(g(x))$, a *lower bound*.
- (e) Any function that is both O(g(x)) and $\Omega(g(x))$ is $\Theta(g(x))$.
- (f) Little versions, o(x) and $\omega(x)$, are asymptotic bounds. They hold true for arbitrary positive constants, c.

i. f(x) is bounded above by some constant times g(x).



- ii. f(x) need not ever be equal to $c \cdot g(x)$. The bound need not be *tight*.
- iii. It only needs to be bounded above to the right of some x_0 .