#### Deduplication

CSCI 333 Spring 2019

# Logistics

- Lab 2a/b
- Final Project
- Final Exam
- Grades

## Last Class

- BetrFS [FAST '15]
  - Linux file system using B<sup>e</sup>-trees
    - Metadata B<sup>e</sup>-tree: path -> struct stat
    - Data in B<sup>e</sup>-tree: path | {block#} -> 4KiB block
  - Schema maps VFS operations to efficient B<sup>e</sup>-tree operations
    - Upserts, Range queries
  - Next iteration [FAST '16] : fixed slowest operations
    - Rangecast delete messages
    - "Zones"
    - Late-binding journal

# This Class

- Introduction to Deduplication
  - Big picture idea
  - Design choices and tradeoffs
  - Open questions
- Slides from Gala Yadgar & Geoff Kuenning, presented at Dagstuhl
- I've added new slides (slides without borders) for extra context

#### Deduplication



#### Geoff Kuenning







## Sources of Duplicates

- Different people store the same files
  - Shared documents, code development
  - Popular photos, videos, etc.



- May also share blocks
  - Attachments
  - Configuration files
  - Company logo and other headers

#### $\rightarrow$ Deduplication!

## Deduplication

- Dedup(e) is one form of compression
- High-level goal: identify duplicate objects and eliminate redundant copies
  - How should we define a duplicate object?
  - What makes a copy "redundant"?
- Answers are application-dependent and some of the more interesting research questions!

#### 857 Desktops at Microsoft



D. Meyer, W. Bolosky. A Study of Practical Deduplication. FAST 2011

#### "Naïve" Deduplication

#### For each new file

Compare each block to all existing blocks If new, write block and add pointer If duplicate, add pointer to existing copy



Are we done?

# Identifying Duplicates

- It's unreasonable to "Compare each block to all existing blocks"
- $\rightarrow$  Fingerprints



Cryptographic hash of block content

Low collision probability

# **Dedup Fingerprints**

- Goal: uniquely identify an object's contents
- How big should a fingerprint be?
  - Ideally, large enough that the probability of a collision is lower than the probability of a hardware error
    - MD5: 16-byte hash
    - SHA-1: 20-byte hash
- Technique: system stores a map (index) between each object's fingerprint and each object's location
  - Compare a new object's fingerprint against all existing fingerprints, looking for a match
  - Scales with *number* of unique objects, not *size* of objects

# Identifying Duplicates

- It's unreasonable to "Compare each block to all existing blocks"
- $\rightarrow$  Fingerprints



Cryptographic hash of block content

Low collision probability

It's also unreasonable to compare to all fingerprints...
 →Fingerprint cache



## Fingerprint Lookup

- How should we store the fingerprints?
- Every unique block is a miss  $\rightarrow$  miss rate  $\geq$  40%
- One solution: Bloom filter





• Challenge: 2% false positive rate  $\rightarrow$  1TB for 4PB of data

## How To Implement a Cache?

- (Bloom) Filters help us determine if a fingerprint exists
  - We still need to do an I/O to find the mapping
- Locality in fingerprints?
  - If we sort our index by fingerprint: cryptographic hash destroys all notions of locality
  - What if we grouped fingerprints by temporal locality of writes?

#### **Reading and Restoring**



- How long does it take to read File1?
- How long does it take to read File3?
- Challenge: when is it better to store the duplicates?





#### **Delete Path**



# Chunking

- Chunking: splitting files into blocks
- Fixed-size chunks: usually aligned to device blocks
- What is the best chunk size?





#### **Updates and Versions**

- Best case:
  aabbccdd
  →aAbbccdd
- Worst case:
  aabbccdd
  →aAabbccdd





### Variable-Size Chunks

- Basic idea: chunk boundary is triggered by a random string
- For example: 010

aa010bb010cc010dd  $\rightarrow$  aAa010bb010cc010dd

- Triggers should be:
  - Not too short/long
  - Not too popular (000000...)
  - Easy to identify

# Identifying Chunk Boundaries

- 48-byte triggers (empirically, this works)
- Define a set of possible triggers

 $\rightarrow$  K highest bits of the hash are == 0

 $\rightarrow$  Rabin fingerprints do this efficiently

 $\rightarrow$  "systems" solutions for corner cases



• Challenge: parallelize this process

# **Rabin Fingerprints**

- "The polynomial representation of the data modulo a predetermined irreducible polynomial" [LBFS sosp01]
- What/why Rabin fingerprints?
  - Calculates a rolling hash
  - "Slide the window" in a constant number of operations (intuition: we "add" a new byte and "subtract" an old byte to slide the window by one)
  - Define a "chunk" once our window's hash matches our target value (i.e., we hit a trigger)

## Defining chunk boundaries

- Tradeoff between small and large chunks?
   Finer granularity of sharing vs. metadata overhead
- With process just described, how might we:
  - Produce a very small chunk?
  - Produce a very large chunk?
- How might we modify our chunking algorithm to give us "reasonable" chunk sizes?
  - To avoid small chunks: don't consider boundaries until minimum size threshold
  - To avoid large chunks: as soon as we reach a maximum threshold, insert a chunk boundary

## **Distributed Storage**

Increase storage capacity and performance with multiple storage servers

- Each server is a separate machine (CPU,RAM,HDD/SSD)
- Data access is distributed between servers
- Scalability

Increase capacity with data growth

Load balancing

Independent of workload

Failure handling

Network, nodes and devices always fail





- Where/when should we look for duplicates?
- Where should we store each file?



### Next Class?

- Specific dedup system(s) (4)
- Mapreduce (+ write-optimized) (2)
- Google file system (1)
- RAID (3)

## **Final Project Discussion**

- Get with your group
- Find another group
- Pitch your project / show them your proposal
   React/revise