

[TAP:CWJXL] Balanced Trees

- Which of the following are not guaranteed to be “balanced”?
 - A. AVL Tree
 - B. Red-black Tree
 - C. Splay Tree
 - > D. They are all balanced
 - E. Whatever

Today's Outline

- • Graphs
 - Undirected Graph
 - Directed Graph
 - Implementation

Graphs Describe the World

- map of cities

cities , roads

cities , rivers

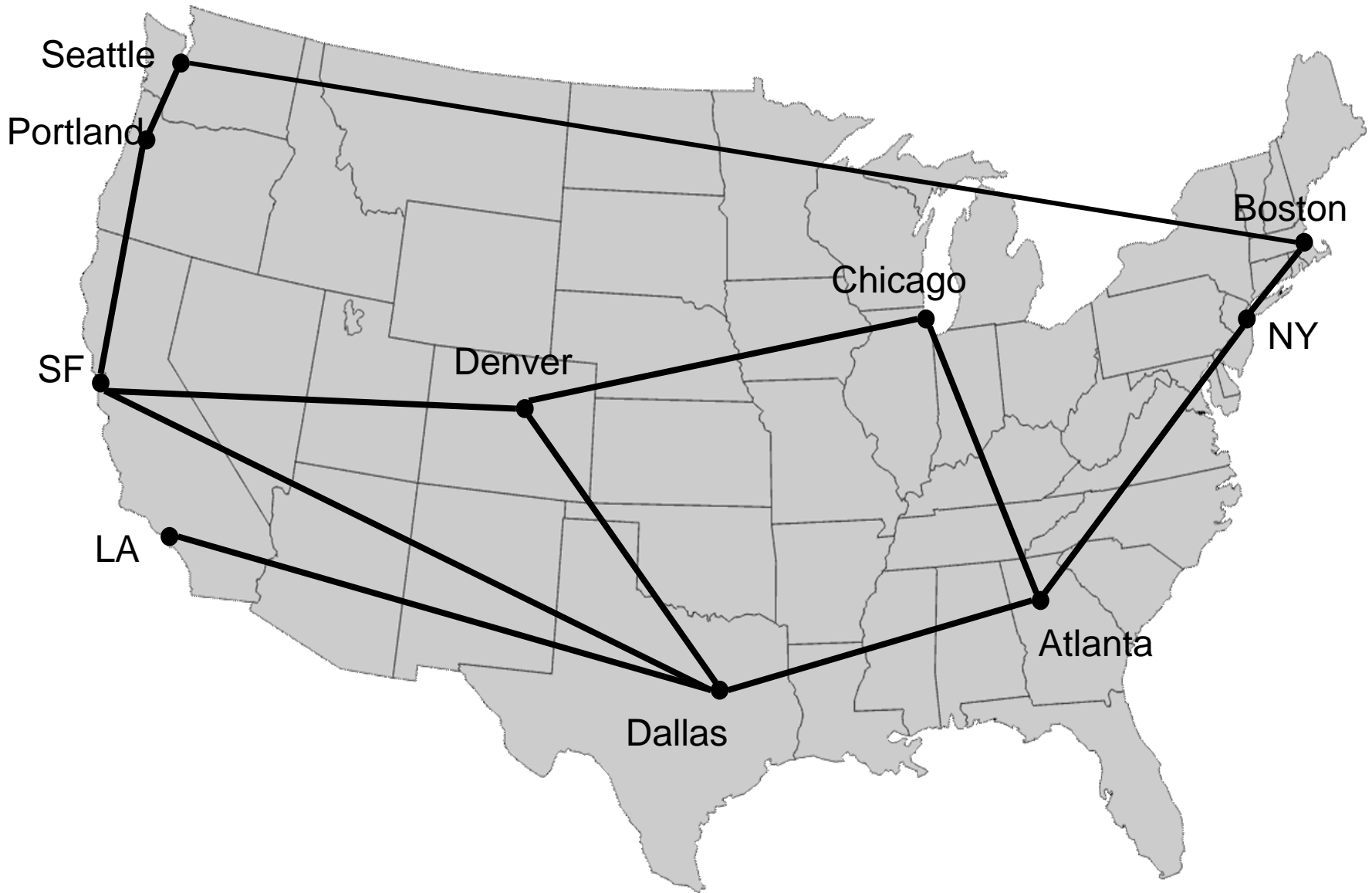
- social network

users , following (twitter)

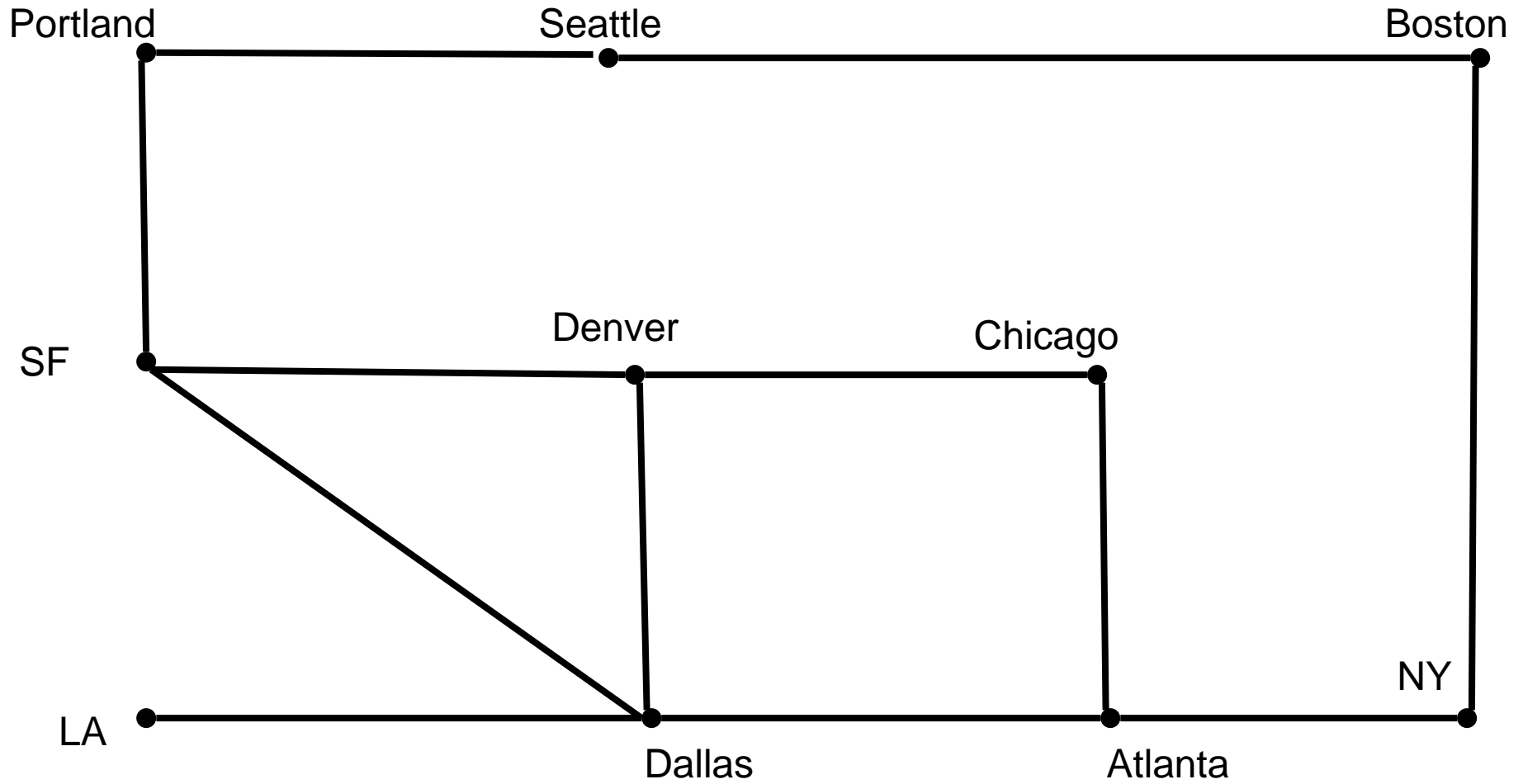
users , friend (facebook)



Nodes = subway stops; Edges = track between stops

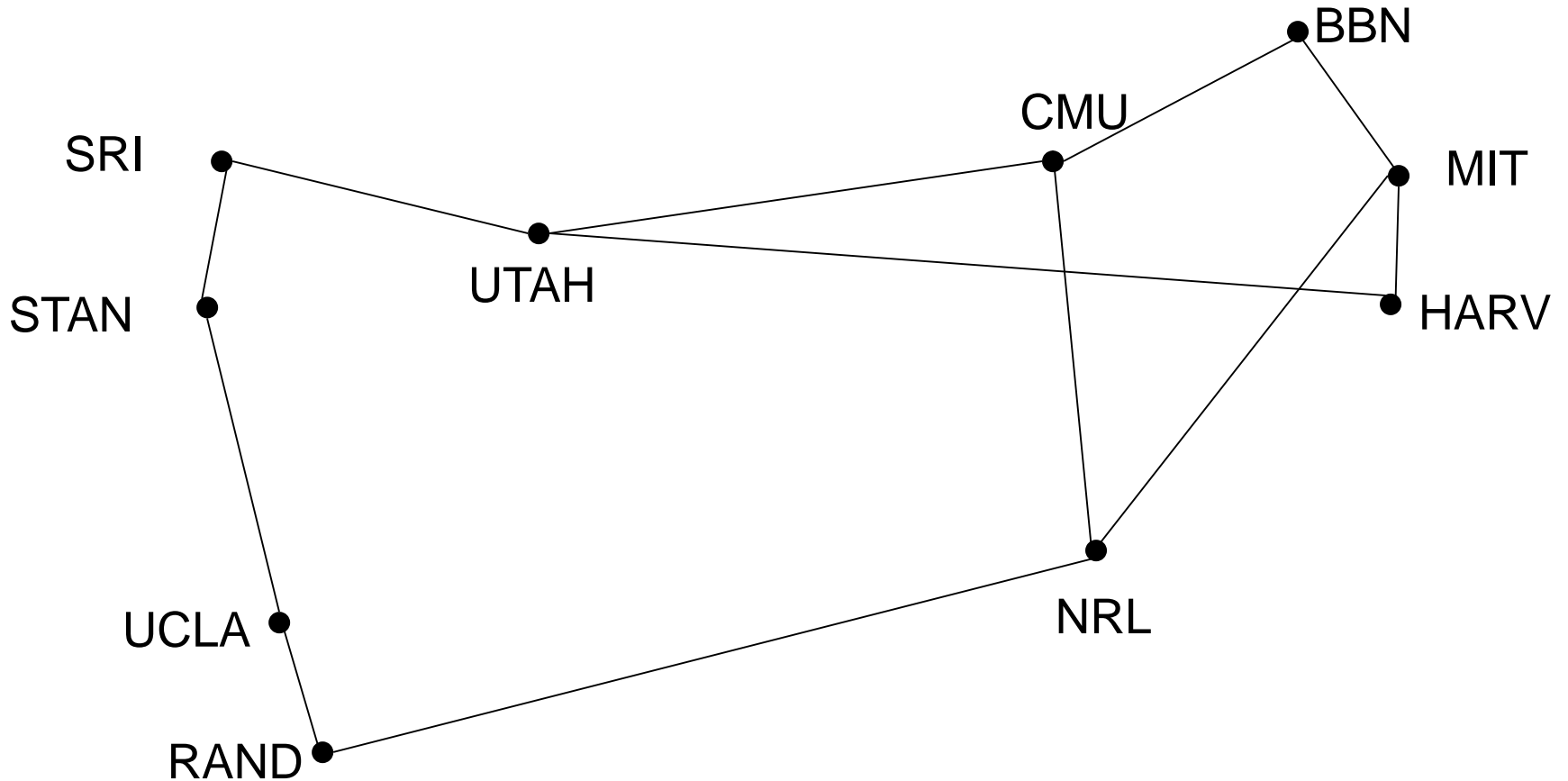


Nodes = cities; Edges = rail lines connecting cities



Connections in graph matter, not precise locations of nodes

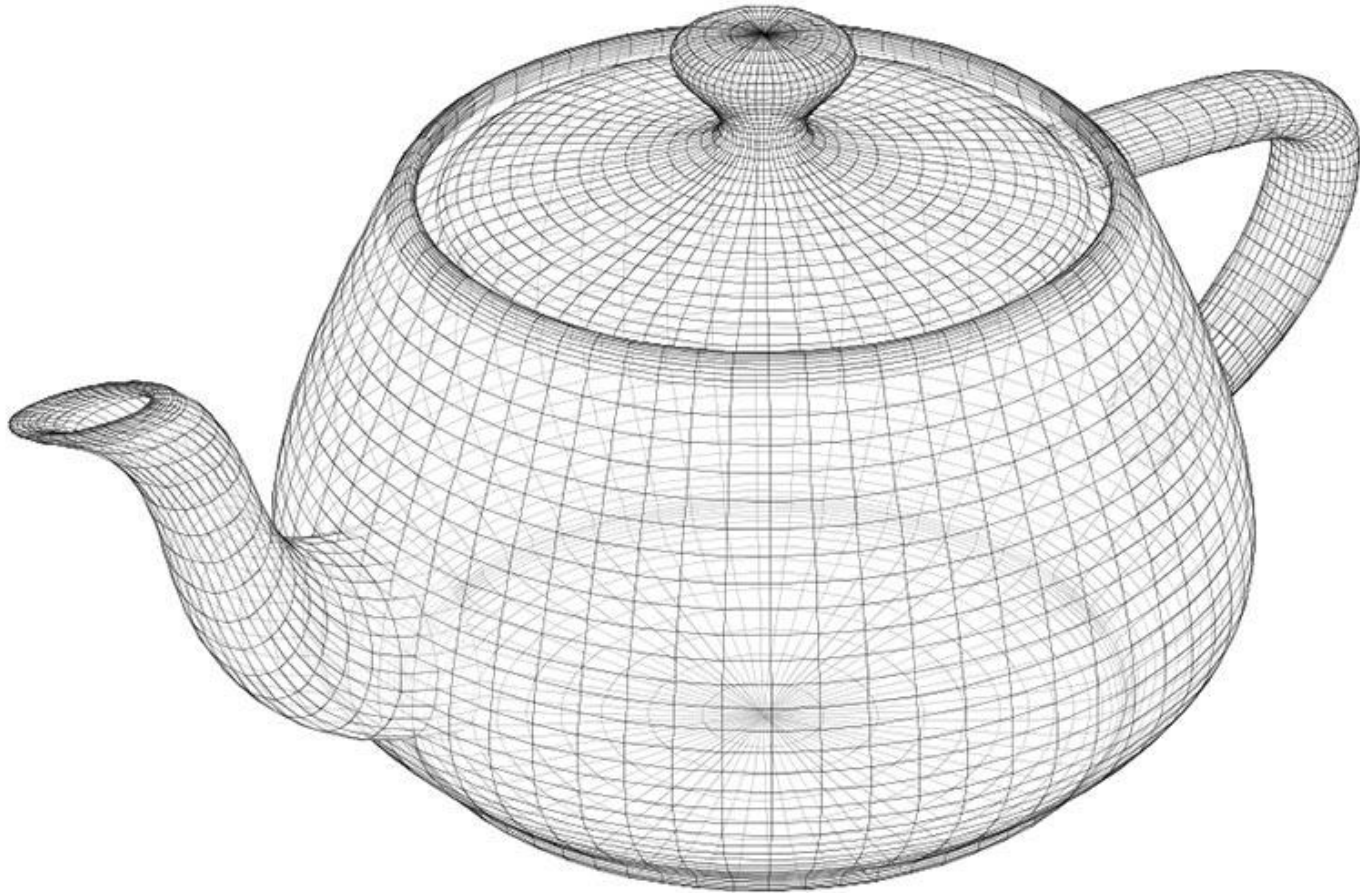
Internet (~1972)



Facebook social network graph



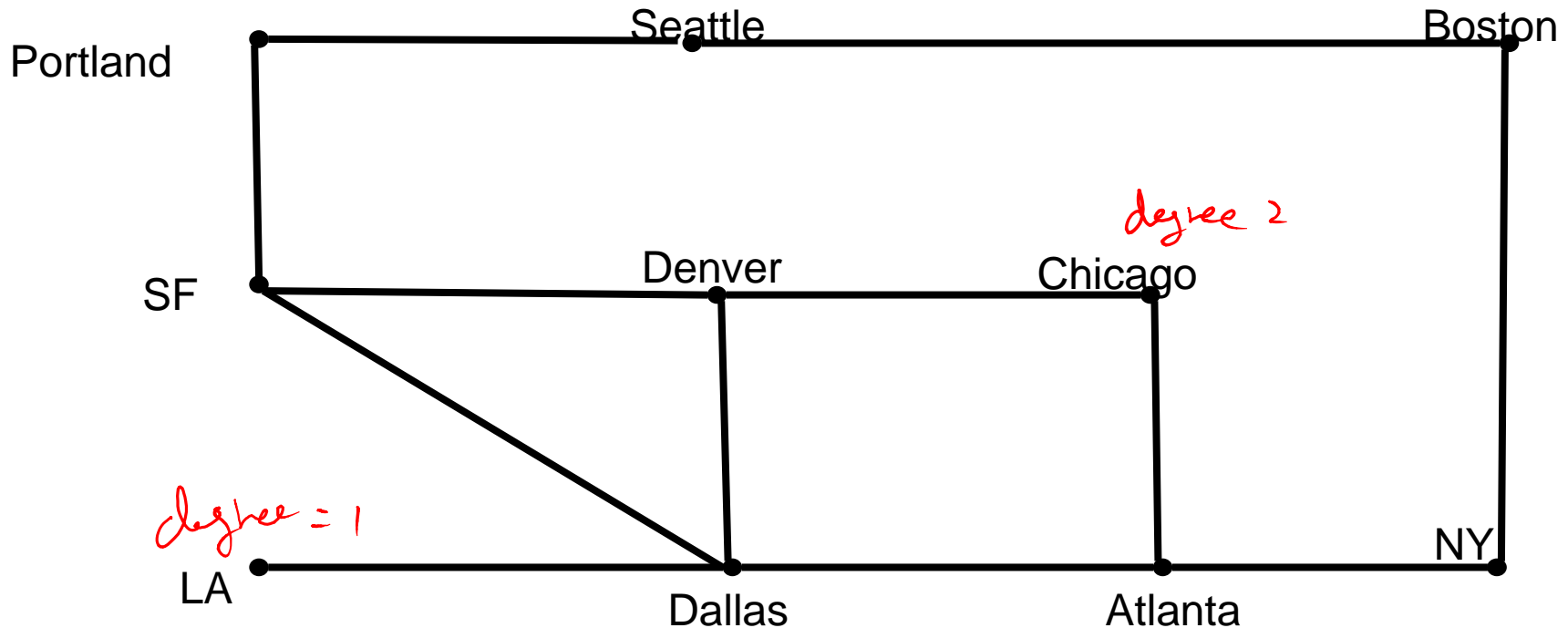
Wire-Frame Models



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Undirected Graph



An *undirected graph* is denoted as $G = (V, E)$, where

- V : set of vertices

u & v are adjacent if there is an edge connecting u and v .

- E : set of edges, and each edge is an unordered pair of vertices (we write $e = \{u, v\}$)

degree (v) = # of edges that are incident to v .

Walking Along a Graph

- A walk from u to v in a graph $G = (V, E)$ is an *alternating* sequence of vertices and edges (often, we just write the vertices)

if $u = v$

$$u = v_0, e_1, v_1, e_2, v_2, \dots, v_{k-1}, e_k, v_k = v$$

such that each $e_i = \{v_i, v_{i+1}\}$ for $i = 1, \dots, k$

closed walk

- A path (trail) is a walk where no edge appears more than once



circuit

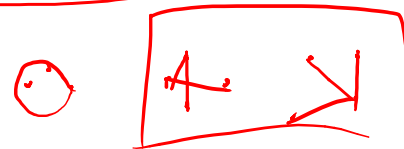
- A simple path (path) is a walk where no vertex appears more than once



cycle

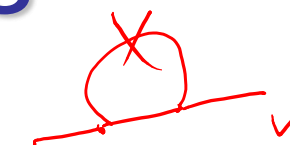

Reachability and Connectedness

- A vertex v in G is reachable from a vertex u in G if there is a path from u to v
 - Note, v is reachable from u *or walk* iff u is reachable from v
- An undirected graph G is connected if for every pair of vertices u, v in G , v is reachable from u (and vice versa)
- The set of all vertices reachable from v , along with all edges of G connecting any two of them, is called the connected component of v



G is not connected but has 2 CC.

Little Tiny Theorems

- If there is a walk from u to v , then 
 - there is a walk from v to u .
 - there is a path from u to v (and from v to u)
- If there is a path from u to v , then 
 - there is a simple path from u to v (and v to u)

[TAP] Sum of degrees

- Let $\text{deg}(v)$ be the degree of a vertex v . Is the following statement true?
- For any graph $G = (V, E)$

$$\sum_{v \in V} \text{deg}(v) = 2 |E|$$

where $|E|$ is the number of edges in G

T

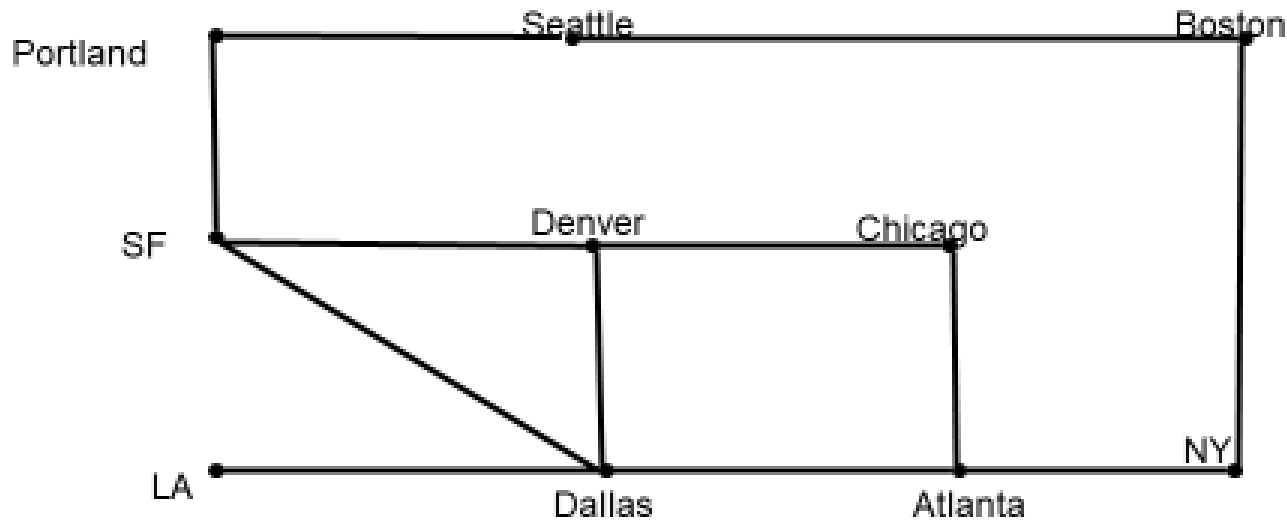
Q

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Directed Graph

Undirected Graph

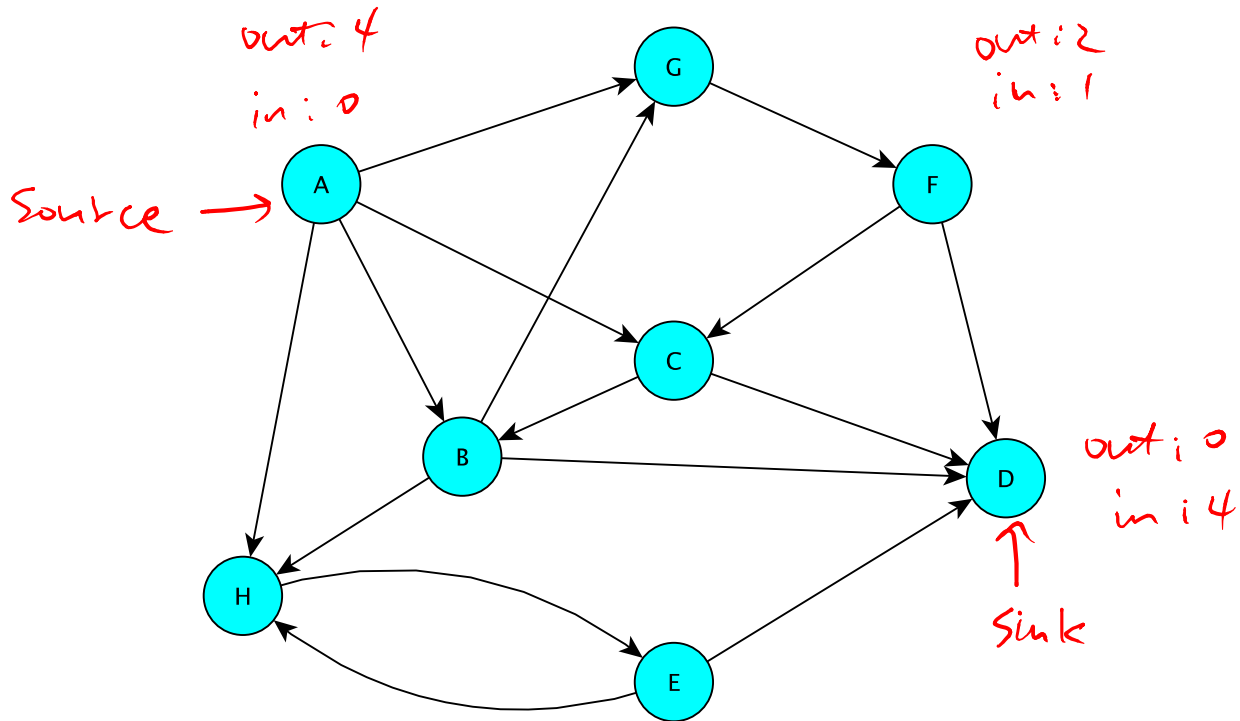


An *undirected graph* is denoted as $G = (V, E)$, where

- V : set of vertices
- E : set of edges, and each edge is an ~~unordered~~ pair of vertices (we write $e = \{u, v\}$)

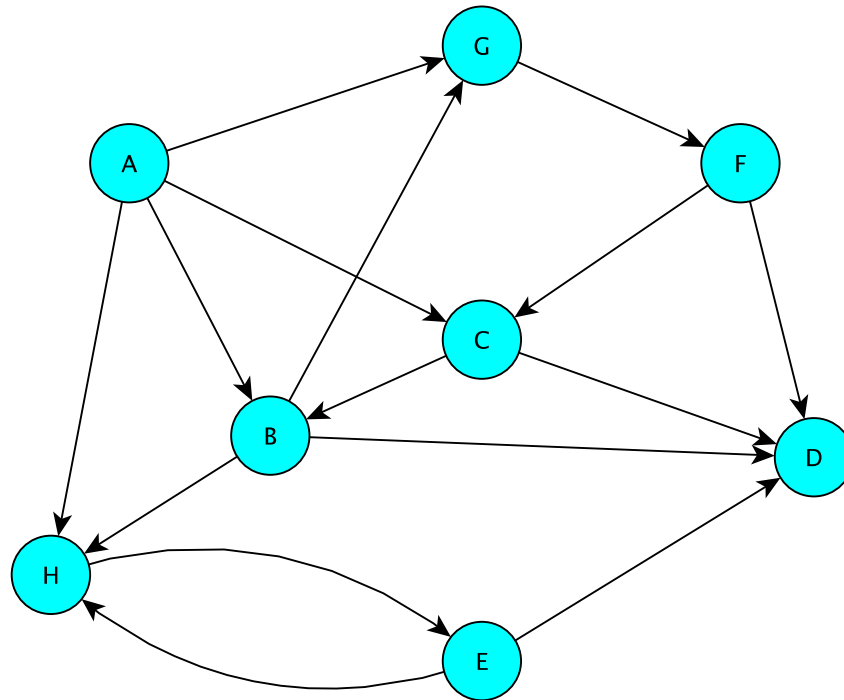
↑ source
↑ target/destination
ordered

Degrees



out-degree = # of outgoing edges
in-degree = # of incoming edges

Walking Along a Graph



The concept of a walk and path is still the same, but you can only walk along the direction of the edges.

Reachability and Connectedness

- A vertex v in G is *reachable* from a vertex u in G if there is a path from u to v
 - Note, v is reachable from u *iff* u is reachable from v (not necessarily. It's true if u and v are mutually reachable)
- An undirected graph G is *connected* if for every pair of vertices u, v in G , v is reachable from u (and vice versa)
- The set of all vertices reachable from v , along with all edges of G connecting any two of them, is called the *connected component* of v

connected



not strongly connected

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Implementing Graphs

- Involves a number of implementation decisions, depending on intended uses
 - What kinds of graphs will be supported?
 - Undirected, directed, mixed
 - What underlying data structures will be used?
 - What functionality will be provided
 - What aspects will be public/protected/private

Graphs in structure5

- Interface $\text{Graph}\langle V, E \rangle$ extends $\text{Structure}\langle V \rangle$
 - Type V holds a *label* for a vertex
 - Type E holds a *label* for an edge

information

*e.g. city name,
distance*

Desired Functionality

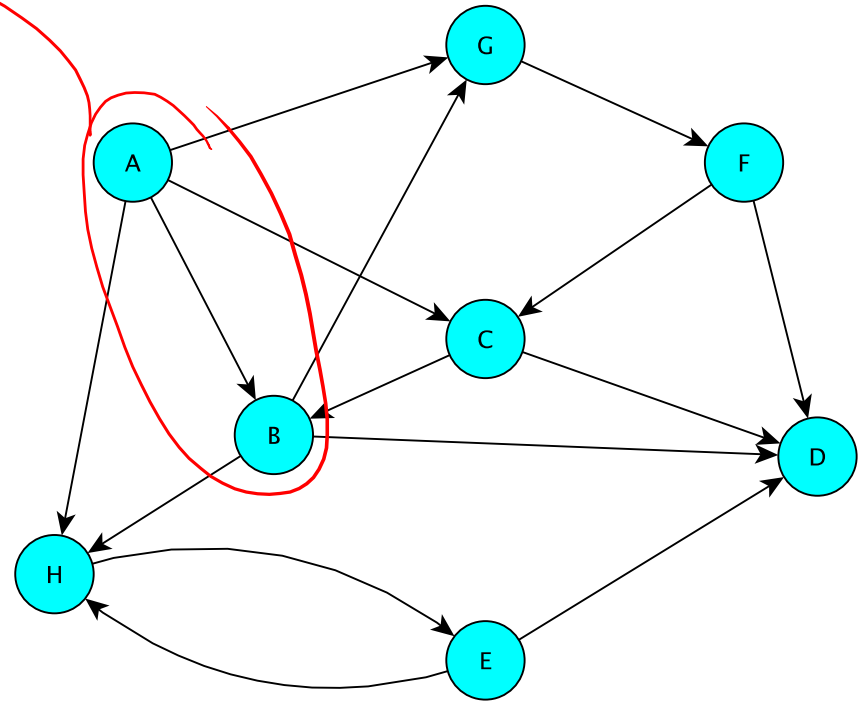
- What are the basic operations we need to describe algorithms on graphs?
 - Given vertices u and v : are they adjacent?
 - Given vertex v and edge e , are they incident?
 - Given an edge e , get its incident vertices (*ends*)
 - How many vertices are adjacent to v ? (*degree of v*)
 - The vertices adjacent to v are called its *neighbors*
 - Get a list of the neighbors of v (or the edges incident with v)

Representing Graphs

- Two standard approaches
 - Option 1: Array-based (directed and undirected)
 - Option 2: List-based (directed and undirected)

Adjacency Array: Directed Graph

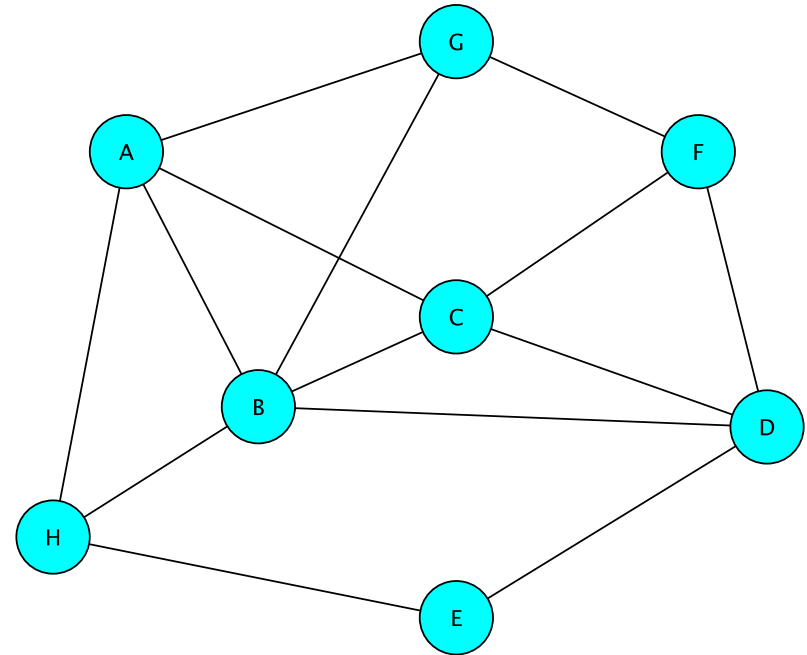
	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	0	0	0	1	0	0	1	1
C	0	1	0	1	0	0	0	0
D	0	0	0	0	0	0	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	0	0
G	0	0	0	0	0	1	0	0
H	0	0	0	0	1	0	0	0



Entry (i,j) stores 1 if there is an edge from i to j; 0 otherwise
E.G.: $\text{edges}(B,C) = 1$ but $\text{edges}(C,B) = 0$

Adjacency Array: Undirected Graph

	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	1	0	1	1	0	0	1	1
C	1	1	0	1	0	1	0	0
D	0	1	1	0	1	1	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	1	0
G	1	1	0	0	0	1	0	0
H	1	1	0	0	1	0	0	0



Entry (i,j) store 1 if there is an edge between i and j; else 0
E.G.: $\text{edges}(B,C) = 1 = \text{edges}(C,B)$

Adjacency Array: Undirected Graph

Halving the Space (not in structure5)

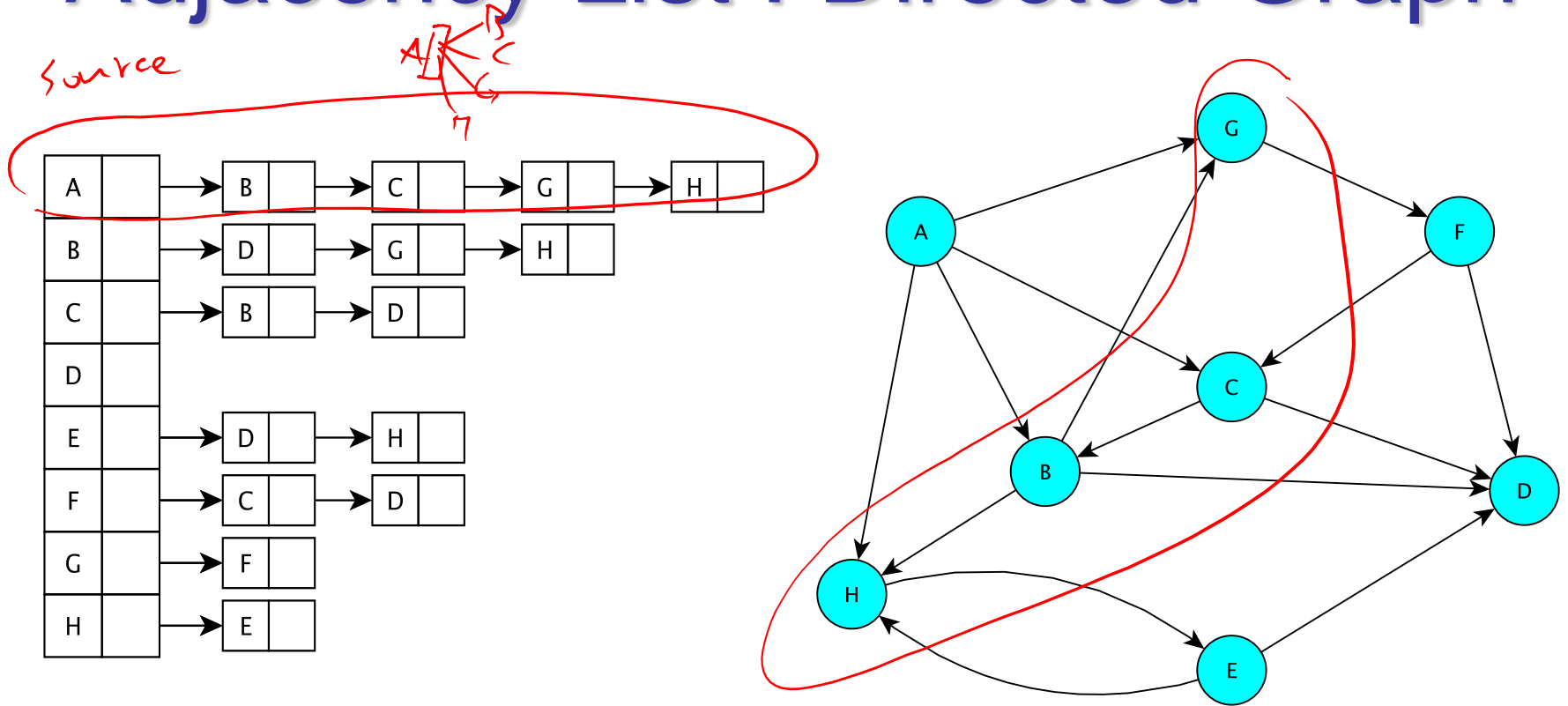
	0	1	2	3	4	5	6
0	0	1	1	0	0	0	1
1	1	0	1	1	0	0	1
2	1	1	0	1	0	1	0
3	0	1	1	0	1	1	0
4	0	0	0	1	0	0	0
5	0	0	1	1	0	0	1
6	1	1	0	0	0	1	0

	0	1	2	3	4	5	6
0	0	1	1	0	0	0	1
1		0	1	1	0	0	1
2			0	1	0	1	0
3				0	1	1	0
4					0	0	0
5						0	1
6							0

0	1	2	3	4	5	6	7	8	9	...																		
0	1	1	0	0	0	1	0	1	1	0	0	1	0	1	0	1	0	0	1	1	0	0	0	0	0	0	1	0

(i,j) maps to $i*7+j$

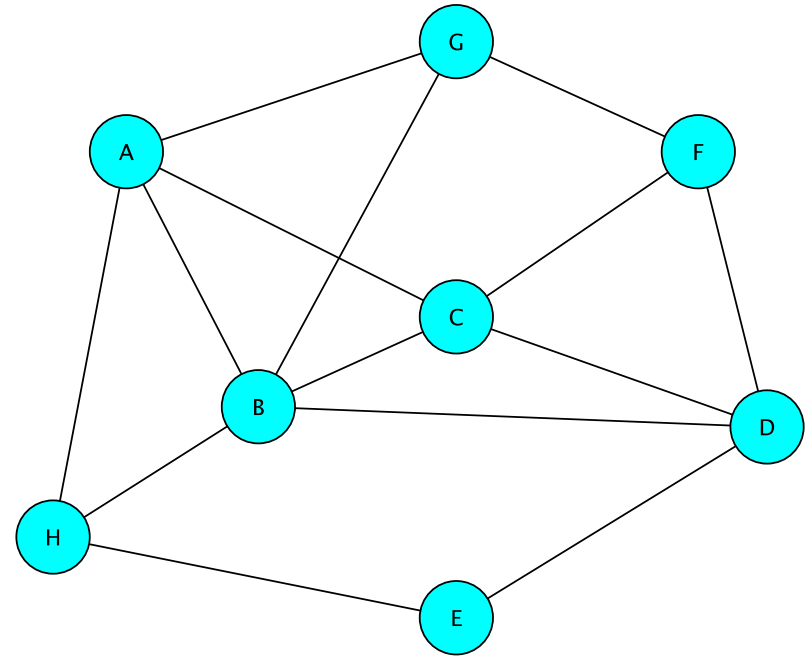
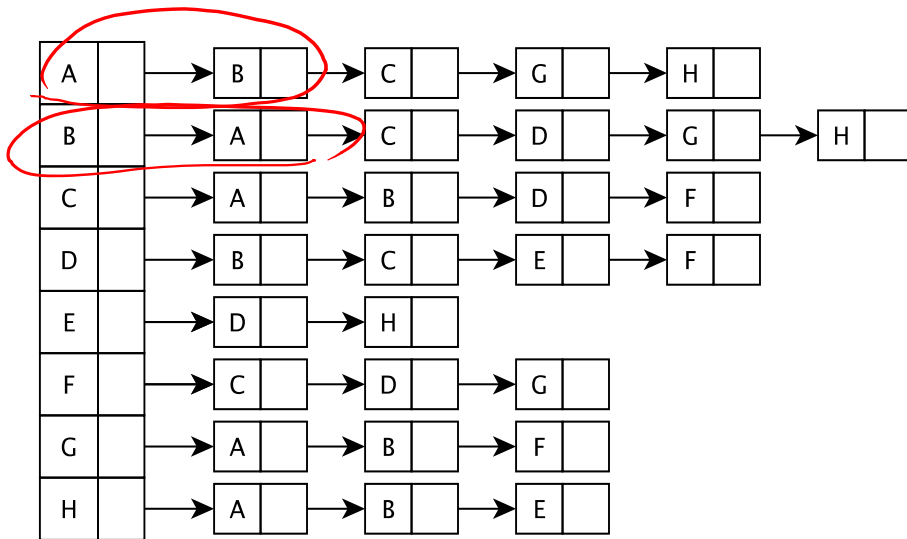
Adjacency List : Directed Graph



The vertices are stored in an array $V[]$

$V[]$ contains a linked list of edges having a given source

Adjacency List : Undirected Graph



The vertices are stored in an array $V[]$

$V[]$ contains a linked list of edges incident to a given vertex