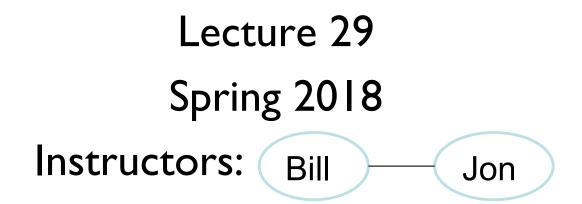
CSCI 136 Data Structures & Advanced Programming



Last Time

- BSTs
 - Balance is important to maintain height (logn)
 - AVL Trees
 - Rotate left, rotate right
 - One of many types of balanced trees
- Game Trees
 - Backwards induction

Today's Outline

- Introduction To Graphs
 - Definitions and Properties: Undirected Graphs
 - Small Proofs
 - Rechability
 - Graph Interface in Structure5

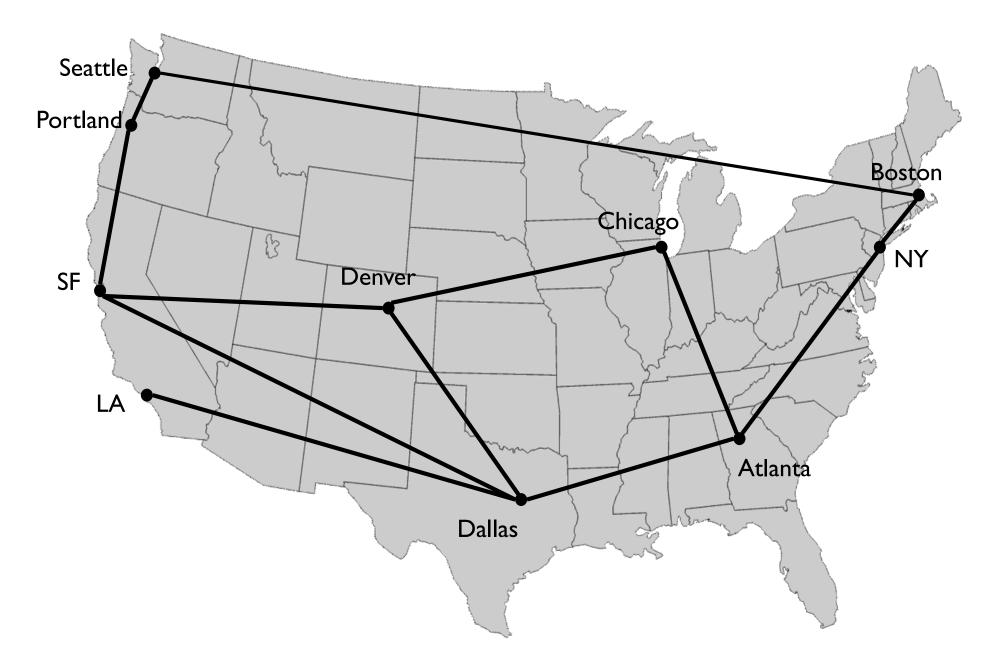
Graphs Describe the World¹

- Transportation Networks
- Communication Networks
- Social Networks
- Molecular structures
- Dependency structures
- Scheduling
- Matching
- Graphics Modeling

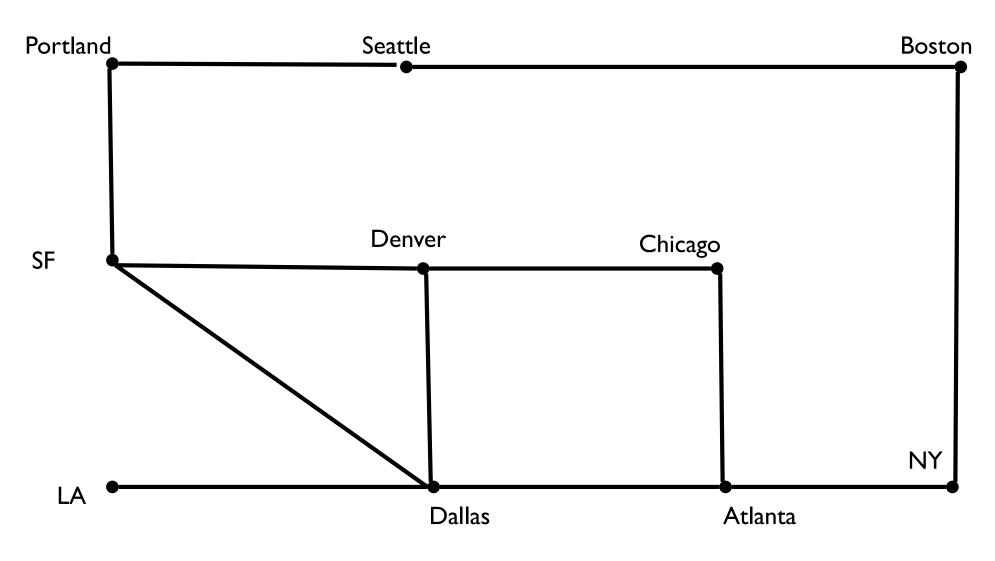




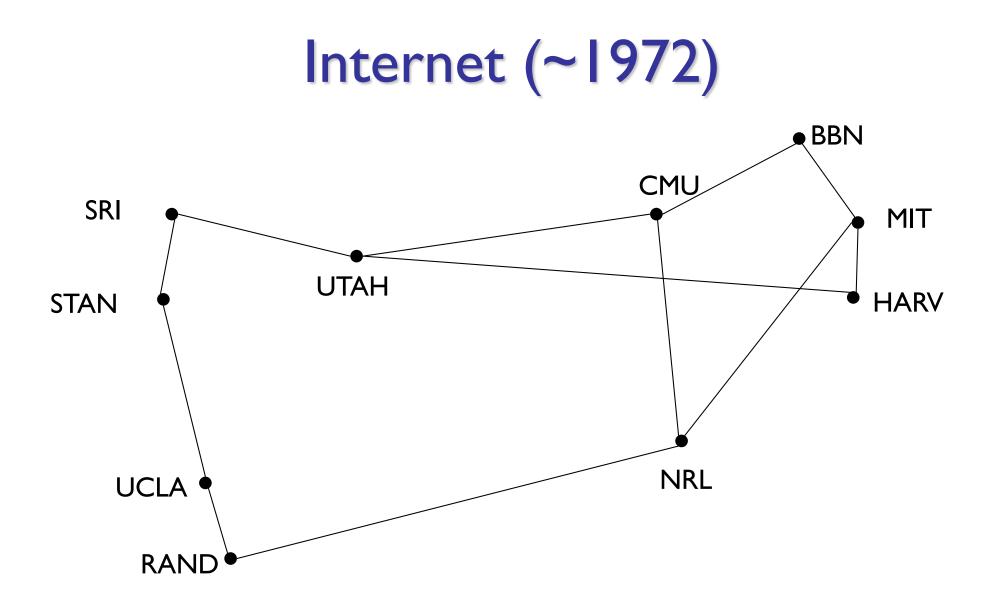
Nodes = subway stops; Edges = subway lines



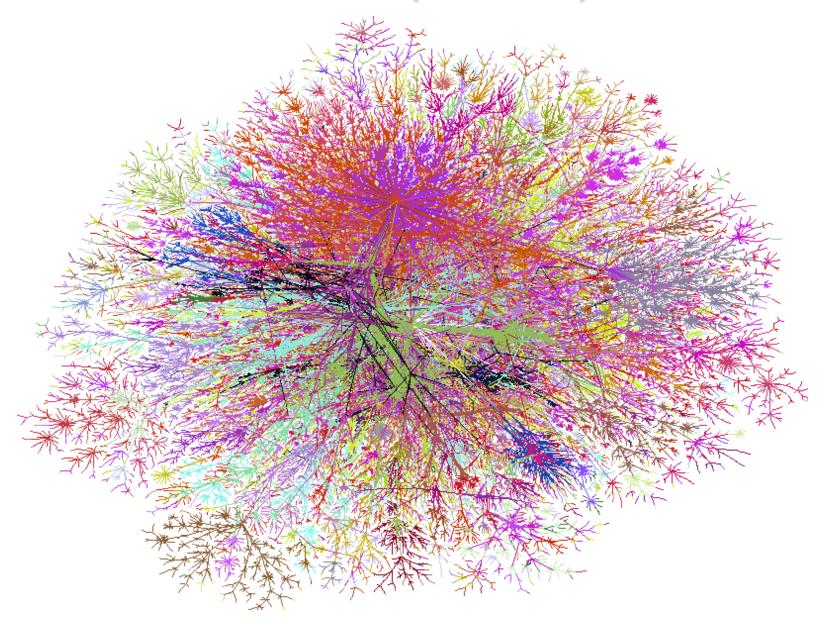
Nodes = cities; Edges = rail lines connecting cities

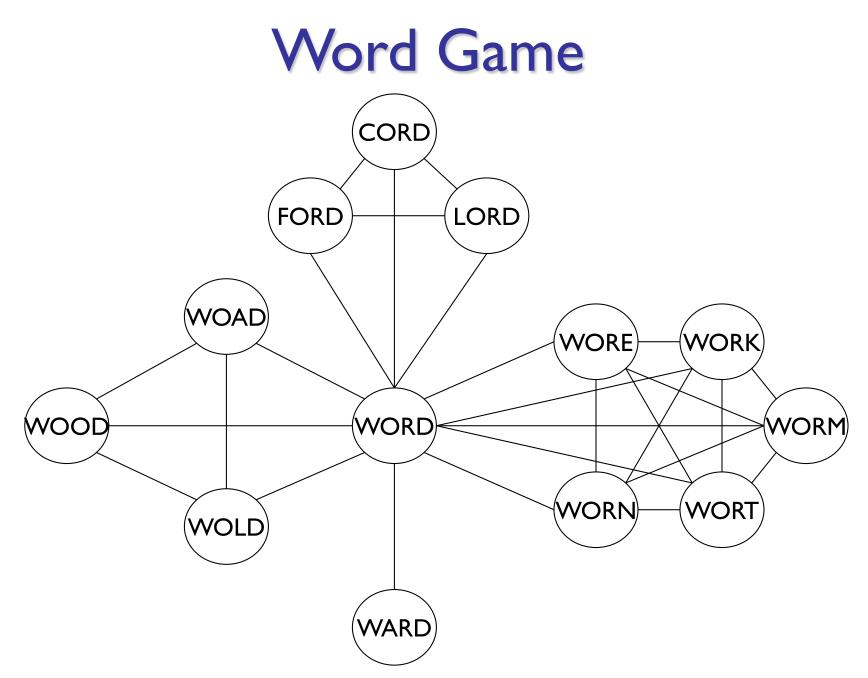


Note: Connections in graph matter, not precise locations of nodes



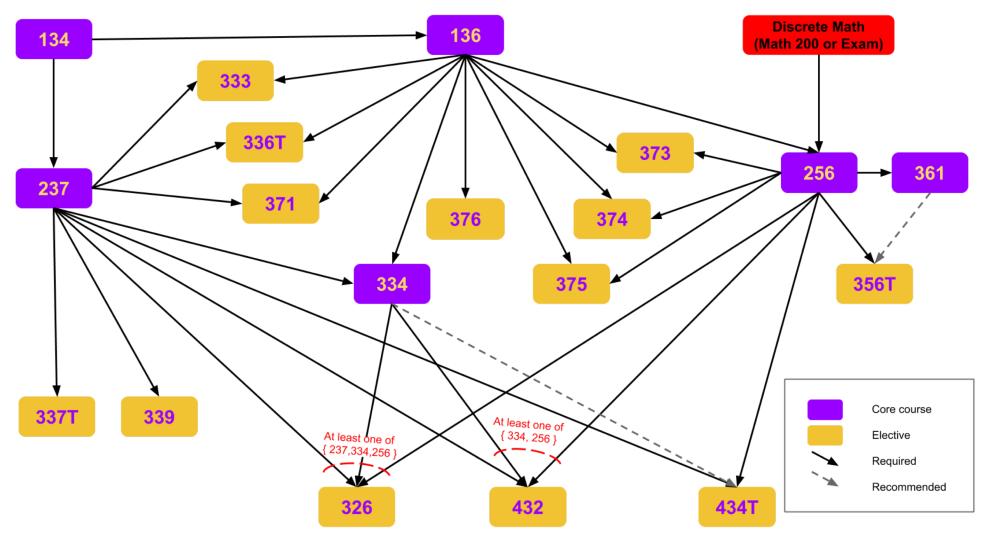
Internet (~1998)





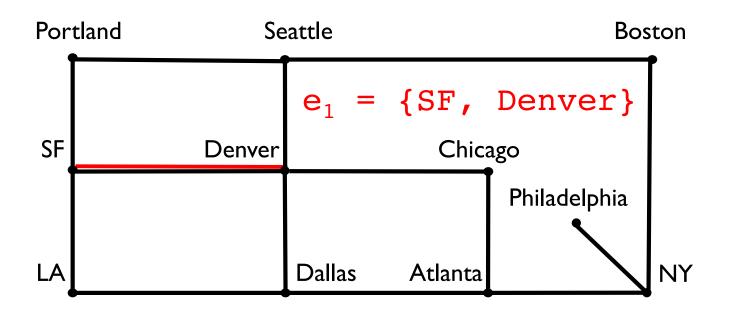
Nodes = words; Edges = words that differ by exactly one letter





Nodes = courses; Edges = prerequisites ***

Basic Definitions & Concepts



Definition: An *undirected graph* G = (V, E) consists of two sets

- V: the *vertices* of G, and E: the *edges* of G
- Each edge e in E is defined by a set of two vertices: its *incident vertices*.
- We write e = {u,v} and say that u and v are *adjacent*.

Basic Definitions & Concepts

- Definition: An undirected graph G = (V, E) consists of two sets:
 - V : the vertices of G
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- Each edge e in E is defined by a set of two vertices: its *incident vertices*
- We write $e = \{u, v\}$ and say that u and v are *adjacent*
- The degree of a vertex is the number of *incident edges* (loops counted twice)

Walking Along a Graph

 A walk from u to v in a graph G = (V,E) is an alternating sequence of vertices and edges

 $u = v_0, e_1, v_1, e_2, v_2, ..., v_{k-1}, e_k, v_k = v$

such that each $e_i = \{v_i, v_{i+1}\}$ for i = 1, ..., k

- (Note a walk starts and ends on a vertex)
- If no edge appears more than once then the walk is called a path
- If no vertex appears more than once then the walk is a simple path

Walking In Circles

• A closed walk in a graph G = (V,E) is a walk $v_0, e_1, v_1, e_2, v_2, ..., v_{k-1}, e_k, v_k$

such that $v_0 = v_k$ (it ends at the starting v)

- A circuit is a path where v₀ = v_k
 Circuit vs. closed walk? Circuit has no repeat edges
- A cycle is a simple path where v₀ = v_k
 Circuit vs. cycle? Cycle has no repeated vertices.
- The length of any of these is the number of edges in the sequence

Little Tiny Theorems

- If there is a walk from u to v, then there is a walk from v to u.
- If there is a walk from u to v, then there is a path from u to v (and from v to u)
- If there is a path from u to v, then there is a simple path from u to v (and v to u)
- Every circuit through v contains a cycle through v
- Not every closed walk through v contains a cycle through v! [Try to find an example!]

A Basic Graph Fact

- Denote the degree of a vertex v by deg(v).
- **Theorem**: For any graph G = (V, E)

$$\sum_{v \in V} \deg(v) = 2 |E|$$

where |E| is the number of edges in G

- Proof Hint: Induction on |E|: How does removing an edge change the equation?
 - Instead: Count pairs (v,e) where v is incident with e

Reachability and Connectedness

- **Definition:** A vertex v in G is *reachable* from a vertex u in G if there is a path from u to v
 - $\bullet \ v$ is reachable from u iff u is reachable from v
- Definition: An undirected graph G is connected if for every pair of vertices (u, v) in G, v is reachable from u (and vice versa)
- The set of all vertices reachable from v, along with all edges of G connecting any two of them, is called the *connected component* of v

Basic Graph Algorithms

- We'll look at a number of graph algorithms
 - Connectedness: Is G connected?
 - If not, how many connected components does G have?
 - Cycle testing: Does G contain a cycle?
 - Does G contain a cycle through a given vertex?
 - If the edges of G have costs:
 - What is the cheapest subgraph connecting all vertices
 - Called a connected, spanning subgraph
 - What is a cheapest path from u to v?
 - And more.... (if not here, then in CSCI 256!)

Testing Connectedness

- How can we determine whether G is connected?
 - Pick a vertex v; see if every vertex u is reachable from \boldsymbol{v}
- How could we do this?
 - Visit the neighbors of v, then visit their neighbors, etc. See if you reach all vertices

• (Assume we can mark a vertex as "visited")

• How do we manage all of this visiting?

Reachability: Breadth-First Search

 $BFS(G, v) \qquad // Do \ a \ breadth-first \ search \ of \ G \ starting \ at \ v$ $// pre: \ all \ vertices \ are \ marked \ as \ unvisited$ $count \ \leftarrow 0;$ $Create \ empty \ queue \ Q; \ enqueue \ v; \ mark \ v \ as \ visited; \ count++$ $While \ Q \ isn't \ empty$ $current \ \leftarrow Q. dequeue();$ $for \ each \ unvisited \ neighbor \ u \ of \ current :$ $add \ u \ to \ Q; \ mark \ u \ as \ visited; \ count++$

return count;

Now compare value returned from BFS(G,v) to size of V

BFS Reflections

- The BFS algorithm traced out a tree T_v: the edges connecting a visited vertex to (as yet) unvisited neighbors
- T_v is called a BFS tree of G with root v (or from v)
- The vertices of T_v are visited in *level-order*
- This reveals a natural measure of distance between vertices: the length of (any) shortest path between the vertices