CSCI 136 Data Structures & Advanced Programming

> Bill Jannen Lecture 32 May 3, 2017

Administrative Details

- Lab 10 Today/Thursday
 - Bring design documents to lab!
- Quick Hexapawn Demo?

- Lab 10 is the last lab...
 - Next week we will post a sample exam instead
- Review session:
 - Monday 5/15 from 7-9pm in Physics 203

Last Time (Monday)

- Finished Binary Search Trees
 - predecessor(), remove()
 - Game Trees
 - For lab, you don't need to implement backwards induction
 - ComputerPlayer moves randomly, but...
 - Each time ComputerPlayer loses, prune losing node

Today's Outline

- Introduction to Graphs!
 - Examples
 - Terminology
 - 2 Representations

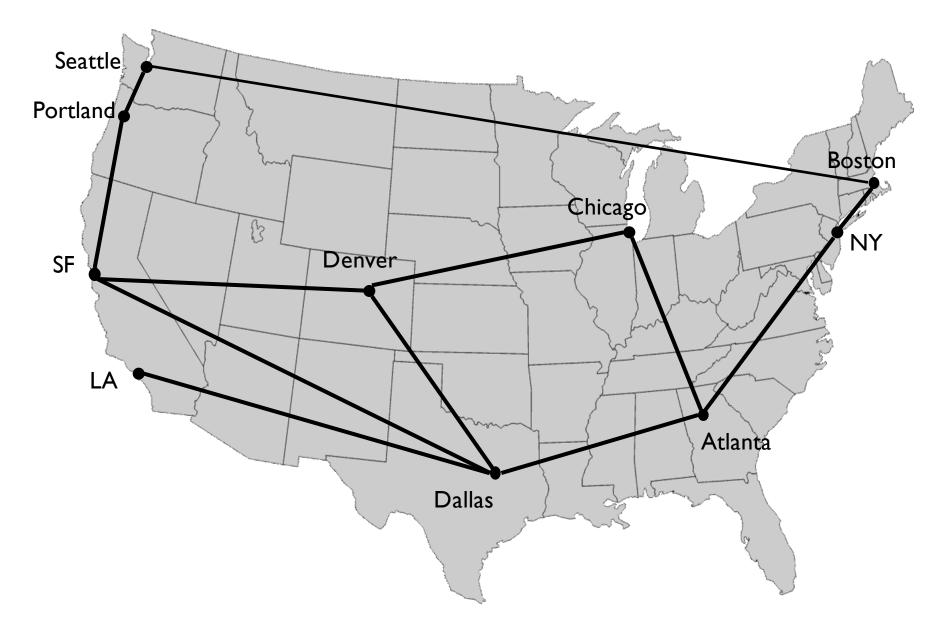
Putting Data Structures in Context

• Types of data structures

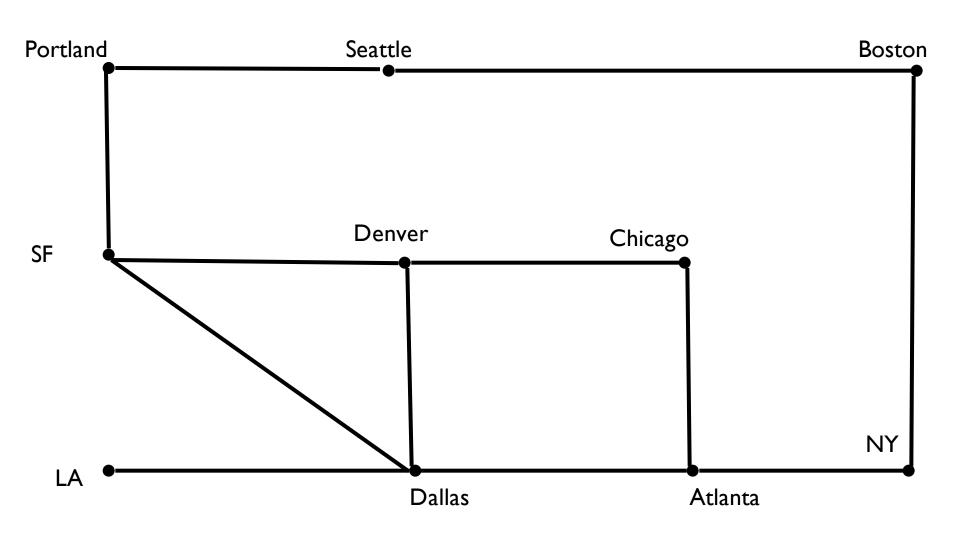
- Basic Lists/Vectors (no ordering relation)
- Linear Stacks/Queues (ordered by insertion)
- Ordered Structures value ordering
- Tree hierarchical ordering
- BST value ordering (in a hierarchical fashion)
- Next up: Graphs
 - The most general way to describe relationships between data

Graphs

- Definition
 - A graph is a collection of vertices (nodes) and edges (links) connecting them
- Let's use real world examples for intuitions



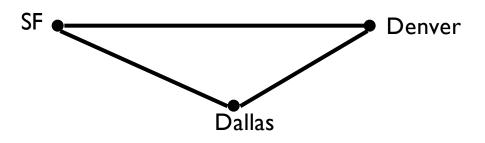
Nodes = cities; Edges = lines connecting cities



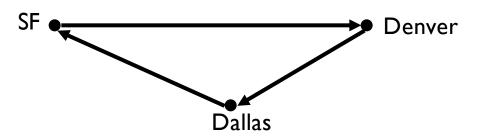
Note: Structure of graph matters, not actual placement of nodes

Types of Graphs

- Undirected
 - All edges are bi-directional

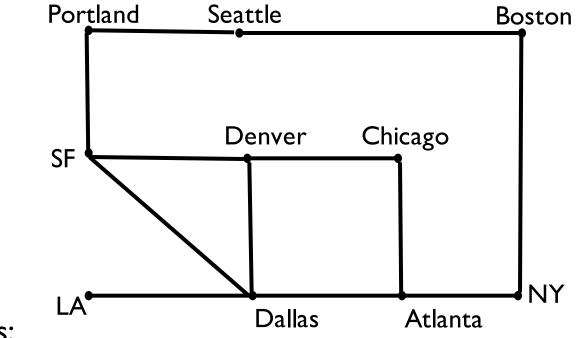


- Directed
 - Edges have a source and destination



Paths

- A *path* is a sequence of distinct edges between two nodes
- A cycle is a path that starts and ends at the same node

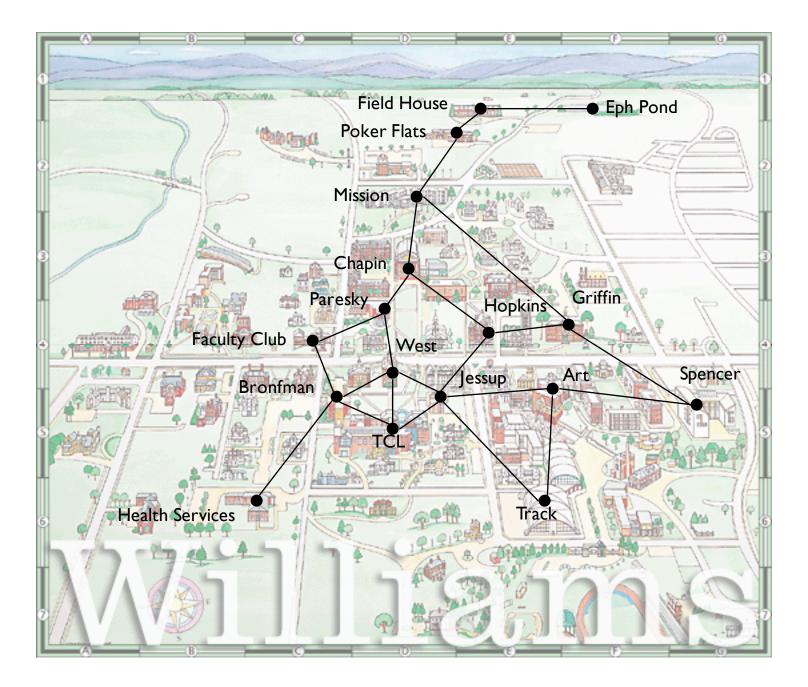


- Questions:
 - What is the shortest path from SF to Boston?
 - What is the shortest cycle from SF to SF that goes through Dallas and Chicago?

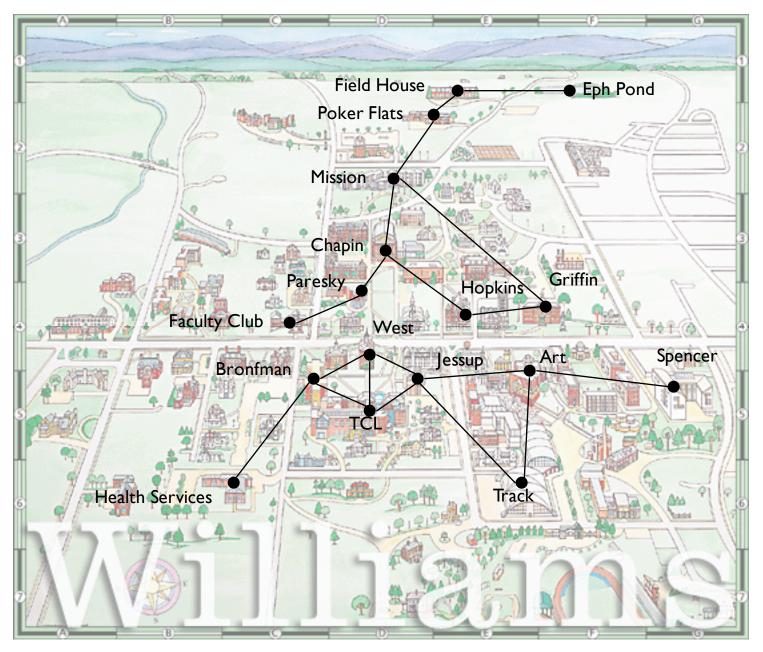
Connectedness

Nodes U and V are connected if there is an edge between U and V

- A connected component is a set S where there is a path between every vertex pair in S
- A fully connected component is a set S where there is an edge between every pair of vertices in S

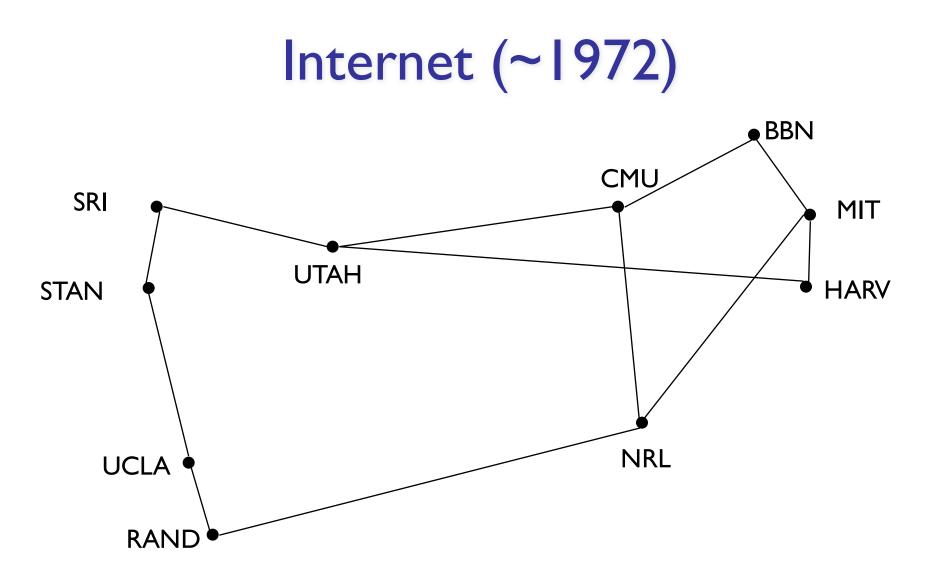


What's reachable from TCL?

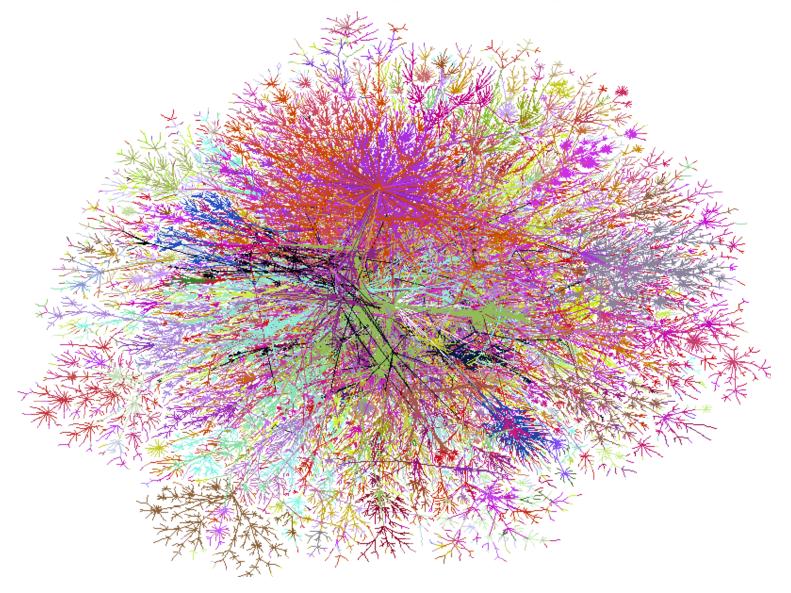


Graph Applications

- Connectedness in the real world
 - Flights, campus, (social) networks, etc.
 - Useful to finding shortest number of steps/hops

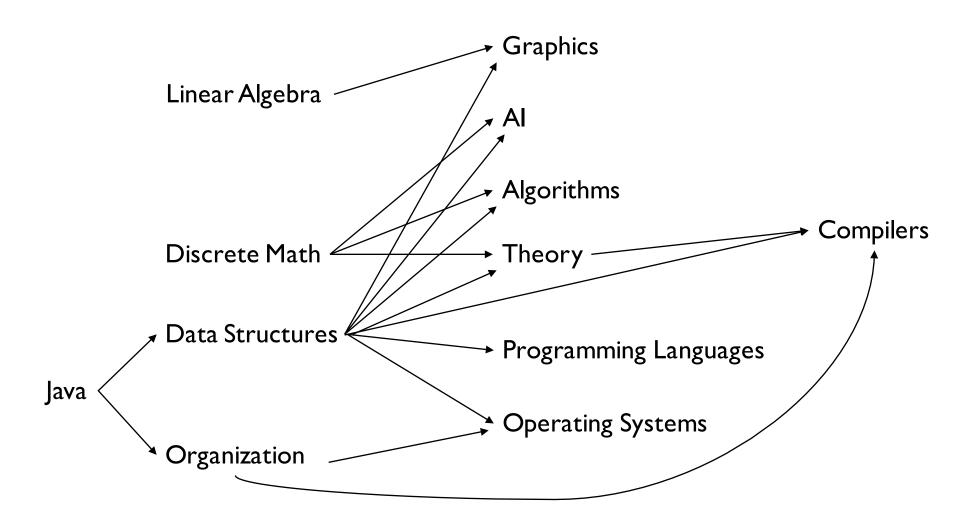






Graph Applications

- Connectedness in the real world
 - Flights, campus, (social) networks, etc.
 - Often useful to find shortest number of steps/hops
- CS Courses
 - In edges/out edges indicate prerequisite relationships (why no cycles?)



Question: Is this a tree?

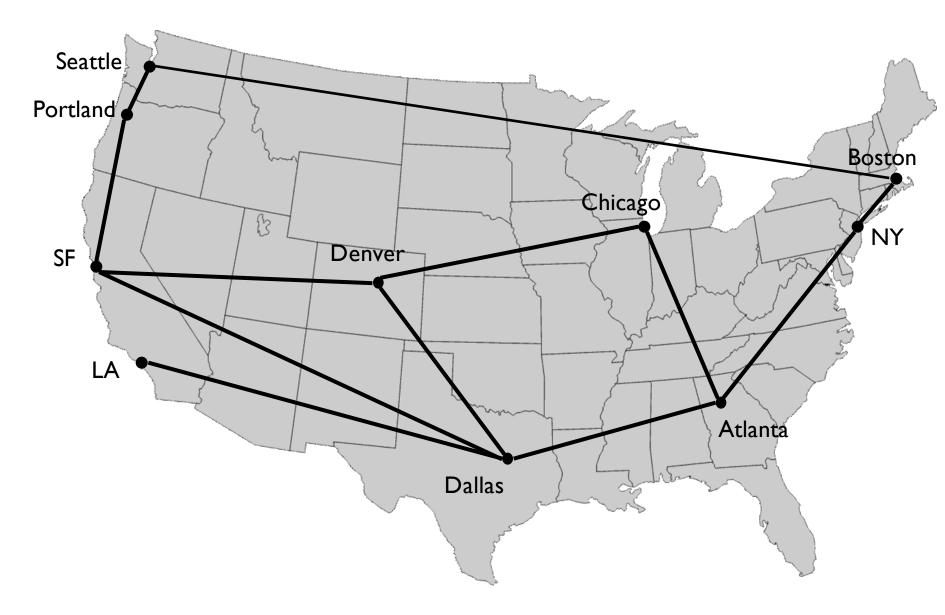
• No! No root node, Courses can have multiple parents

Vertices and Edges

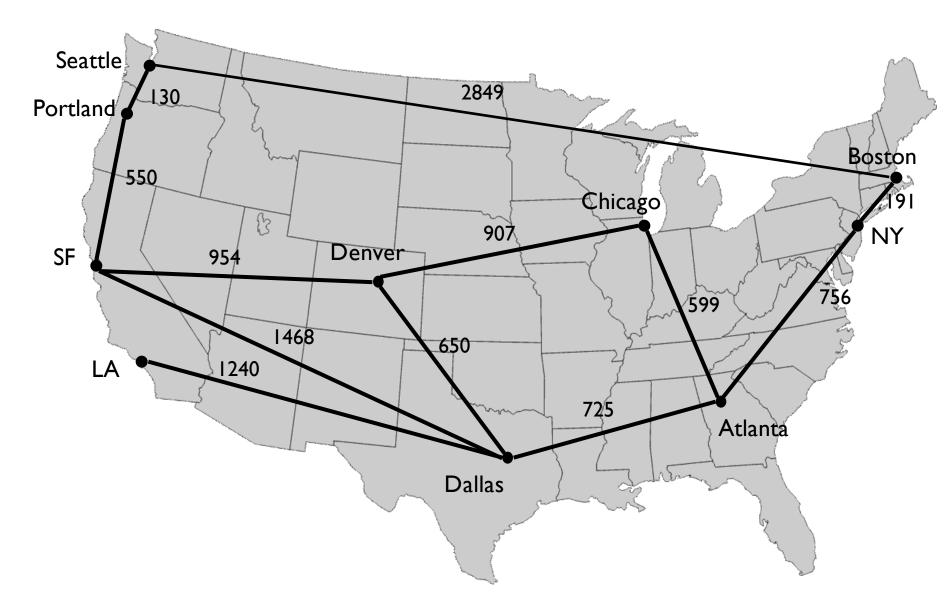
- Vertices represent "things"
- Edges encode relationships between "things"
 - Not all edges are the same

Edges

- Edges can have different "weight"
- Weight = the cost of traversing that edge
 - Cost may be a function of time, distance, price to pay, probability, etc.
- May lead to different solutions to previously answered questions
 - What is shortest path between SF and NY given edge weights?



• What is the shortest path from SF to Boston?



• What is the shortest path from SF to Boston?

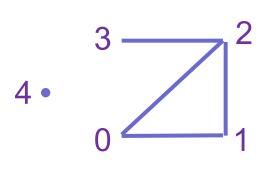
Representing Graphs

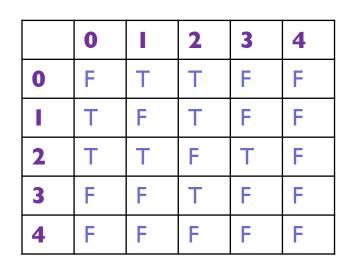
Let's think back to the ways we represented trees:

- Nodes store explicit pointers to parent/children
- Nodes are stored in a Vector
 - Which was better for sparse trees?
 - Which was better for dense trees?

Adjacency Matrix

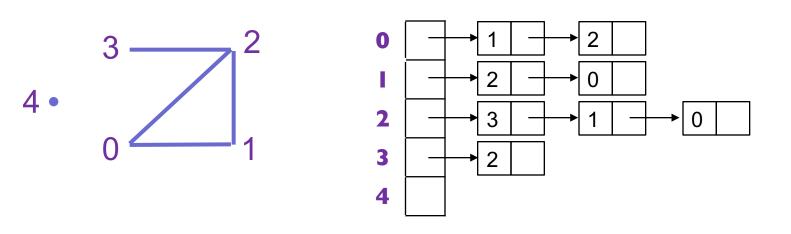
- Let G = (V, E) be a graph with *n* vertices
 - Number the vertices 0...n-1
 - The adjacency matrix of G is an n x n matrix where each (x,y) coordinate is T if there is an edge between v_x,v_y and F otherwise.
- Example:





Adjacency List

- Let G = (V, E) be a graph with *n* vertices
 - Number the vertices 0...n-1
 - The adjacency list of G is a Vector of length *n* where each entry in the Vector contains a list of all adjacent vertices.
- Example:



Representation Tradeoffs

- Let G = (V, E) be a graph with *n* vertices
- What is the maximum number of edges in G?
 - $m \leq n^2$ (every node connected to every other node)
- G is dense if m is close to n^2
- G is sparse if m is far from n^2

Representation Tradeoffs		
• $G = (V, E)$ with $ E = m, V = n$		
	Adjacency Matrix	Adjacency List
Space	O(n ²)	O(n+m)
Time to check if v_1 connected to v_2	O(1)	O(out-degree(v ₁))
Time to find all v _i adjacent to v ₁	O(n)	O(out-degree(v ₁))
Time to visit all edges	O(n²)	O(n+m)

No Clear Efficiency Winner

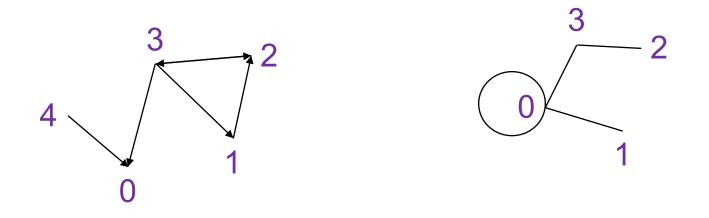
- Matrix is better for dense graphs
- List is better for sparse graphs
- Graphs "in the middle"?

Other Considerations

- What API should graphs support?
 - Want to lookup vertices by label
 - Want extra information to manage traversals
 - "Visited" info for nodes and edges
- What does it mean for two vertices to be equal? Two edges?
- Next class we will talk about implementation details and traversal strategies...

Practice

• Draw the adjacency matrix and adjacency list representations of the following graphs:



What does it mean for an adjacency matrix to be symmetric?