# CSCI 136 Data Structures & Advanced Programming

Lecture 27

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Instructors:



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#### Last Time

- Introduction To Graphs
  - Definitions and Properties: Undirected Graphs

## Today's Outline

- More on Graphs
  - Applications and Problems
    - Testing connectedness
    - Counting connected components
      - Breadth-first and Depth-first search
  - Directed Graphs
    - Definition and Properties
  - Reachability and (Strong) Connectedness
- Graph Data Structures: Preliminaries
  - Graph Interface

#### Reachability and Connectedness

- Def'n: A vertex v in G is reachable from a vertex u in G if there is a path from u to v
- v is reachable from u iff u is reachable from v
- Def'n: An undirected graph G is connected if for every pair of vertices u, v in G, v is reachable from u (and vice versa)
- The set of all vertices reachable from v, along with all edges of G connecting any two of them, is called the *connected component of v*

#### Basic Graph Algorithms

- We'll look at a number of graph algorithms
  - Connectedness: Is G connected?
    - If not, how many connected components does G have?
  - Cycle testing: Does G contain a cycle?
    - Does G contain a cycle through a given vertex?
  - If the edges of G have costs:
    - What is the cheapest subgraph connecting all vertices
      - Called a connected, spanning subgraph
    - What is a cheapest path from u to v?
  - And more....

## Operations on Graphs

- What are the basic operations we need to describe algorithms on graphs?
  - Given vertices u and v: are they adjacent?
  - Given vertex v and edge e, are they incident?
  - Given an edge e, get its incident vertices (ends)
  - How many vertices are adjacent to v? (degree of v)
    - The vertices adjacent to v are called its neighbors
  - Get a list of the vertices adjacent to v
    - From which we can get the edges incident with v

#### Testing Connectedness

- How can we determine whether G is connected?
  - Pick a vertex v; see if every vertex u is reachable from v
- How could we do this?
  - Visit the neighbors of v, then visit their neighbors,
     etc. See if we reach all vertices
    - Assume we can mark a vertex as "visited"
- How do we manage all of this visiting?
  - Let's try an example...

## Reachability: Breadth-First Search

```
BFS(G, v) // Do a breadth-first search of G starting at v
// pre: all vertices are marked as unvisited
count \leftarrow 0;
Create empty queue Q; enqueue v; mark v as visited; count++
While Q isn't empty
        current \leftarrow Q.dequeue();
        for each unvisited neighbor u of current:
                 add u to Q; mark u as visited; count++
return count;
```

Now compare value returned from BFS(G,v) to size of V

#### **BFS** Reflections

- The BFS algorithm traced out a tree  $T_v$ : the edges connecting a visited vertex to (as yet) unvisited neighbors
- T<sub>v</sub> is called a BFS tree of G with root v (or from v)
- The vertices of T<sub>v</sub> are visited in *level-order*
- This reveals a natural measure of distance between vertices: the length of (any) shortest path between the vertices

#### Distance in Undirected Graphs

Def: The distance between two vertices u and v in an undirected graph G=(V,E) is the minimum of the path lengths over all u-v paths.

- It is the depth of u in  $T_v$ : a BFS tree from v
- We write it as d(u,v). It satisfies the properties
  - d(u,u) = 0, for all  $u \in V$
  - d(u,v) = d(v,u), for all  $u,v \in V$
  - $d(u,v) \leq d(u,w) + d(w,v)$ , for all  $u,v,w \in V$
- This last property is call the triangle inequality

## Reachability: Depth-First Search

```
DFS(G, v) // Do a depth-first search of G starting at v
// pre: all vertices are marked as unvisited
count \leftarrow 0;
Create empty stack S; push v; mark v as visited; count++;
While S isn't empty
        current \leftarrow S.pop();
        for each unvisited neighbor u of current:
                 add u to S; mark u as visited; count++
return count;
```

Now compare value returned from DFS(G,v) to size of V

#### **DFS** Reflections

- The DFS algorithm traced out a tree different from that produced by BFS
  - It still consists of the edges connecting a visited vertex to (as yet) unvisited neighbors
- It is called a DFS tree of G with root v (or from v)
- Vertices are processed in pre-order w.r.t. the tree
- By manipulating the stack differently, we could produce a post-order version of DFS
- And perhaps write DFS recursively....

```
// Before first call to DFS, set all vertices to unvisited
//Then call DFS(G,v)

DFS(G, v)

Mark v as visited; count = 1;

for each unvisited neighbor u of v:

count += DFS(G,u);

return count;
```

Is it even clear that this method does what we want?!

Let's prove some facts about it....

Claim: DFS visits all vertices w reachable from v

- Proof: Induction on length d of shortest path from v to w
  - Base case: d = 0: Then  $v = w \checkmark$
  - Ind. Hyp.: Assume DFS visits all vertices w of distance at most d from v (for some d ≥ ●).
  - Ind. Step: Suppose now that w is distance d+l from v. Consider a path of length d+l from v to w and let u be the next-to-last vertex on the path

Claim: DFS visits all vertices w reachable from v

- Proof: Induction on length d of shortest path from v to w
  - The path is  $v = v_0, v_1, v_2, ..., v_d = u, v_{d+1} = w$ 
    - The edges are implied so not explicitly written!
  - By Ind. Hyp., u is visited. At this point, if w has not yet been visited, it will be one of the unvisited vertices on which DFS() is recursively called, so it will then be visited.

Claim: DFS visits only vertices reachable from v

Idea: Prove by induction on number of times
 DFS is called that DFS is only called on vertices
 w reachable from v

Claim: DFS counts correctly the number of vertices reachable from v

- Idea: Induction on number of unvisited vertices reachable from v
  - DFS will never be called on same vertex twice

Claim: DFS(G,v) returns the number of unvisited nodes reachable from v

Proof: Uses previous two observations

- DFS visits every node reachable from v
- DFS doesn't visit any node not reachable from v