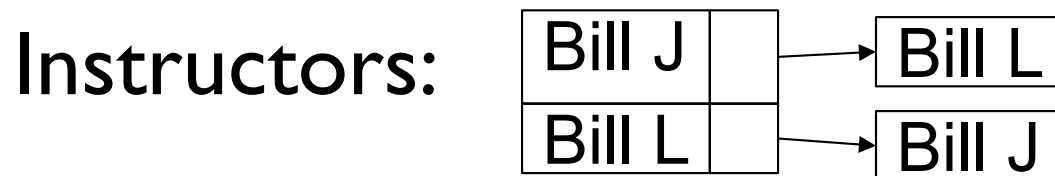


# CSCI 136

## Data Structures & Advanced Programming

Lecture 29

Fall 2017



# Last Time

- Graph Data Structures: Implementation
  - Graph Interface
  - Adjacency Array Implementation Basic Concepts
  - Adjacency List Implementation Basic Concepts

# Today's Outline

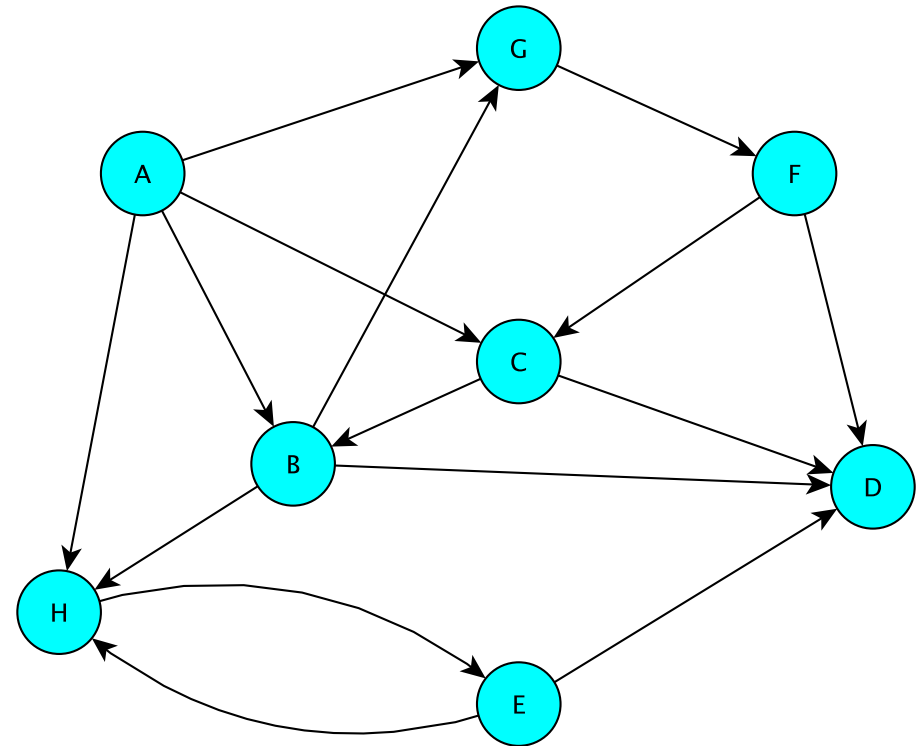
- Graph Data Structures: Implementation
  - Adjacency Array Implementation Details
  - Adjacency List Implementation Details
    - Featuring many Iterators!

# Representing Graphs

- Two standard approaches
  - Option 1: Array-based (directed and undirected)
  - Option 2: List-based (directed and undirected)
- We'll look at both
  - Array-based graphs store the edge information in a 2-dimensional array indexed by the vertices
  - List-based graphs store the edge information in a (1-dimensional) array of lists
    - The array is indexed by the vertices
    - Each array element is a list of edges incident with that vertex

# Adjacency Array: Directed Graph

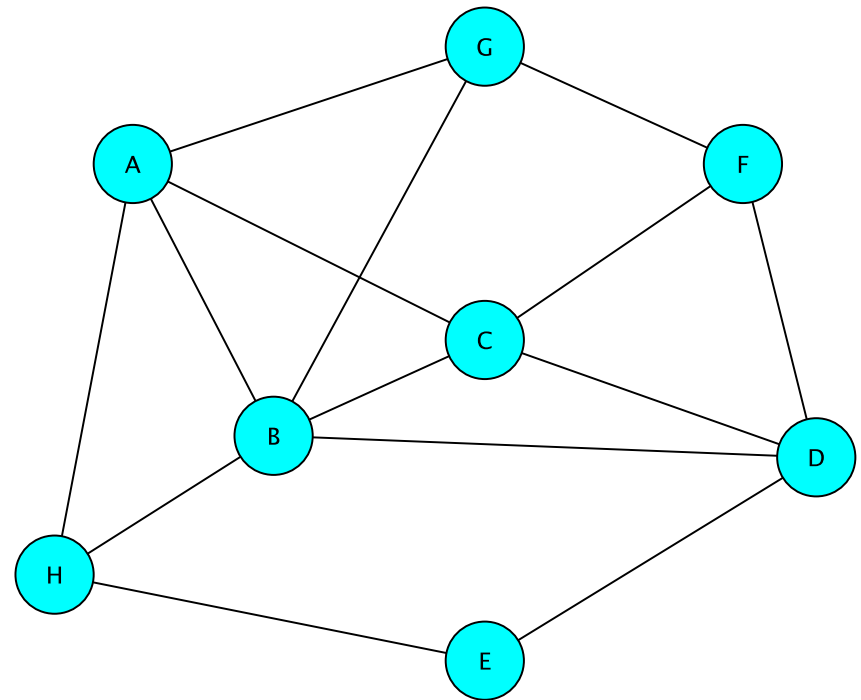
	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	0	0	0	1	0	0	1	1
C	0	1	0	1	0	0	0	0
D	0	0	0	0	0	0	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	0	0
G	0	0	0	0	0	1	0	0
H	0	0	0	0	1	0	0	0



Entry (i,j) stores 1 if there is an edge from i to j; 0 otherwise  
E.G.:  $\text{edges}(B,C) = 1$  but  $\text{edges}(C,B) = 0$

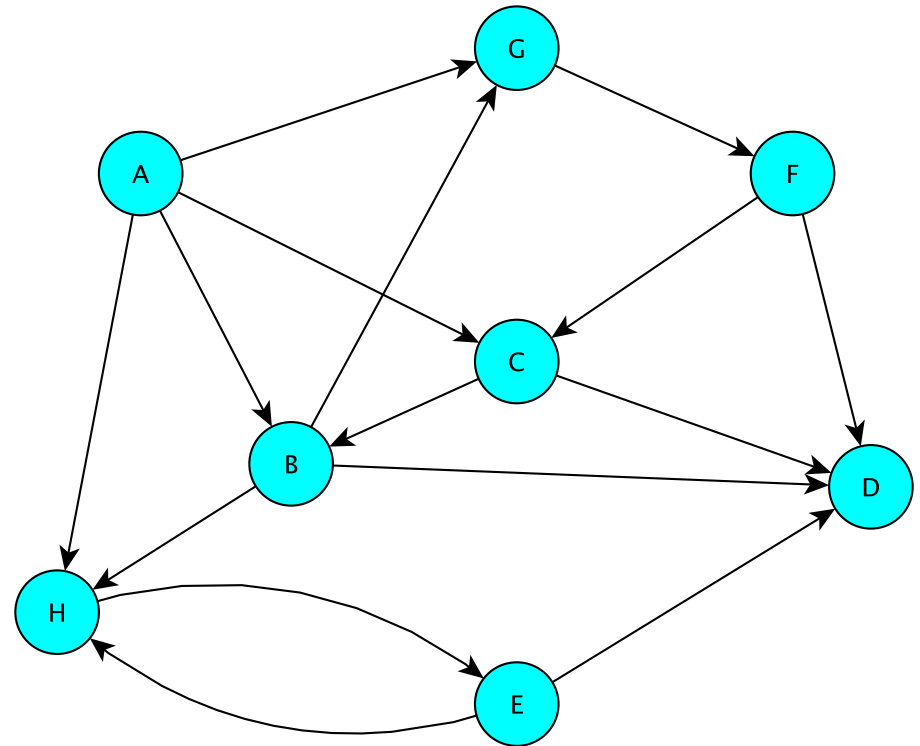
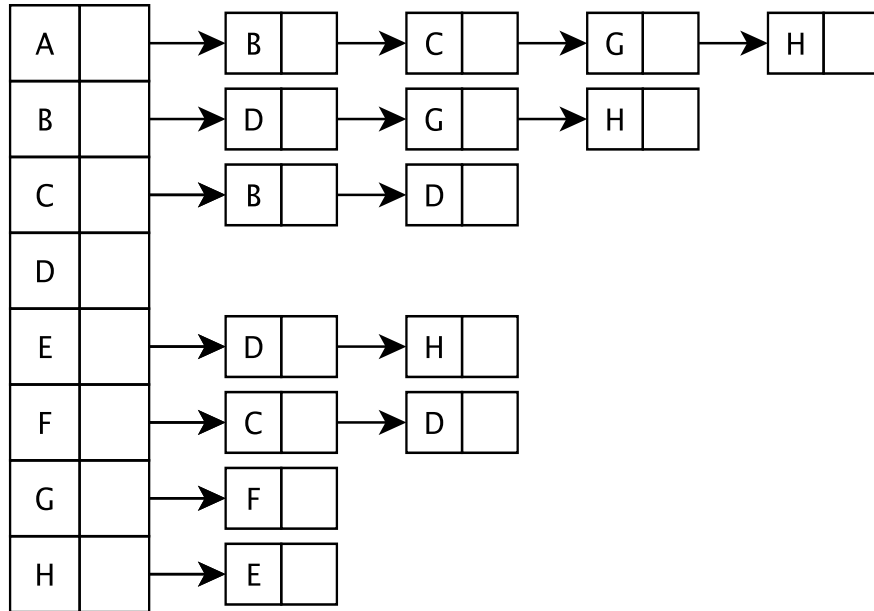
# Adjacency Array: Undirected Graph

	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	1	0	1	1	0	0	1	1
C	1	1	0	1	0	1	0	0
D	0	1	1	0	1	1	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	1	0
G	1	1	0	0	0	1	0	0
H	1	1	0	0	1	0	0	0



Entry (i,j) store 1 if there is an edge between i and j; else 0  
E.G.:  $\text{edges}(B,C) = 1 = \text{edges}(C,B)$

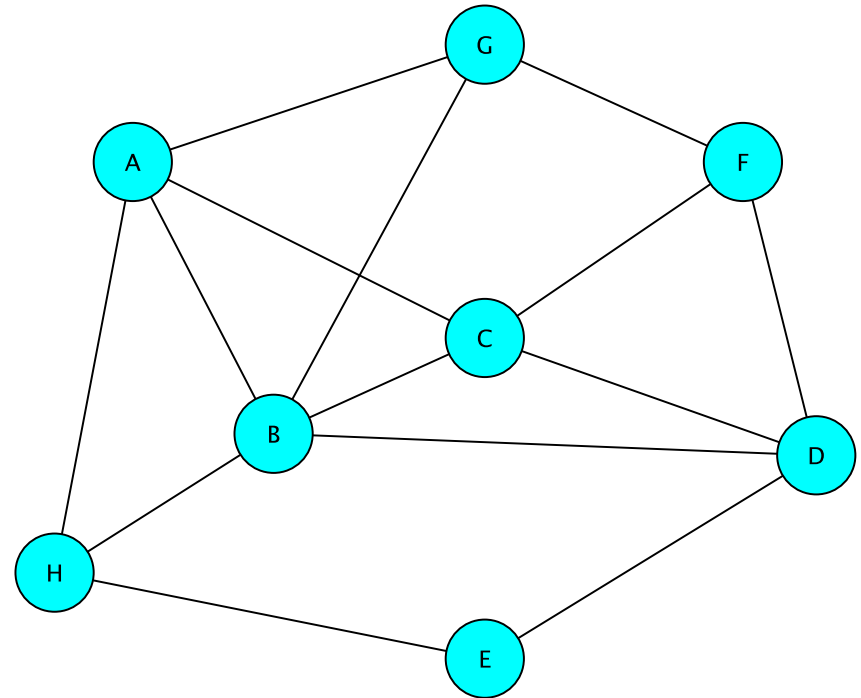
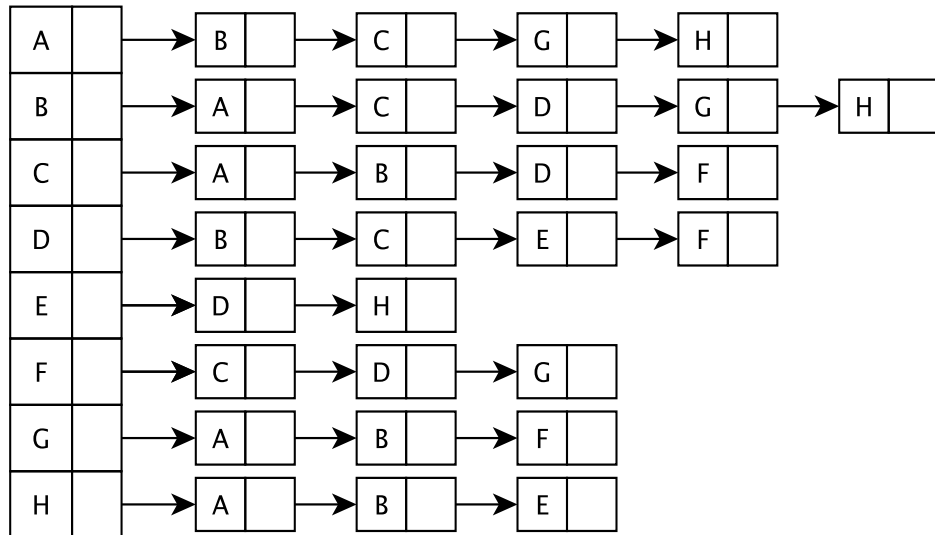
# Adjacency List : Directed Graph



The vertices are stored in an array  $V[]$

$V[]$  contains a linked list of edges having a given source

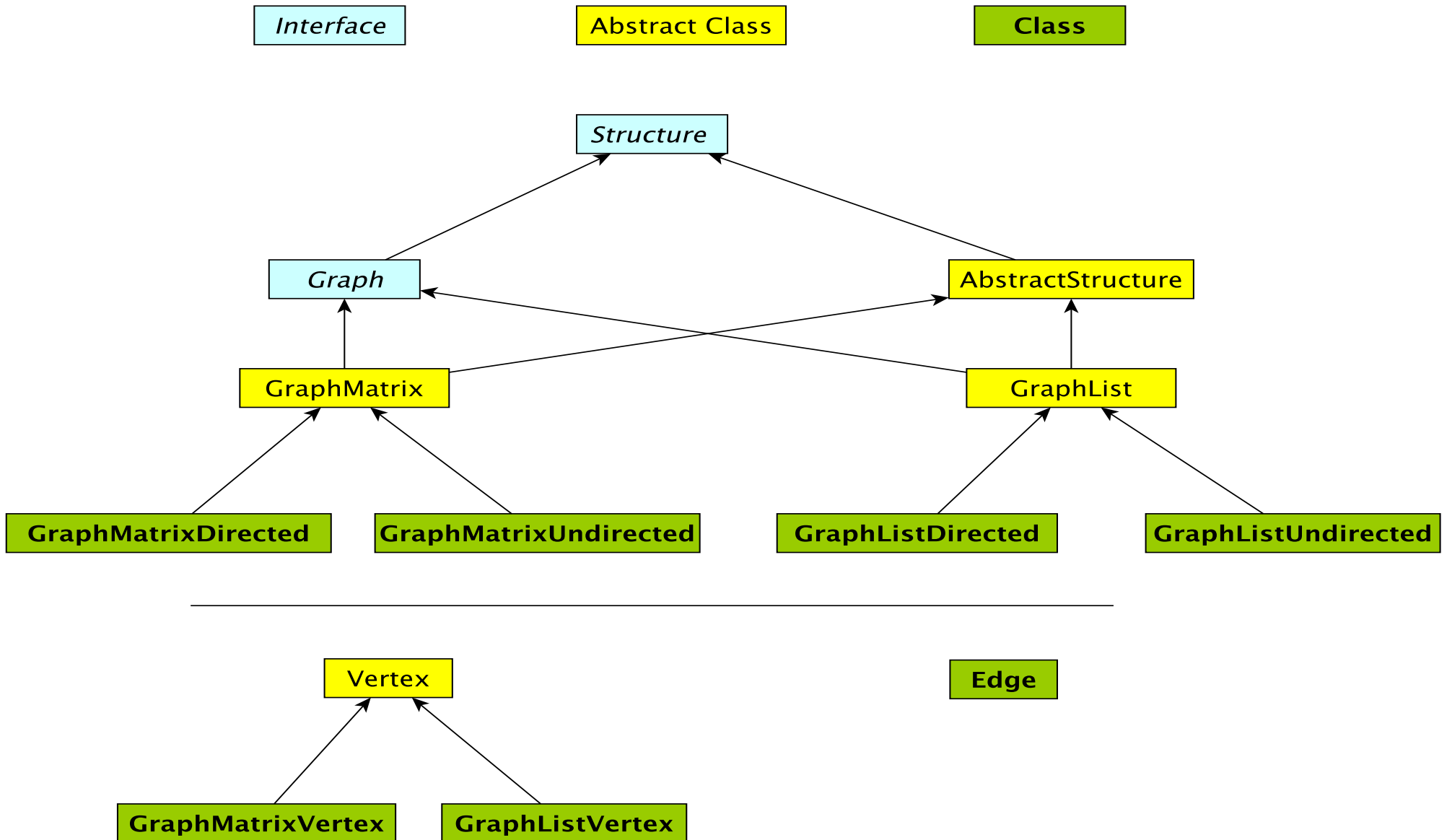
# Adjacency List : Undirected Graph



The vertices are stored in an array  $V[]$   
 $V[]$  contains a linked list of edges incident to a given vertex



# Graph Classes in structure5



# Graph Classes in structure5

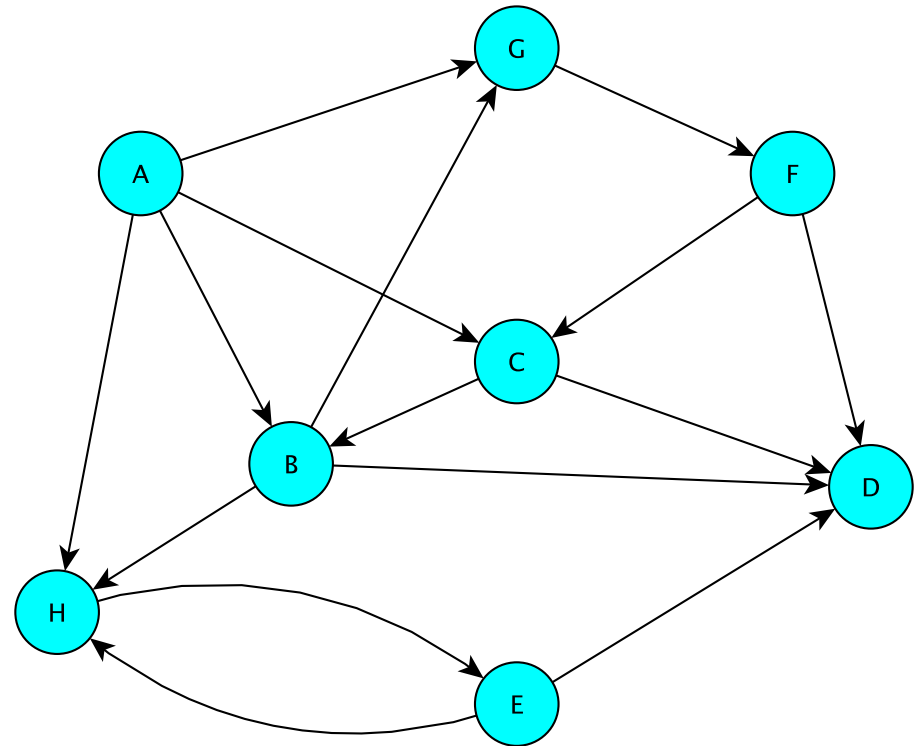
Why so many?!

- There are two types of graphs: undirected & directed
- There are two implementations: arrays and lists
- We want to be able to avoid large amounts of identical code in multiple classes
- We abstract out features of implementation common to both directed and undirected graphs

We'll tackle array-based graphs first....

# Adjacency Array: Directed Graph

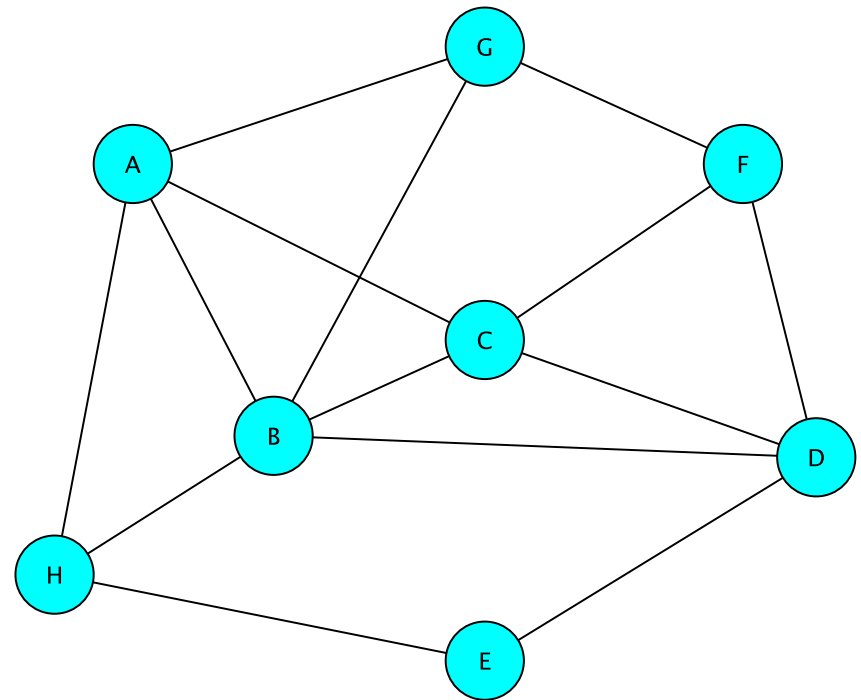
	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	0	0	0	1	0	0	1	1
C	0	1	0	1	0	0	0	0
D	0	0	0	0	0	0	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	0	0
G	0	0	0	0	0	1	0	0
H	0	0	0	0	1	0	0	0



Entry (i,j) stores 1 if there is an edge from i to j; 0 otherwise  
E.G.:  $\text{edges}(B,C) = 1$  but  $\text{edges}(C,B) = 0$

# Adjacency Array: Undirected Graph

	A	B	C	D	E	F	G	H
A	0	1	1	0	0	0	1	1
B	1	0	1	1	0	0	1	1
C	1	1	0	1	0	1	0	0
D	0	1	1	0	1	1	0	0
E	0	0	0	1	0	0	0	1
F	0	0	1	1	0	0	1	0
G	1	1	0	0	0	1	0	0
H	1	1	0	0	1	0	0	0



Entry (i,j) store 1 if there is an edge between i and j; else 0  
E.G.:  $\text{edges}(B,C) = 1 = \text{edges}(C,B)$

# Adjacency Array: Undirected Graph

Halving the Space (not in structure5)

	0	1	2	3	4	5	6
0	0	1	1	0	0	0	1
1	1	0	1	1	0	0	1
2	1	1	0	1	0	1	0
3	0	1	1	0	1	1	0
4	0	0	0	1	0	0	0
5	0	0	1	1	0	0	1
6	1	1	0	0	0	1	0

	0	1	2	3	4	5	6
0	0	1	1	0	0	0	1
1		0	1	1	0	0	1
2			0	1	0	1	0
3				0	1	1	0
4					0	0	0
5						0	1
6							0

0	1	2	3	4	5	6	7	8	9	...																		
0	1	1	0	0	0	1	0	1	1	0	0	1	0	1	0	1	0	0	1	1	0	0	0	0	0	0	1	0

$(i,j)$  maps to  $i*7+j$

# Vertex and GraphMatrixVertex

- We need to define a Vertex class
  - Unlike the Edge class, Vertex class **is not public**
  - Useful Vertex methods:  
`v label(), boolean visit(),  
boolean isVisited(), void reset()`
  - GraphMatrixVertex class adds one more useful attribute to Vertex class
    - Index of node (int) in adjacency matrix  
`int index()`
    - Why do we only need one int to represent index?
- In these slides, we write GMV for GraphMatrixVertex

# Choosing a Dictionary Structure

- We need a structure that will let us retrieve the index of a vertex given the vertex label (a dictionary)
- Many choices
  - Vector of associations:
    - `Vector<Association<V, GraphMatrixVertex<V>>>`
  - Ordered Vector of Associations
  - BinarySearchTree of Associations
- Problem: We don't want to allow multiple vertices with same label.... [Why?]
- We'll use the Map Interface [Chapter 15]
  - Maps require a unique key for each entry

# Digression : Map Interface

- Methods for Map<K, VAL>
  - int size() - returns number of entries in map
  - boolean isEmpty() - true iff there are no entries
  - boolean containsKey(K key) - true iff key exists in map
  - boolean containsValue(VAL val) - true iff val exists at least once in map
  - VAL get(K key) - get value associated with key
  - VAL put(K key, VAL val) - insert mapping from key to val, returns value replaced (old value) or null
  - VAL remove(K key) - remove mapping from key to val
  - void clear() - remove all entries from map
- We'll study this more in a week or so....



# Implementing the Matrix Model

- Abstract class – partially implements Graph

```
public abstract class GraphMatrix<V,E> implements Graph<V,E>
```

- This class will implement features common to directed and undirected graphs

- Instance variables

```
protected int size; //max size of matrix
protected Object data[][]; //matrix of edges
protected Map<V, GMV<V>> dict; //labels -> vertices
// This is structure5.Map, NOT java.util.Map!
protected List<Integer> freeList; //avail indices
protected boolean directed;
```

# GraphMatrix Constructor

(Yes, abstract classes can have constructors!)

```
protected GraphMatrix(int size, boolean dir) {
    this.size = size; // set maximum size
    directed = dir; // fix direction of edges

    // the following constructs a size x size matrix
    // (the "Objects" will be "Edges")
    // (can't use generics with arrays!)
    data = new Object[size][size];

    // label→index translation table
    dict = new Hashtable<V,GraphMatrixVertex<V>>(size);

    // put all indices in the free list
    freeList = new SinglyLinkedList<Integer>();
    for (int row = size-1; row >= 0; row--)
        freeList.add(new Integer(row));
}
```

# GraphMatrix add()

```
public void add(V label) {  
    // if there already, do nothing  
    if (dict.containsKey(label)) return;  
  
    Assert.pre(!freeList.isEmpty(), "Matrix not full");  
    // allocate a free row and column  
    int row = freeList.removeFirst().intValue();  
    // add vertex to dictionary  
    dict.put(label, new GraphMatrixVertex<V>(label, row));  
}
```

# GraphMatrix remove()

```
public V remove(V label) {
    // find and extract vertex
    GraphMatrixVertex<V> vert;
    vert = dict.remove(label);
    if (vert == null) return null;
    // remove vertex from matrix
    int index = vert.index();
    // clear row and column entries
    for (int row=0; row<size; row++) {
        data[row][index] = null;
        data[index][row] = null;
    }
    // add node index to free list
    freeList.add(new Integer(index));
    return vert.label();
}
```

# Neighbors Iterator : GraphMatrix

## neighbors Iterator

```
public Iterator<V> neighbors(V label) {
    GraphMatrixVertex<V> vert = dict.get(label);
    List<V> list = new SinglyLinkedList<V>();
    for (int row=size-1; row>=0; row--) {
        Edge<V,E> e = (Edge<V,E>)data[vert.index()][row];
        if (e != null)
            if (e.here().equals(vert.label()))
                list.add(e.there());
            else list.add(e.here());
    }
    return list.iterator();
}
```

# GraphMatrixDirected

- Completes the implementation of GraphMatrix to ensure graph is directed
- GraphMatrixUndirected is very similar...
- How do we implement GraphMatrixDirected?
  - We'll discuss some methods
  - Read Ch 16 for complete details...

# GraphMatrixDirected

- **Constructor**

```
public GraphMatrixDirected(int size) {  
    // pre: size > 0  
    // post: constructs an empty graph that may be  
    //        expanded to at most size vertices. Graph  
    //        is directed if dir true and undirected  
    //        otherwise  
  
    // call GraphMatrix constructor  
    super(size,true);  
}
```

# GraphMatrixDirected

- **addEdge**

```
// pre: vLabel1 and vLabel2 are labels of existing vertices
public void addEdge(V vLabel1, V vLabel2, E label) {
    GraphMatrixVertex<V> vtx1, vtx2;
    vtx1 = dict.get(vLabel1);
    vtx2 = dict.get(vLabel2);
    Edge<V,E> e = new Edge<V,E>(vtx1.label(), vtx2.label(),
                                label, true);
    data[vtx1.index()][vtx2.index()] = e;
}
```



# GraphMatrixDirected

- removeEdge

```
// pre: vLabel1 and vLabel2 are labels of existing vertices
public E removeEdge(V vLabel1, V vLabel2) {
    // get indices
    int row = dict.get(vLabel1).index();
    int col = dict.get(vLabel2).index();
    // cache old value
    Edge<V,E> e = (Edge<V,E>)data[row][col];
    // update matrix
    data[row][col] = null;
    if (e == null) return null;
    else return e.label(); // return old value
}
```

# GraphMatrix Efficiency

- Assume Map operations are  $O(1)$  (for now)
  - $|E|$  = number of edges
  - $|V|$  = number of vertices
- Runtime of add, addEdge, getEdge, removeEdge, remove?
- Space usage?
- Conclusions
  - Matrix is good for dense graphs
  - Have to commit to maximum # of vertices in advance

# Efficiency : Assuming Fast Map

	GraphMatrix
add	$O(1)$
addEdge	$O(1)$
getEdge	$O(1)$
removeEdge	$O(1)$
remove	$O( V )$
space	$O( V ^2)$