

# CSCI 136

## Data Structures & Advanced Programming

Lecture 24

Fall 2017

Instructor: Bills

# Administrative Details

- Lab 9 today!
- You can work with a partner
- Bring a design to lab
- You can deviate from our plan but you should try to take advantage of
  - Abstract base classes/inheritance
  - Data structures you've learned

# Last Time

- Heapsort
- Skew Heaps
- Binary search trees (Ch 14)
  - Overview
  - Definition
  - Some Applications

# Today's Outline

- Binary search trees (Ch 14)
  - The *locate* method
  - Further Implementation
  - Tree balancing to maintain small height
  - Partial taxonomy of balanced tree species

# Binary Search Trees

- Binary search trees maintain a *total* ordering among elements (assumes comparability)
- Definition: A BST  $T$  is either:
  - Empty
  - Has root  $r$  with subtrees  $T_L$  and  $T_R$  such that
    - All nodes in  $T_L$  have smaller value than  $r$
    - All nodes in  $T_R$  have larger value than  $r$
    - $T_L$  and  $T_R$  are also BSTs

# BST Observations

- The same data can be represented by many BST shapes
- Searching for a value in a BST takes time proportional to the height of the tree
  - Reminder: trees have height, nodes have depth
- Additions to a BST happen at nodes missing at least one child (*a constraint!*)
- Removing from a BST can involve *any* node

# BST Operations

- BSTs will implement the OrderedStructure Interface
  - `add(E item)`
  - `contains(E item)`
  - `get(E item)`
  - `remove(E item)`
  - Runtime of above operations?
    - All  $O(h)$  – where  $h$  is the tree height
  - `iterator()`
    - This will provide an in-order traversal

# BST Implementation

- The BST holds the following items
  - BinaryTree root: the root of the tree
  - BinaryTree EMPTY: a static empty BinaryTree
    - To use for all empty nodes of tree
  - int count: the number of nodes in the BST
  - Comparator<E> ordering: for comparing nodes
    - Note: E must implement Comparable
- Two constructors: One takes a Comparator



# BST Implementation: locate

- Several methods search the tree
  - add, remove, contains
- We factor out common code: locate method
- *protected* locate(BinaryTree<E> node, E v)
  - Returns a BinaryTree<E> n in the subtree with root node such that either
    - n has its value equal to v, or
    - v is not in this subtree and n is the node whose child v should be
- How would we implement locate()?

# BST Implementation: locate

*BinaryTree locate(BinaryTree root, E value)*

*if root's value equals value return root*

*child ← child of root that should hold value*

*if child is empty tree, return root*

*// value not in subtree based at root*

*else //keep looking*

*return locate(child, value)*

# BST Implementation: locate

- What about this line?  
*child* ← *child of root that should hold value*
- If the tree can have multiple nodes with same value, then we need to be careful
- Convention: During *add* operation, only move to right subtree if value to be added is *greater than* value at node
- We'll look at *add* later
- Let's look at *locate* now....

# The code : locate

```
protected BinaryTree<E> locate(BinaryTree<E> root, E value) {
    E rootValue = root.value();
    BinaryTree<E> child;

    // found at root: done
    if (rootValue.equals(value)) return root;

    // look left if less-than, right if greater-than
    if (ordering.compare(rootValue,value) < 0)
        child = root.right();
    else
        child = root.left();

    // no child there: not in tree, return this node,
    // else keep searching
    if (child.isEmpty()) return root;
    else
        return locate(child, value);
}
```

# Other core BST methods

- `locate(v)` returns either a node containing `v` or a node where `v` can be added as a child
- `locate()` is used by
  - `public boolean contains(E value)`
  - `public E get(E value)`
  - `public void add(E value)`
  - `Public void remove(E value)`
- Some of these also use another utility method
  - `protected BT predecessor(BT root)`
- Let's look at `contains()` first...

# Contains

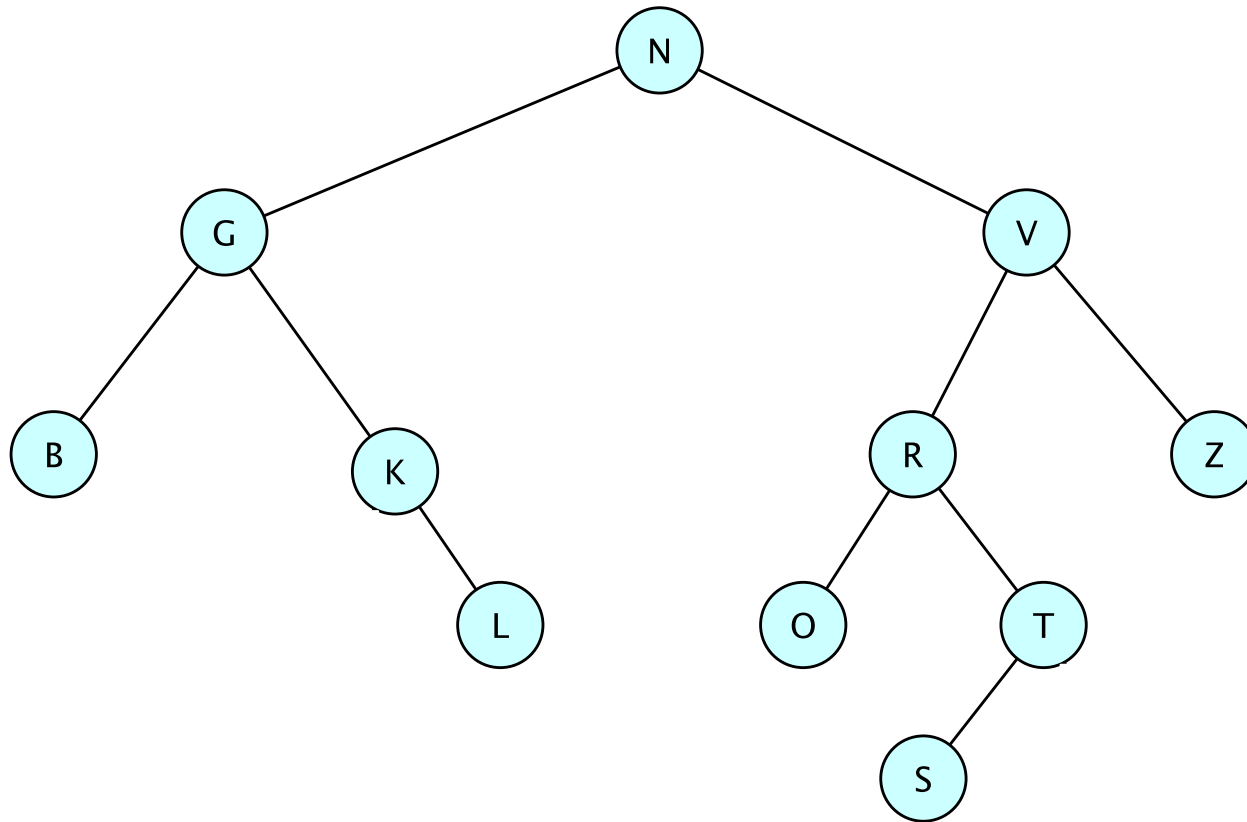
```
public boolean contains(E value){  
    if (root.isEmpty()) return false;  
  
    BinaryTree<E> possibleLocation = locate(root,value);  
  
    return value.equals(possibleLocation.value());  
}
```

# First (Bad) Attempt: add(E value)

```
public void add(E value) {
    BinaryTree<E> newNode = new BinaryTree<E>(value,EMPTY,EMPTY);
    if (root.isEmpty()) root = newNode;
    else {
        BinaryTree<E> insertLocation = locate(root,value);
        E nodeValue = insertLocation.value();
        if (ordering.compare(nodeValue,value) < 0)
            insertLocation.setRight(newNode);
        else
            insertLocation.setLeft(newNode);
    }
    count++;
}
```

Problem: If repeated values are allowed, left subtree might not be empty when setLeft is called

# Add: Repeated Nodes



Where would a new K be added?  
A new V?



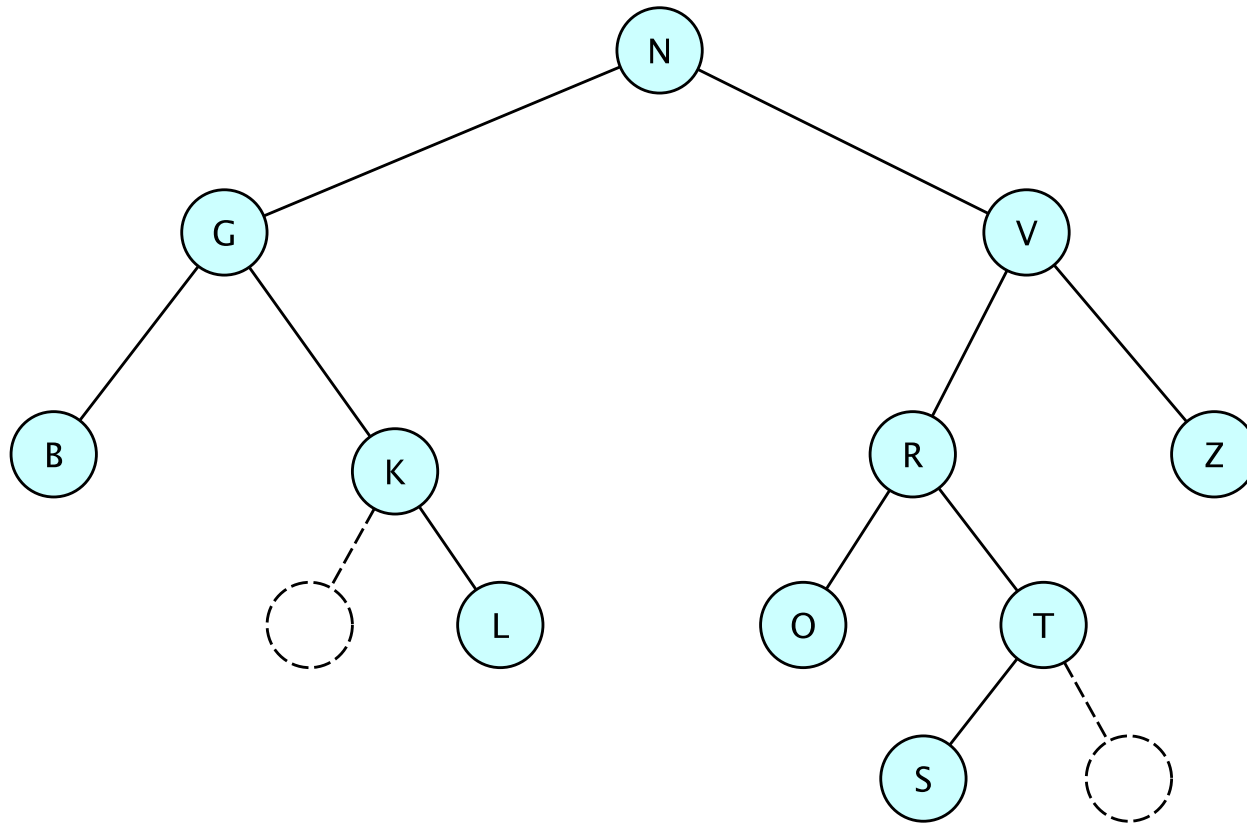
# Add Duplicate to Predecessor

- If insertLocation has a left child then
  - Find insertLocation's predecessor
  - Add repeated node as right child of predecessor
  - Predecessor will be in insertLocation's left sub-tree
    - Do you believe me?

# Corrected Version: add(E value)

```
BinaryTree<E> newNode = new BinaryTree<E>(value,EMPTY,EMPTY);
if (root.isEmpty()) root = newNode;
else {
    BinaryTree<E> insertLocation = locate(root,value);
    E nodeValue = insertLocation.value();
    if (ordering.compare(nodeValue,value) < 0)
        insertLocation.setRight(newNode);
    else
        if (insertLocation.left().isEmpty())
            insertLocation.setLeft(newNode);
        else
            // if value is in tree, we insert just before
            predecessor(insertLocation).setRight(newNode);
}
count++;
```

# How to Find Predecessor



Where would a new K be added?  
A new V?

# Predecessor

```
protected BinaryTree<E> predecessor(BinaryTree<E> root) {
    Assert.pre(!root.isEmpty(), "Root has predecessor");
    Assert.pre(!root.left().isEmpty(), "Root has left child.");

    BinaryTree<E> result = root.left();

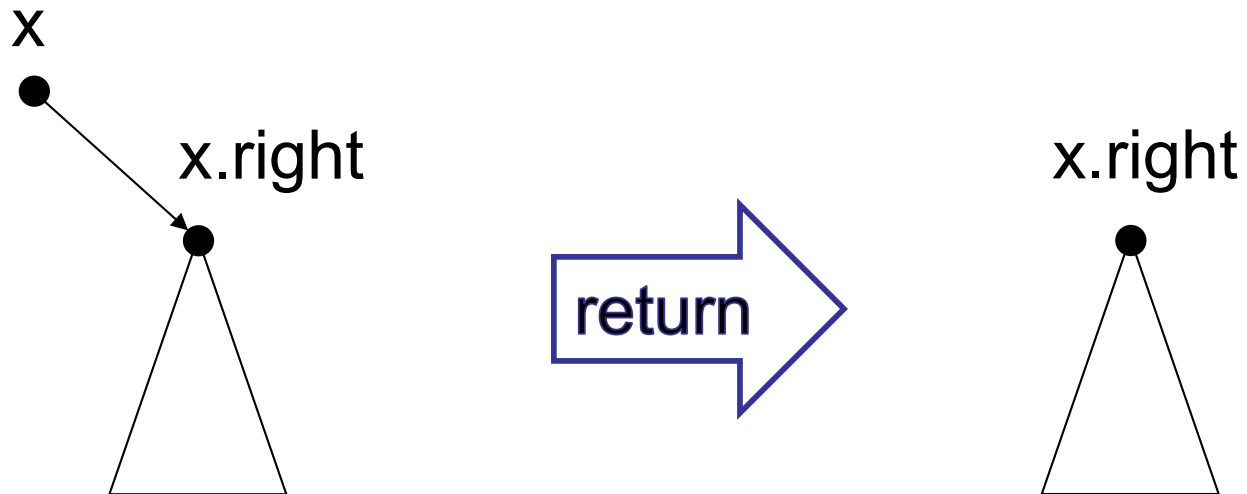
    while (!result.right().isEmpty())
        result = result.right();

    return result;
}
```

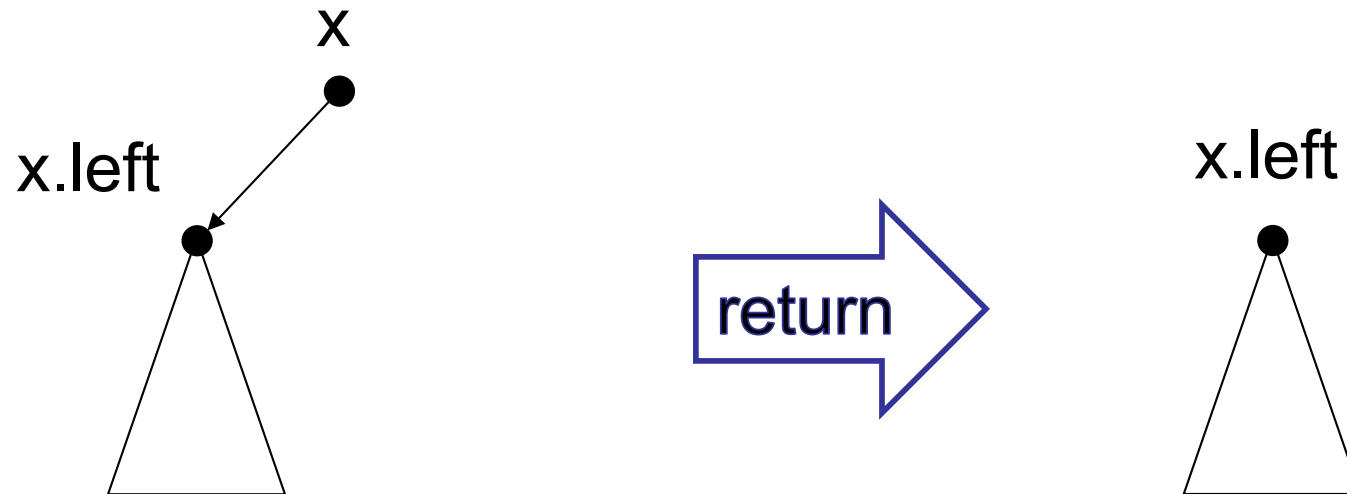
# Removal

- Removing the root is a (not so) special case
- Let's figure that out first
  - If we can remove the root, we can remove any element in a BST in the same way
    - Do you believe me?
- We need to implement:
  - `public E remove(E item)`
  - `protected BT removeTop(BT top)`

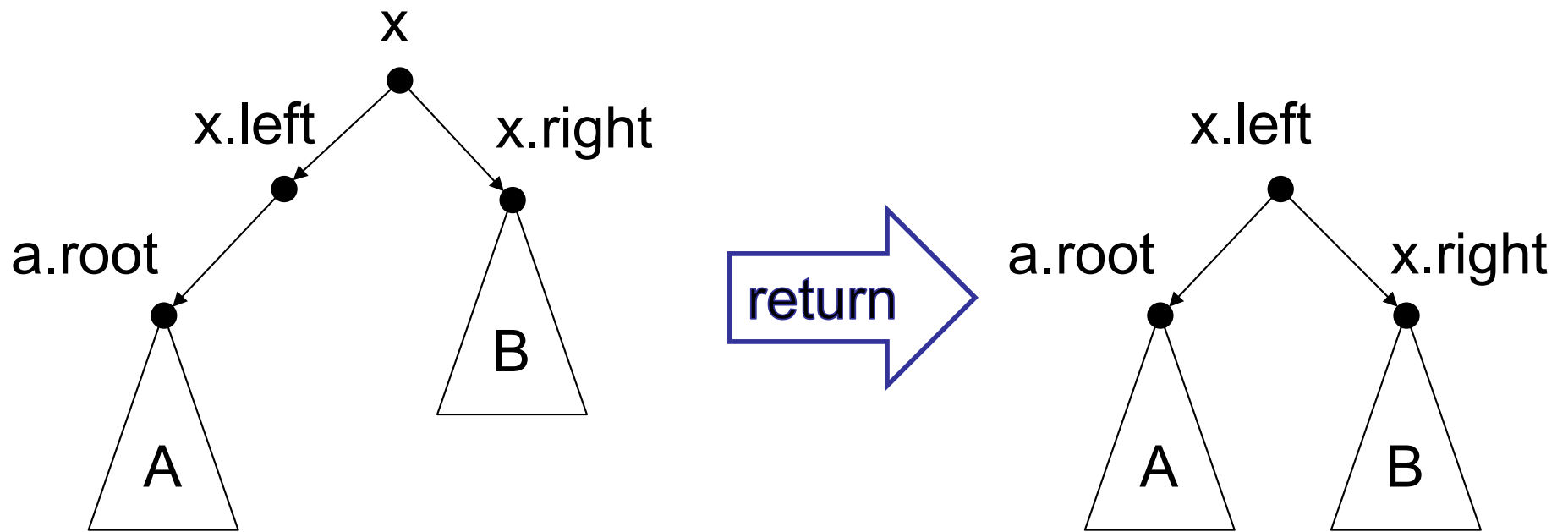
# Case I: No left binary tree



# Case 2: No right binary tree



# Case 3: Left has no right subtree

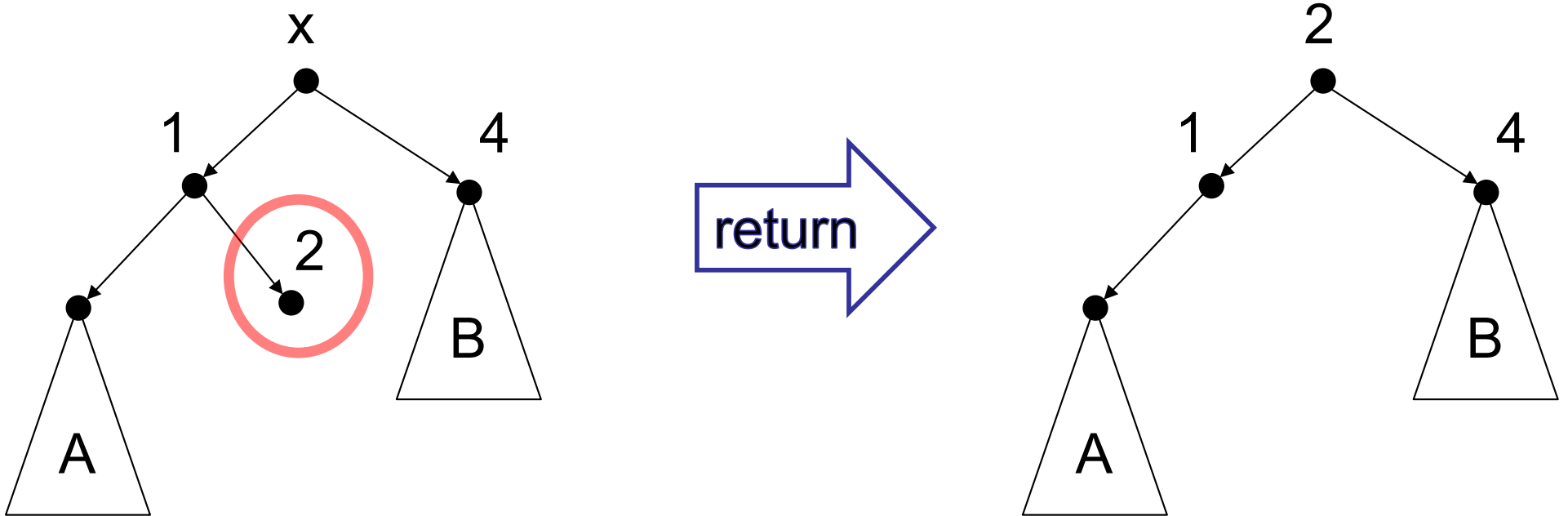




# Case 4: General Case (HARD!)

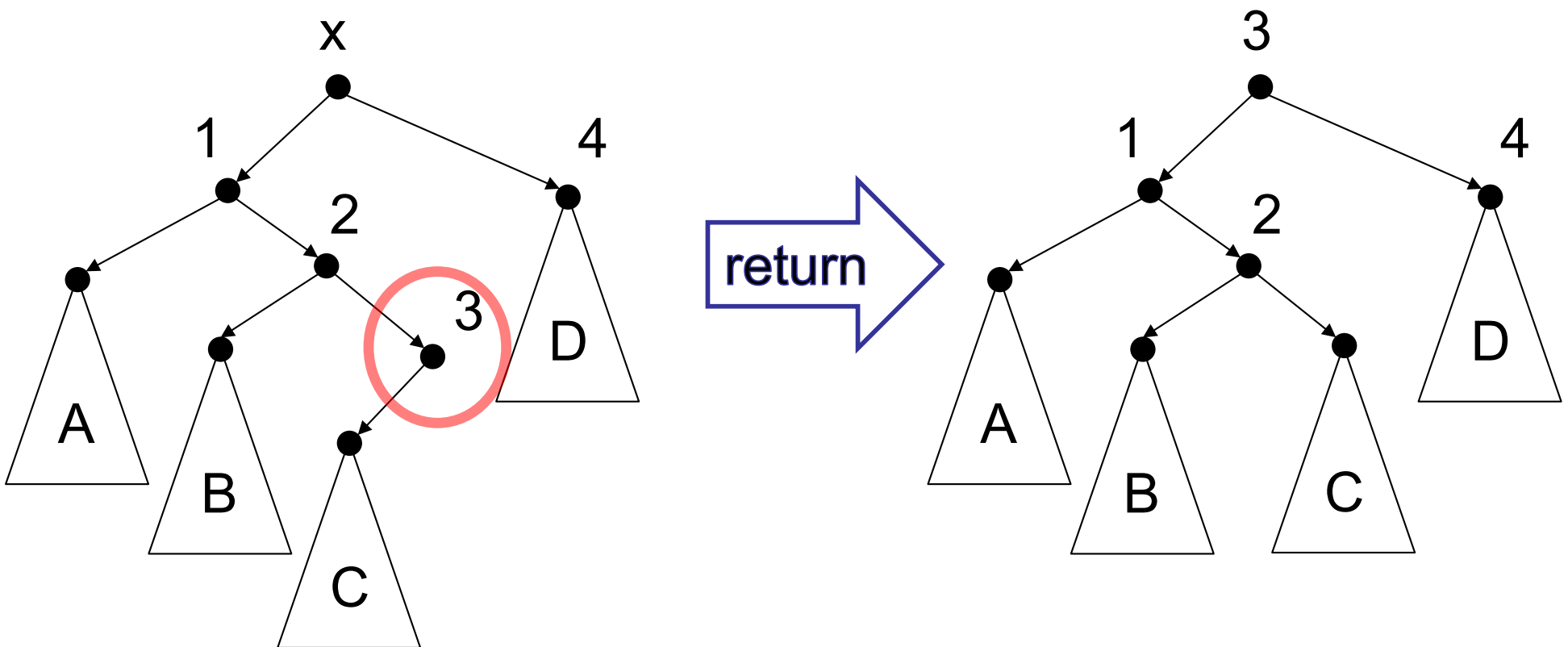
- Consider BST requirements:
  - Left subtree must be  $\leq$  root
  - Right subtree must be  $>$  root
- Strategy: replace the root with the largest value that is less than or equal to it
  - predecessor(root) : rightmost left descendant
- This may require reattaching the predecessor's left subtree!

# Case 4: General Case (HARD!)



Replace root with predecessor(root),  
then patch up the remaining tree

# Case 4: General Case (HARD!)



Replace root with predecessor(root),  
then patch up the remaining tree

# RemoveTop(topNode)

*Detach left and right sub-trees from root (i.e. topNode)*

*If either left or right is empty, **return** the other one*

*If left has no right child*

*make right the right child of left then **return** left*

*Otherwise find largest node C in left*

*// C is the right child of its own parent P*

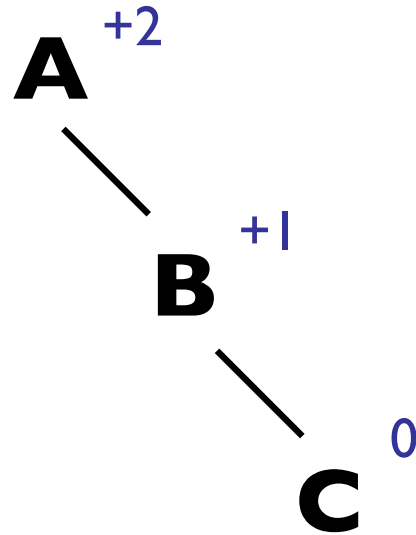
*// C is the predecessor of right (ignoring topNode)*

*Detach C from P; make C's left child the right child of P*

*Make C new root with left and right as its sub-trees*

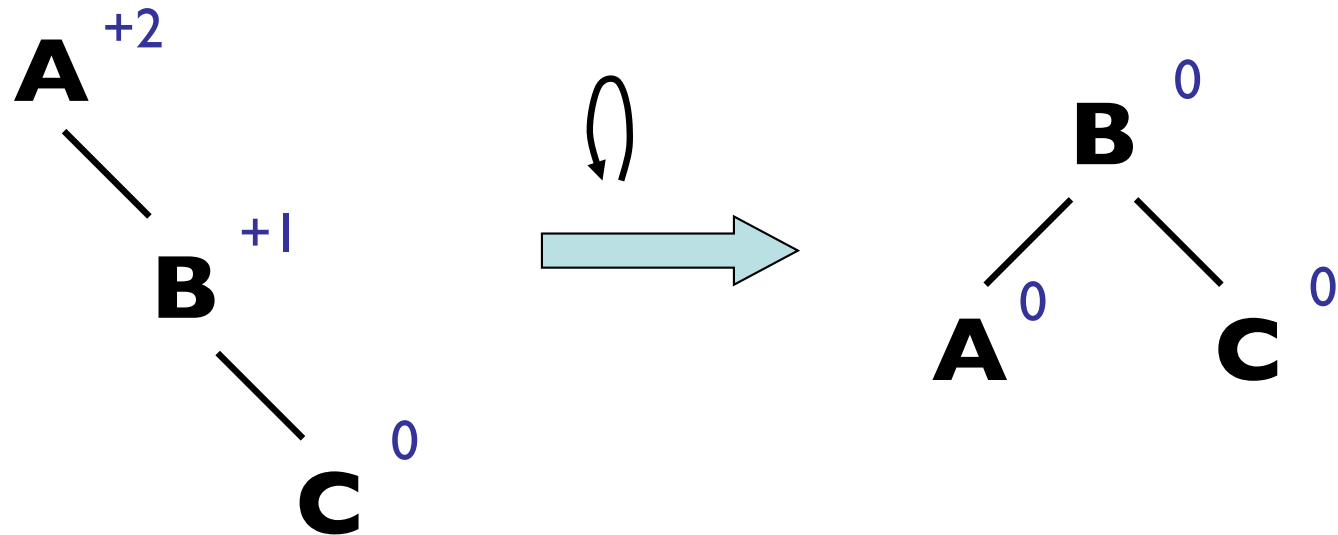
# But What About Height?

- Can we design a binary search tree that is always “shallow”?
- Yes! In many ways. Here’s one
- AVL trees
  - Named after its two inventors, G.M. Adelson-Velsky and E.M. Landis, who published a paper about AVL trees in 1962 called "An algorithm for the organization of information"



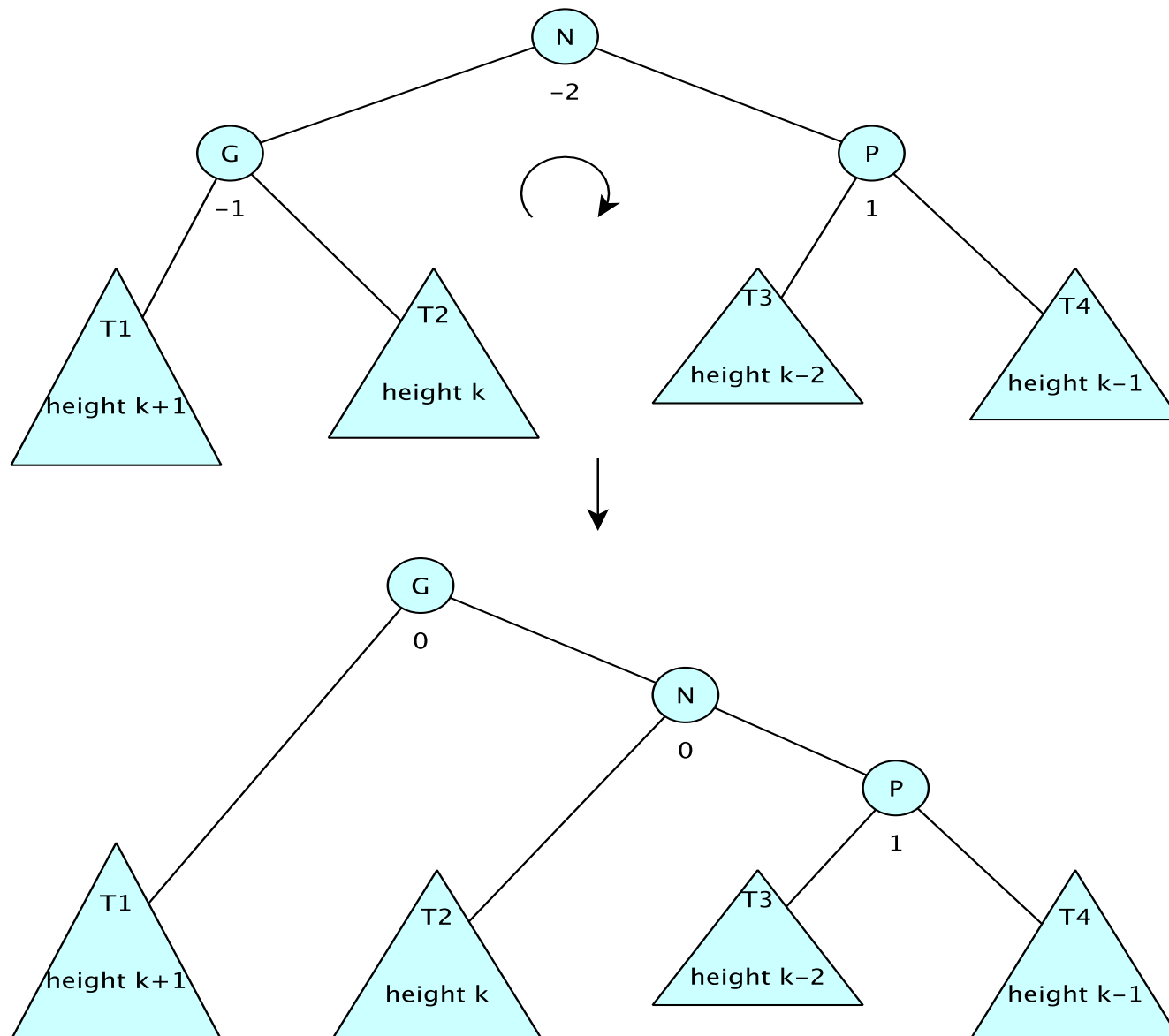
- The *balance factor* of a node is the height of its right subtree minus the height of its left subtree. A node with balance factor 1, 0, or -1 is considered *balanced*.
- A node with any other balance factor is considered *unbalanced* and requires rebalancing the tree.

# Single Rotation



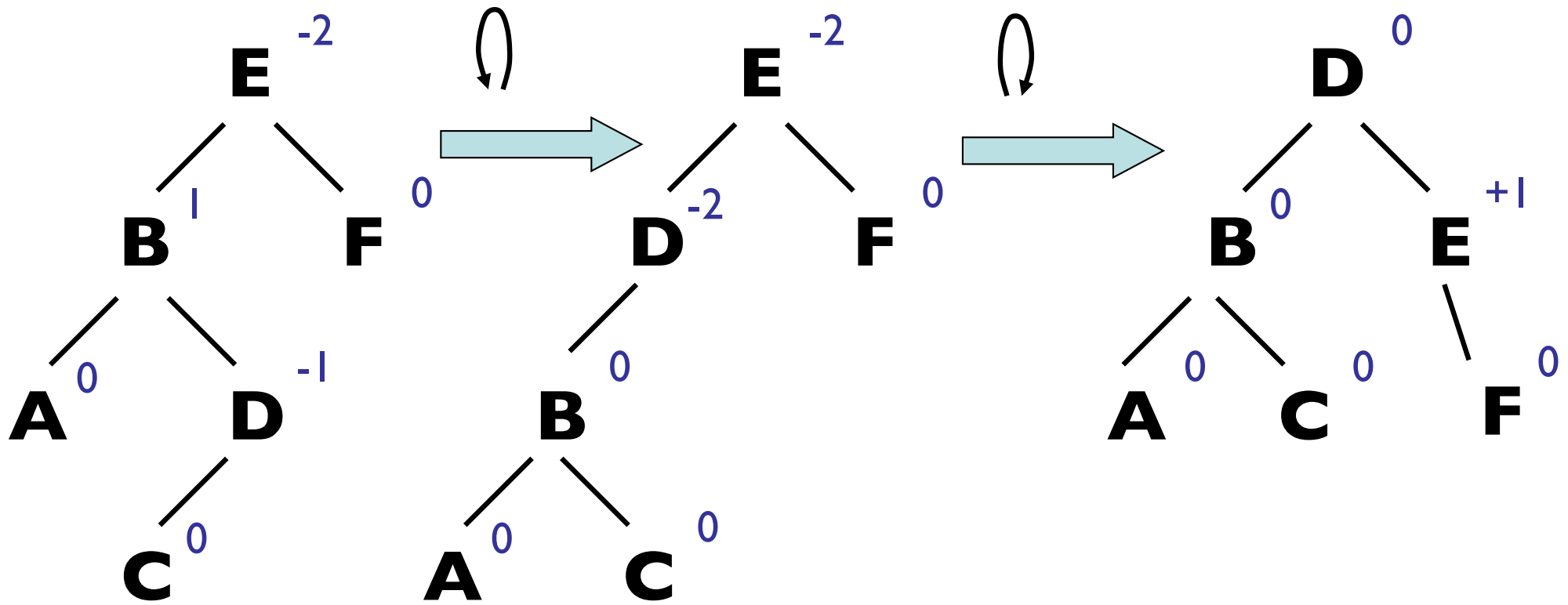
Unbalanced trees can be rotated to achieve balance.

# Single Right Rotation





# Double Rotation



# AVL Tree Facts

- A tree that is AVL except at root, where root balance factor equals  $\pm 2$  can be rebalanced with at most 2 rotations
- $\text{add}(v)$  requires at most  $O(\log n)$  balance factor changes and one (single or double) rotation to restore AVL structure
- $\text{remove}(v)$  requires at most  $O(\log n)$  balance factor changes and (single or double) rotations to restore AVL structure

# AVL Trees: One of Many

- There are many strategies for tree balancing to preserve  $O(\log n)$  height, including
- AVL Trees: guaranteed  $O(\log n)$  height
- Red-black trees: guaranteed  $O(\log n)$  height
- B-trees (not binary): guaranteed  $O(\log n)$  height
  - 2-3 trees, 2-3-4 trees, red-black 2-3-4 trees, ...
- Splay trees: *Amortized*  $O(\log n)$  time operations
- Randomized trees:  $O(\log n)$  expected height