

CSCI 136
Data Structures &
Advanced Programming

Lecture 23

Fall 2017

Instructor: Bills

Administrative Details

- Lab 9: Simulations
 - You will simulate two queuing strategies
 - You can work with a partner
 - Time spent on lab before Wed. is time well-spent!

Last Time

- Finishing up with heaps
 - More on implementation
 - “Heapifying” constructor for VectorHeap
 - Alternate heapify approach

Today

- Finishing up with heaps
 - HeapSort
 - Alternative Heap Structures
- Binary Search Tree: A New Ordered Structure
 - Definitions
 - Implementation

Heapifying A Vector (or array)

- Method I: Top-Down
 - Assume $V[0..k]$ satisfies the heap property
 - Now call percolate on item in location $k+1$
 - Then $V[0..k+1]$ satisfies the heap property
- Method II: Bottom-up
 - Assume $V[k..n]$ satisfies the heap property
 - Now call pushDown on item in location $k-1$
 - Then $V[k-1..n]$ satisfies heap property
- Check out the demos at visualgo.net

Top-Down vs Bottom-Up

- Top-down heapify: elements at depth d may be swapped d times: Total # of swaps is at most

$$\sum_{d=1}^h d2^d = (h - 1)2^{h+1} = (\log n - 1)2n + 2$$

- This is $O(n \log n)$
- Some intuition: most of the elements are in the lowest levels of the tree, so each of them might have to move to root: $O(\log n)$ swaps per element

Top-Down vs Bottom-Up

- Bottom-up heapify: elements at depth d may be swapped $h-d$ times: Total # of swaps is at most

$$\sum_{d=1}^h (h-d)2^d = 2^{h+1} - h - 2 = 2n - \log n + 2$$

- This is $O(n)$ --- beats top-down!
- Some intuition: most of the elements are in the lowest levels of the tree, so each of them will only be pushed down (swapped) a small number of times **SO COOL!!!**

Some Sums

$$\sum_{d=0}^{d=k} 2^d = 2^{k+1} - 1$$

All of these can be proven by (weak) induction.

$$\sum_{d=0}^{d=k} r^d = (r^{k+1} - 1) / (r - 1)$$

Try these to hone your skills

$$\sum_{d=1}^{d=k} d * 2^d = (k - 1) * 2^{k+1} + 2$$

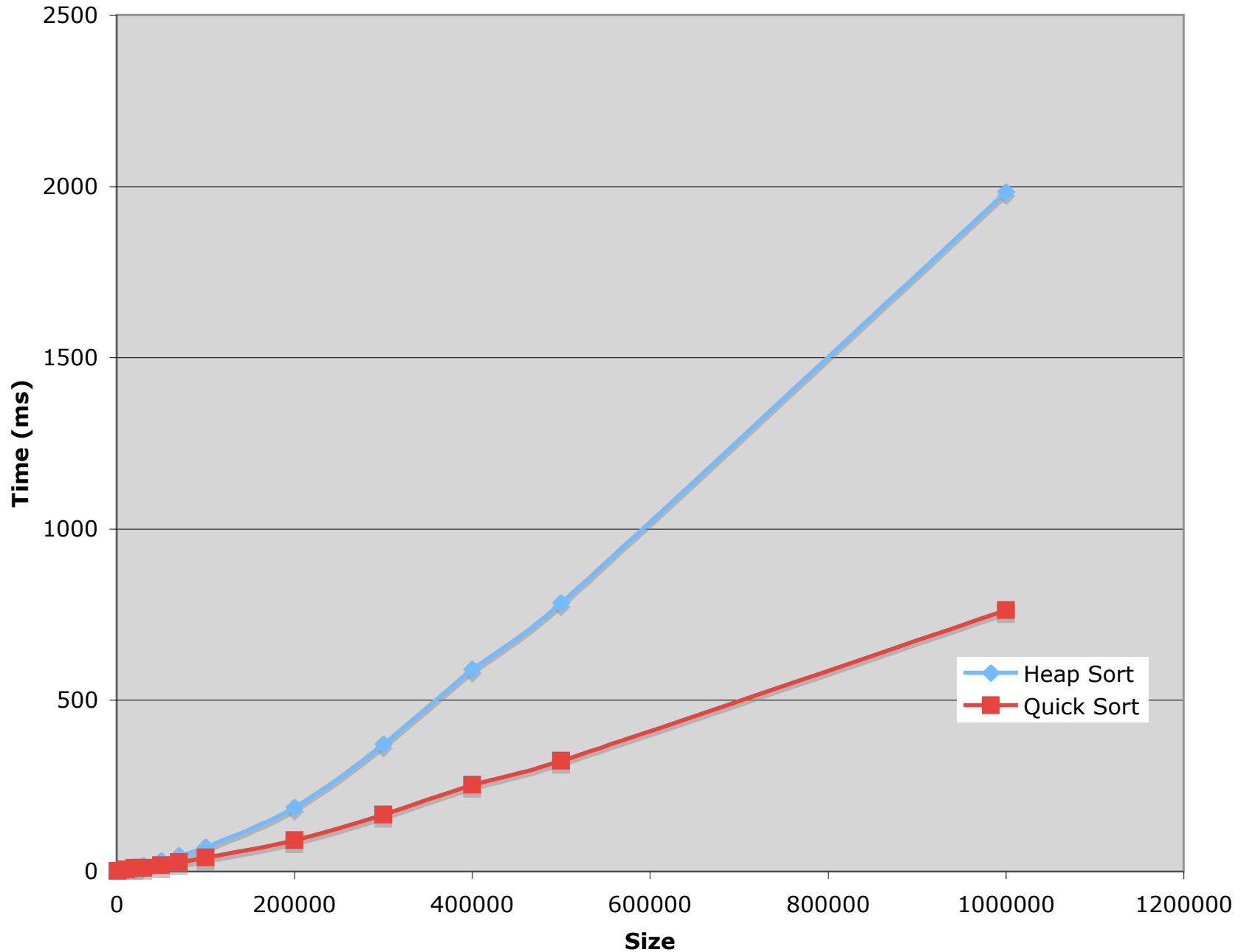
The second sum is called a geometric series. It works for any $r \neq 0$

$$\sum_{d=1}^{d=k} (k - d) * 2^d = 2^{k+1} - k - 2$$

HeapSort

- Heaps yield another $O(n \log n)$ sort method
- To HeapSort a Vector “in place”
 - Perform bottom-up heapify on the reverse ordering: that is: highest rank/lowest priority elements are near the root (low end of Vector)
 - Now repeatedly remove elements to fill in Vector from tail to head
 - For(`int i = v.size() - 1; i > 0; i--`)
 - RemoveMin from `v[0..i]` // `v[i]` is now not in heap
 - Put removed value in location `v[i]`

Heap Sort vs QuickSort



Why Heapsort?

- Heapsort is slower than Quicksort in general
- Any benefits to heapsort?
 - *Guaranteed* $O(n \log n)$ runtime
- Works well on mostly sorted data, unlike quicksort
- Good for incremental sorting

More on Heaps

- Set-up: We want to build a *large* heap. We have several processors available.
- We'd like to use them to build smaller heaps and then merge them together
- Suppose we can share the array holding the elements among the processors.
 - How long to merge two heaps?
 - How complicated is it?
- What if we use BinaryTrees for our heaps?

Mergeable Heaps

- We now want to support the additional *destructive* operation `merge(heap1, heap2)`
- Basic idea: heap with larger root somehow points into heap with smaller root
- Challenges
 - Points how? Where?
 - How much reheapifying is needed
 - How deep do trees get after many merges?

Skew Heap

- Don't force heaps to be complete BTs?
- Develop recursive merge algorithm that keeps tree shallow over time
- Theorem: Any set of m SkewHeap operations can be performed in $O(m \log n)$ time, where n is the total number of items in the SkewHeaps
- Let's sketch out merge operation....

Skew Heap: Merge Pseudocode

SkewHeap merge(SkewHeap S, SkewHeap T)
if either S or T is empty, return the other
if $T.minValue < S.minValue$
swap S and T (S now has minValue)
if S has no left subtree, T becomes its left subtree
else
let temp point to right subtree of S
left subtree of S becomes right subtree of S
merge(temp, T) becomes left subtree of S
return S

Tree Summary

- Trees
 - Express hierarchical relationships
 - Level ordering captures the relationship
 - i.e., ancestry, game boards, decisions, etc.
- Heap
 - Partially ordered tree based on item priority
 - Node invariants: parent has higher priority than each child
 - Provides efficient PriorityQueue implementation

Improving on OrderedVector

- The OrderedVector class provides $O(\log n)$ time searching for a group of n comparable objects
 - `add()` and `remove()`, though, take $O(n)$ time in the worst case---and on average!
- Can we improve on those running times without sacrificing the $O(\log n)$ search time?
- Let's find out....

Binary Trees and Orders

- Binary trees impose multiple orderings on their elements (pre-/in-/post-/level-orders)
- In particular, in-order traversal suggests a natural way to hold comparable items
 - For each node v in tree
 - All values in left subtree of v are $\leq v$
 - All values in right subtree of v are $\geq v$
- This leads us to...

Binary Search Trees

- Binary search trees maintain a *total* ordering among elements
- Definition: A BST T is either:
 - Empty
 - Has root r with subtrees T_L and T_R such that
 - All nodes in T_L have smaller value than r
 - All nodes in T_R have larger value than r
 - T_L and T_R are also BSTs
- Examples

BST Observations

- The same data can be represented by many BST shapes
- Searching for a value in a BST takes time proportional to the height of the tree
 - Reminder: trees have height, nodes have depth
- Additions to a BST happen at nodes missing at least one child (*a constraint!*)
- Removing from a BST can involve *any* node

BST Operations

- BSTs will implement the `OrderedStructure` Interface
 - `add(E item)`
 - `contains(E item)`
 - `get(E item)`
 - `remove(E item)`
 - `iterator()`
 - This will provide an in-order traversal
- Runtime of `add`, `contains`, `get`, `remove`: $O(\text{height})$
- Goal: Keep the height to $O(\log n)$
 - Duane's `BinarySearchTree` class doesn't achieve this...
 - But his `RedBlackSearchTree` does!

Application: Dictionary

- Create a BST of ComparableAssociations
 - Order BST by key
 - Two objects are equal if keys are equal
- Example: Symbol tables (PostScript lab) are Dictionaries
 - But would only use a BST if the set of possible symbols was very large

Application: Tree Sort

- Can we sort data using a BST?
 - Yes!
- Runtime?
 - To build a tree with n elements, we do n insertions: $O(n \cdot h)$, where h is the maximum height attained by the tree
 - In order traversal: $O(n)$
 - Total runtime: $O(n \cdot h)$