

# Squashing the Bugs: Tools for Building Better Software

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Williams College



```

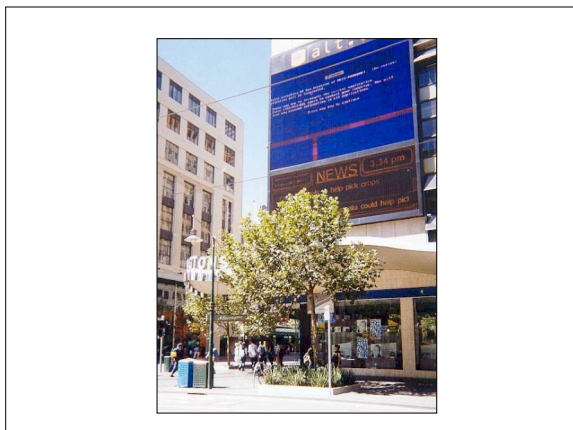
www STOP: 0x00000019 (0x00000000,0xC0000000,0xFFFFFD4,0xC0000000)
MRD_POOL_HEADER
CPUID:GenuineIntel 5.2.c irq:1:1f SYSOER 0x00000065

Dll Base DateStamp Name
01000000 320207e - ntoskrnl.exe 80010000 31e6e52 - hal.dll
00010000 31e6e52 - atapi.sys 80010000 31e6e74 - SCSIPORT.SYS
020c0000 31e486bf - aic78x.sys 80200000 31e42579 - Disk.sys
02010000 31e6e74 - aic78x.sys 80200000 31e6d4a7 - NIFS.sys
0c980000 31e6e74 - Floppy.SYS fc6a0000 31e6d4a7 - Cdrom.SYS
0c9a0000 31e6e74 - Floppy.SYS fc9c0000 31e6e39 - Mail.SYS
0c9b0000 31e4868b - KS.MDF.SYS fc9c0000 31e6e39 - Mail.SYS
0c680000 31e6e90 - I8042prt.sys fc860000 31e6e39 - mouclass.sys
0c740000 31e6e94 - mbc1ass.sys fc860000 31e6e39 - VIDEOPOST.SYS
0c770000 31e6e62 - mpa_nll.sys fc860000 31e6e62 - vga.sys
0c780000 31e6e62 - mpa_nll.sys fc860000 31e6e62 - NIFS.SYS
0c790000 31e4262 - NDIS.SYS a0000000 31f954f7 - win32k.sys
0c7a0000 31f1a71 - mpa.dll fc810000 31e6d407 - Fastfat.SYS
0c7b0000 31e6e6c - TDI.SYS feaf0000 31e69754 - nbf.sys
0c7c0000 31f13077 - tcpip.sys feaf0000 31e69754 - nbf.sys
0c7d0000 31e6e6c - c139x.sys fc560000 31f8f864 - ftd.sys
0c7e0000 31e6e7a - netbios.sys fc560000 31e6e99 - Faxport.SYS
0c7f0000 31e6e9b - Parallel.SYS fc950000 31e6e91 - FaxOdm.SYS
0c800000 31e6e91 - Serial.SYS fc8c0000 31f90820 - rdx.sys
0c810000 31f71ba - mup.sys fe9da000 32031abe - srv.sys

Address dump Build [1381] - Name
fc920004 00153000 00153000 00153000 ffd00000 00070b02 - KeccDD.SYS
010471c0 00144000 00144000 ffd00000 c0300000 00000001 - ntoskrnl.exe
010471c0 00122000 00003f00 ffd00000 e133c000 e133c000 - ntoskrnl.exe
01047304 00030230 0000023c 00000034 00000000 00000000 - ntoskrnl.exe

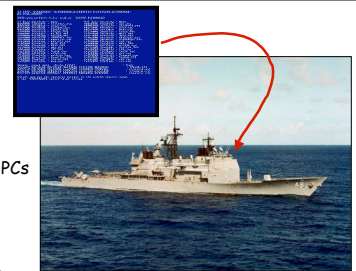
Restart and set the recovery options in the system control panel
or the /CRASHDEBUG system start option.
    
```

## The Blue Screen of Death (BSOD)

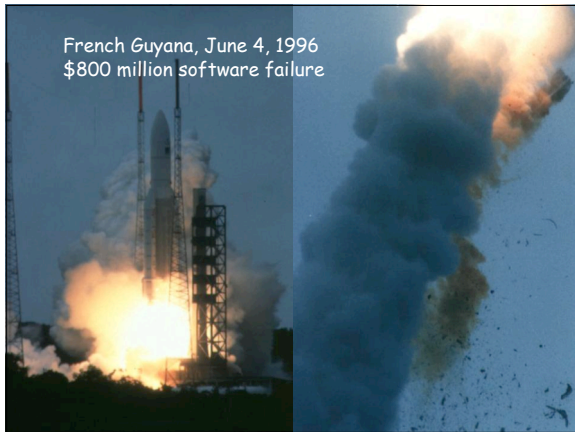


## USS Yorktown

- Smart Ship
  - 27 Pentium-based PCs
  - Windows NT 4.0
- September 21, 1997:
  - data entry error caused a "Divide-By-0" error
  - entire system failed
  - ship dead in the water for over 2 hours

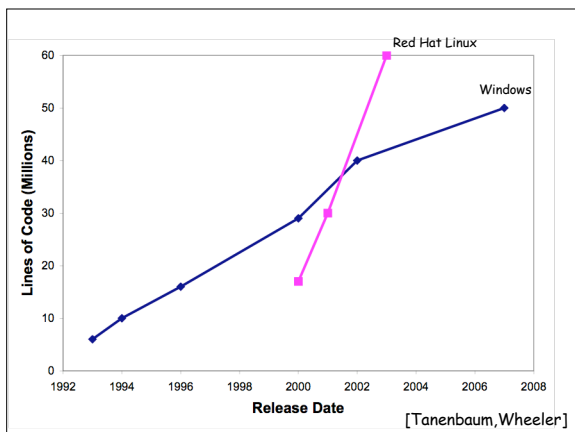
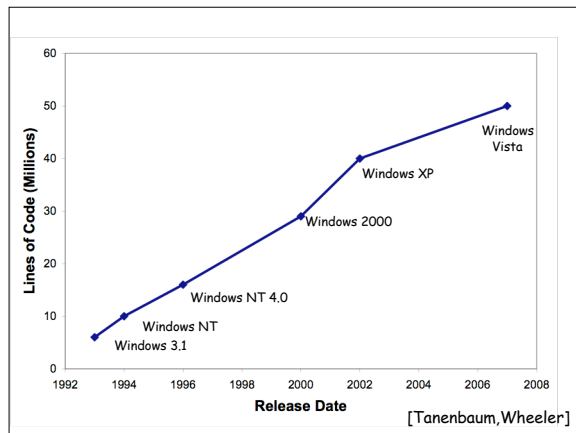


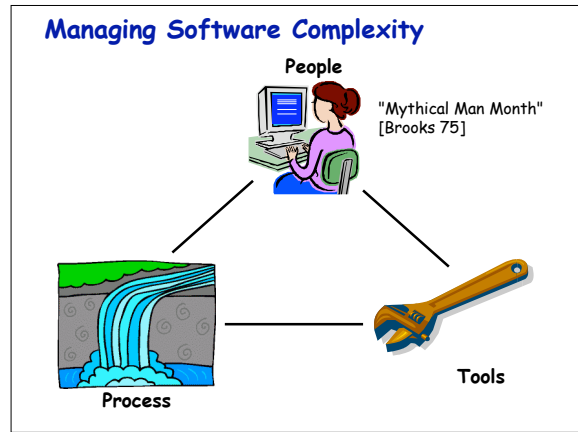
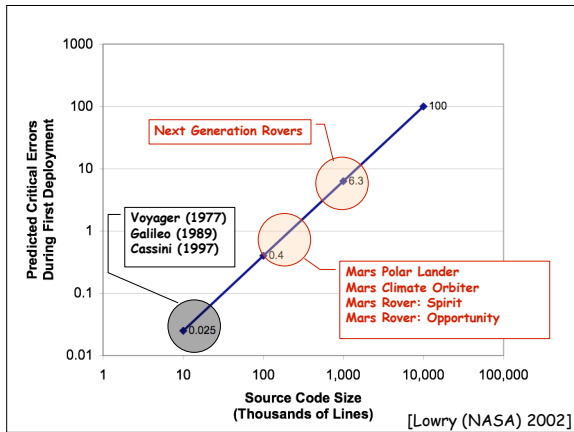
[Wired 1997]



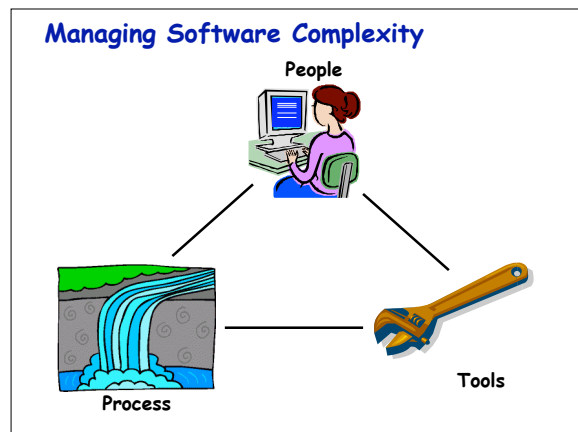
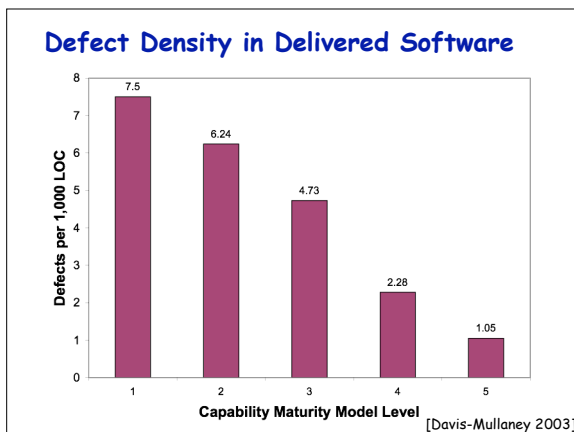
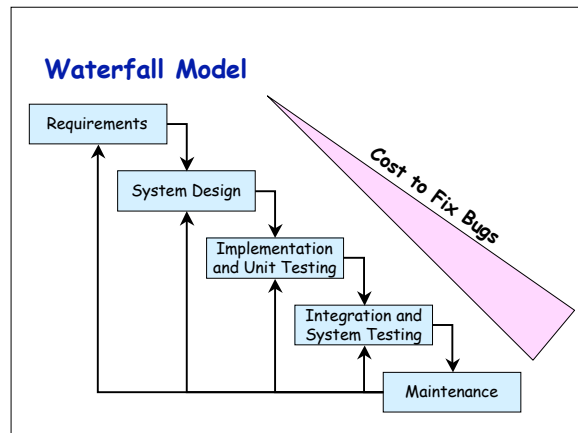
<p><b>Mars Climate Orbiter</b></p> <p><b>Purpose:</b> Collect data. Relay signals from Mars Polar Lander (\$165M)</p> <p><b>Failure:</b> Smashed into Mars (1999)</p> <p><b>Bug:</b> Failed to convert English to metric units</p>	<p><b>Mars Polar Lander</b></p> <p><b>Purpose:</b> Lander to study the Mars climate (\$120M)</p> <p><b>Failure:</b> Smashed into Mars (2000)</p> <p><b>Bug:</b> Spurious signals from sensors caused premature engine shutoff</p>
<p><b>Therac25 Radiation Therapy</b></p> <p><b>Purpose:</b> Computer-controlled radiation therapy machine</p> <p><b>Failure:</b> gave fatal radiation doses to 2 cancer patients (1986)</p> <p><b>Bug:</b> timing bug</p>	<p><b>USS Vincennes</b></p> <p><b>Failure:</b> Shot down an Airbus jet that was mistaken for a F-14. 290 people died. (1988)</p> <p><b>Bug:</b> tracking software displayed cryptic and misleading output</p>

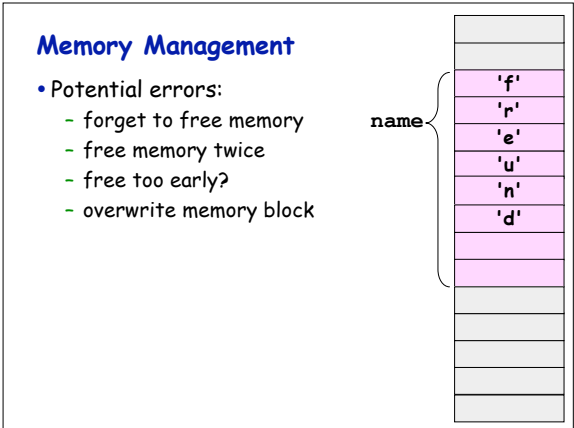
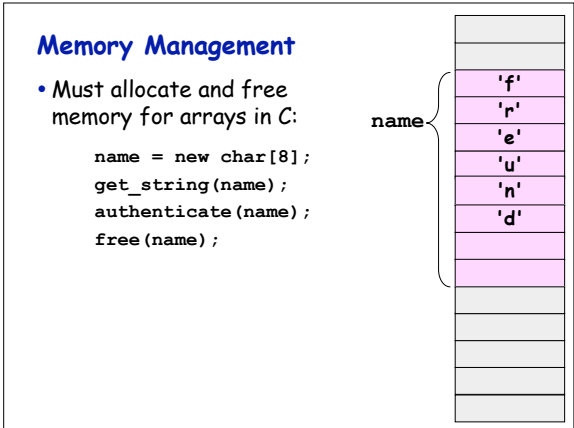
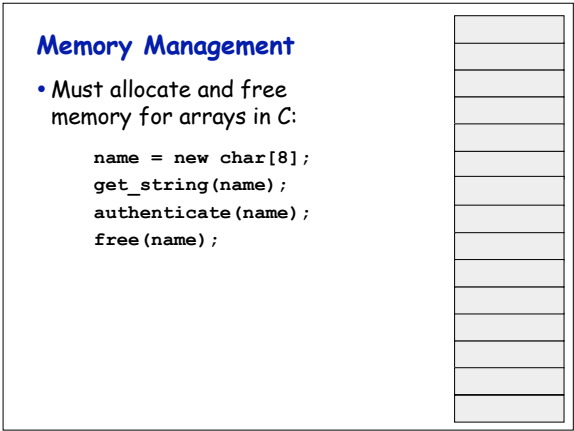
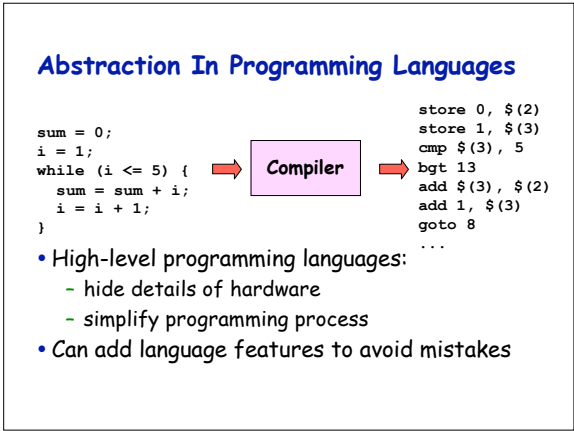
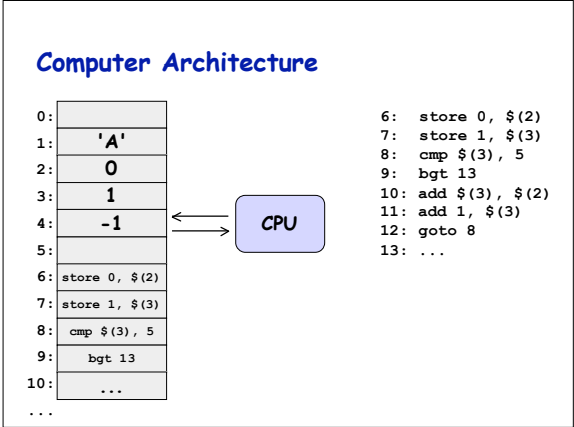
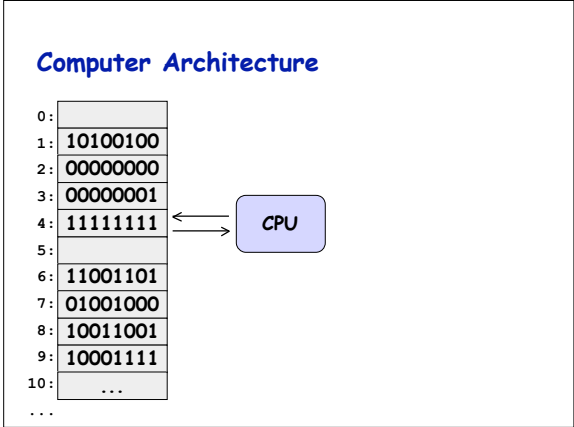
- ### Software Complexity
- Huge costs
    - \$60 billion / year [NIST 2003]
    - convenience, security, safety
  - Why is it so hard to get right?
    - systems are too large to understand completely
    - small mistakes can compromise whole system
    - many failure modes
      - unreliable network, media, hardware, users,...
      - half of code is to handle failures
    - programs evolve over time





- ### Software Processes
- Organization of large software project
    - other examples: army, company, college admin
    - planning, responsibilities, interactions
  - Benefits
    - avoid miscommunication, misunderstandings
    - predict time and cost
    - recognize problems early
  - Process failures do happen (frequently...)
    - Air Traffic Control system, \$2.6Billion, 1983-1996





## Garbage Collection

- Never explicitly free memory

```
name = new char[8];
get_string(name);
authenticate(name);
```

- Program periodically pauses to find and reclaim unused memory
- Used in Java, C#, Python, ...

## Tradeoffs in Design

- No free lunch
  - features impact performance / expressiveness
  - can be prohibitively expensive (or impossible!)
- Other features
  - object-oriented languages / modules
  - exception handling
  - threads

## Program Checking

- Design algorithm to automatically identify errors

- Example 1: type errors

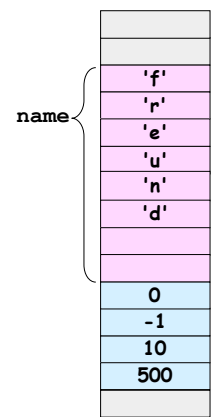
```
WebPage w = new WebPage("http://...");
int x = w - 3; ← BAD
```

```
String s = "hello";
if (s < 100) ... ← BAD
```

- Example 2: buffer overruns in C programs

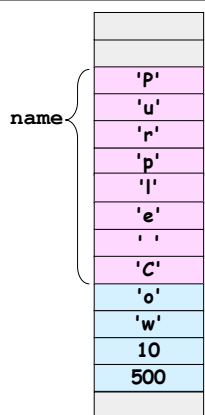
## Buffer Overruns in C

```
name = new char[8];
get_string(name);
authenticate(name);
free(name);
```



## Buffer Overruns in C

```
name = new char[8];
get_string(name);
authenticate(name);
free(name);
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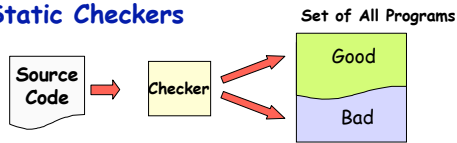


## Dynamic Monitors

- Check program as it executes
  - example: buffer overruns
- Pros:
  - identify cause of bug faster than testing
  - easy to add to development process
- Cons:
  - coverage
  - performance
  - must run whole program

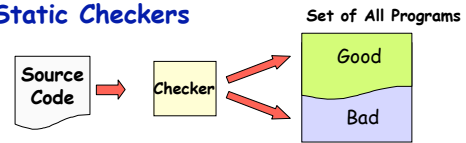


### Static Checkers



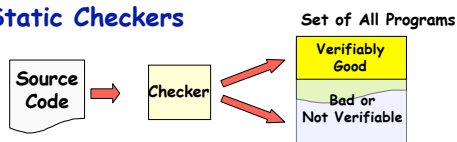
- Pros:
  - catch errors sooner (even before running)
  - check program for all inputs / all possible paths
- Cons:

### Static Checkers



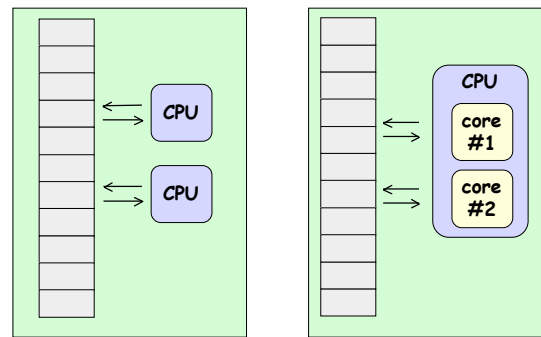
- Pros:
  - catch errors sooner (even before running)
  - check program for all inputs / all possible paths
- Cons:
  - cannot distinguish "good" from "bad" exactly
  - computers *cannot* compute everything
    - undecidability of the Halting Problem [Turing 1936]

### Static Checkers



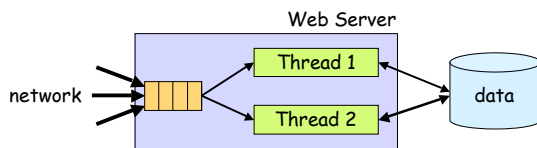
- Pros:
  - catch errors sooner (even before running)
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    - undecidability of the Halting Problem [Turing 1936]

### Multi-Processors and Multi-Core Chips



### Concurrent Programming With Threads

- Decompose into pieces that run in parallel
- Improve throughput



### Demo

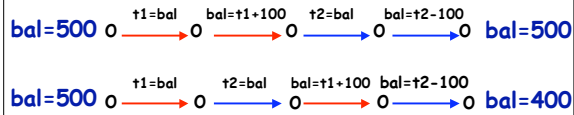
### Multithreaded Program Execution

Thread 1

Thread 2

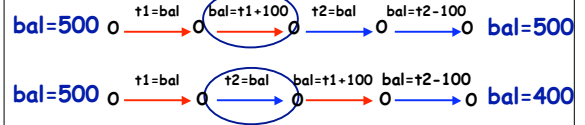
```

...
t1 = bal;
bal = t1 + 100;
...
    
```



### Multithreaded Program Execution

Race condition

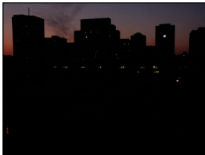


### Race Conditions

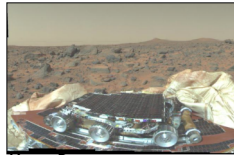
- Common
- Hard to find via testing
  - scheduler dependent
- Memory, files, printers, ...



Therac-25



2003 Blackout (\$6 Billion)



Mars Rovers

### Preventing Race Conditions Using Locks

Thread 1

Thread 2

```

acquire(m);
t1 = bal;
bal = t1 + 100;
release(m);
    
```



### Preventing Race Conditions Using Locks

Thread 1

Thread 2

```

synchronized(m) {
    t1 = bal;
    bal = t1 + 100;
}
    
```



Demo

## Checkers For Race Conditions

```
int bal; /// guarded_by m
```

**Thread 1**

```
synchronized(m) {
    t1 = bal;
    bal = t1 + 100;
}
```

**Thread 2**

```
synchronized(m) {
    t2 = bal;
    bal = t2 - 100;
}
```

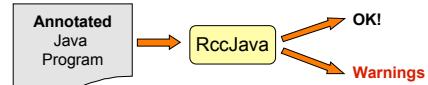
• **Good:** Threads always hold *m* when accessing *bal*

• **Bad:** Thread accesses *bal* without holding *m*

Tools: Eraser [Savage et al. 97], RccJava, ...

## Statically Checking Real Systems

• RccJava [with Flanagan (UCSC), Peter Applegate '03]

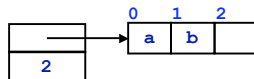


• Found bugs in many pieces of software

- commercial products, Java libraries, web servers
- false positive rate of 75-80%

- benign races, other forms of synchronization
- better than not finding errors

`java.util.Vector`



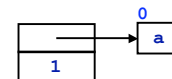
```
class Vector {
    Object elementData[] /// guarded_by this
    int elementCount /// guarded_by this

    synchronized int lastIndexOf(Object elem, int n) {
        for (int i = n ; i >= 0 ; i--)
            if (elem.equals(elementData[i])) return i;
        return -1;
    }

    int lastIndexOf(Object elem) {
        return lastIndexOf(elem, elementCount - 1); /// race!
    }

    synchronized void trimToSize() { ... }
    synchronized boolean remove(int index) { ... }
}
```

`java.util.Vector`



```
class Vector {
    Object elementData[] /// guarded_by this
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    synchronized int lastIndexOf(Object elem, int n) {
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    }

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        return lastIndexOf(elem, elementCount - 1); /// race!
    }

    synchronized void trimToSize() { ... }
    synchronized boolean remove(int index) { ... }
}
```

Demo

## Atomicity Violations

```
int bal; /// guarded_by m
```

**Thread 1**

```
synchronized(m) {
    t1 = bal;
}
```

**Thread 2**

```
synchronized(m) {
    t2 = bal;
    bal = t2 - 100;
}
```

```
synchronized(m) {
    bal = t1 + 100;
}
```





## Atomicity Violations

```
int bal; // # guarded_by m
```

Thread 1

```
atomic {
  synchronized(m) {
    t1 = bal;
  }

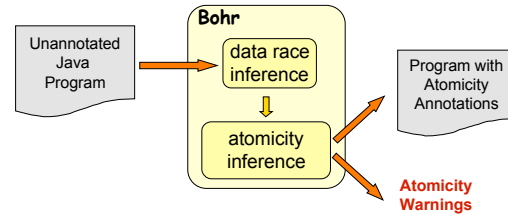
  synchronized(m) {
    bal = t1 + 100;
  }
}
```

Thread 2

```
atomic {
  synchronized(m) {
    t2 = bal;
    bal = t2 - 100;
  }
}
```

## Bohr

- Compute `atomic` annotations automatically
- Identify methods that may suffer interference
- With Masha Lifshin '05



## The (Long) Road to Reliable Software

- Bugs are a real problem
- Checking tools will improve life for everyone
- Industry starting to adopt checkers
- Lots of problems (and fun) left
  - tools often hard to use, imprecise
  - simple tools pave way for more sophisticated
  - need teachable design methodologies

## Thanks

- Pete Applegate '03
- Masha Lifshin '05
- Cormac Flanagan (UCSC)
- Martín Abadi (UCSC and Microsoft)
- Shaz Qadeer (Microsoft)
- NSF/NASA HDCCSR Program